

# Diva workshop 2014

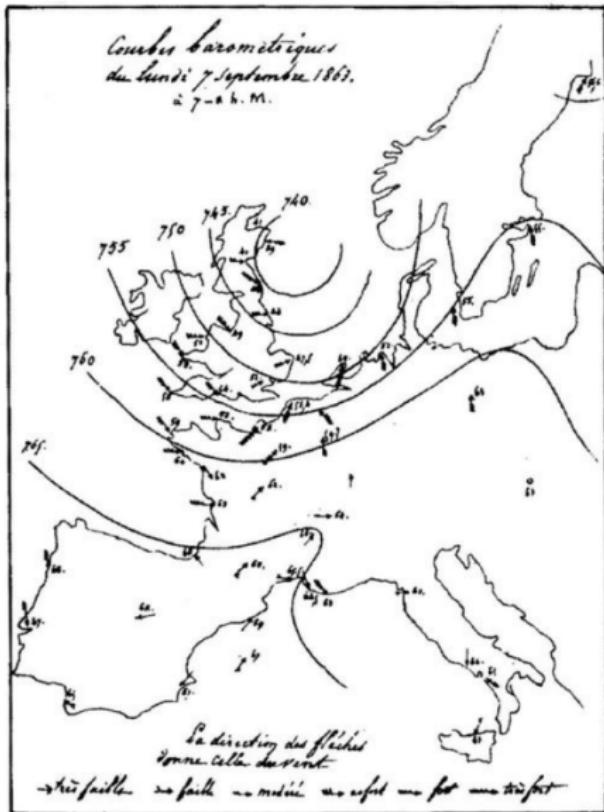
## Diva in 2 dimensions

Alexander Barth, Aida Alvera-Azcárate, Mohamed Ouberdous,  
Charles Troupin, Sylvain Watelet & Jean-Marie Beckers

**Acknowledgements:** SeaDataNet, EMODnet Chemistry,  
EMODnet Biology, STARESO

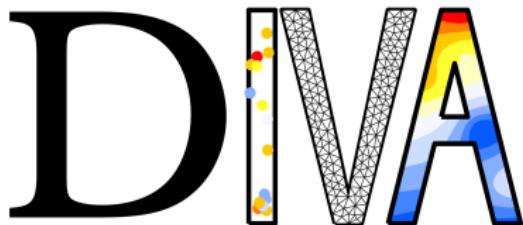


# Interpolation 150 years ago...



# What is Diva?

Data  
Interpolating  
Variational  
Analysis



## What is Diva?

- a method to produce gridded fields
- a set of bash scripts and Fortran programs

## What is not Diva?

- a plotting tool
- a *black-box*
- a numerical model

# A little bit of history

## Code development (1990-1996)

- Variational Inverse Method (VIM) (Brasseur, 1991, JMS, JGR)
- cross-validation (Brankart and Brasseur, 1996, JAOT)
- error computation (Brankart and Brasseur, 1998, JMS; Rixen et al., 2000, OM)

# A little bit of history

Code development (1990-1996)

2D-analysis (2006-2007)

- set of bash scripts (divamesh, divacalc,...)
- Fortran executables
- parameters optimization tools
- Matlab/Octave scripts for plotting

# A little bit of history

Code development (1990-1996)

2D-analysis (2006-2007)

3D-analysis (2007-2008)

- superposition of 2D layers
- automated treatment and optimization
- stability constraint ([Ouberdous et al.](#))

# A little bit of history

Code development (1990-1996)

2D-analysis (2006-2007)

3D-analysis (2007-2008)

4D-analysis (2008-2009)

- start from ODV spreadsheet
- *detronding* (with J. Carstensen, DMU)
- NetCDF 4-D climatology files

# A little bit of history

Code development (1990-1996)

2D-analysis (2006-2007)

3D-analysis (2007-2008)

4D-analysis (2008-2009)

## Web tools

- On-line analysis (Barth et al., 2010, Adv. Geosci.)  
`http://gher-diva.phys.ulg.ac.be/web-vis/diva.html`
- Climatology viewer: `http://gher-diva.phys.ulg.ac.be/web-vis/clim.html`

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Code development (1990-1996)

2D-analysis (2006-2007)

3D-analysis (2007-2008)

4D-analysis (2008-2009)

Web tools

2011-2012

- multivariate approach
- data transformation tools
- 4-D graphical interface
- implementation of *source/decay* terms
- advanced error computation (Troupin et al., 2012, OM)

# A little bit of history

Code development (1990-1996)

2D-analysis (2006-2007)

3D-analysis (2007-2008)

4D-analysis (2008-2009)

Web tools

2011-2012

On-going:

- Modernisation of the code structure
- n-dimensional generalisation
- Spatially correlated observations errors
- optimized and approximate error calculations (clever poor man)

# A little bit of history

Code development (1990-1996)

2D-analysis (2006-2007)

3D-analysis (2007-2008)

4D-analysis (2008-2009)

Web tools

2011-2012

On-going:

General: user-driven developments

# Diva related tools

**Diva:** base tool (command line), 2D analysis

**Godiva:** automatic repetition of 2D analysis

**Diva-on-web:** 2D analysis with your data on our server

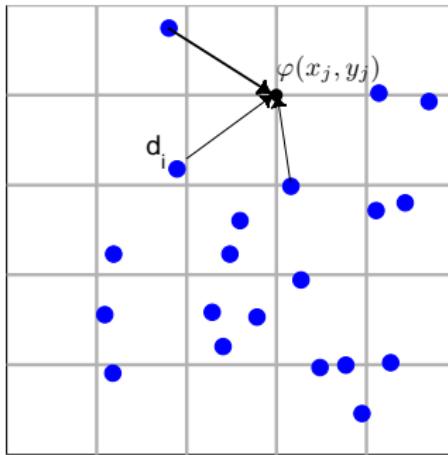
**OceanBrowser:** visualisation tool of 4D NetCDF files

**divand:** multi-dimension analysis (lon, lat, time, depth)

**divaformatlab:** wrapper to use in matlab

# DIVA: Data-Interpolating Variational Analysis

$N_d$  data points  $d_i$  • → gridded field

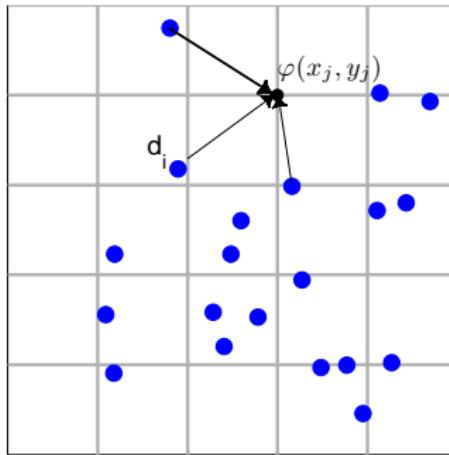


Formulation: minimize cost function  $J[\varphi]$

$$\begin{aligned} \min J[\varphi] = & \sum_{i=1}^N \mu_i [d_i - \varphi(x_i, y_i)]^2 \\ + & \int_D (\nabla \nabla \varphi : \nabla \nabla \varphi + \alpha_1 \nabla \varphi \cdot \nabla \varphi + \alpha_0 \varphi^2) \, dD \end{aligned}$$

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Formulation: minimize cost function  $J[\varphi]$

$$\min J[\varphi] = \sum_{i=1}^N \mu_i [d_i - \varphi(x_i, y_i)]^2 \quad \text{data-analysis misfit}$$

$$+ \int_D (\nabla \nabla \varphi : \nabla \nabla \varphi + \alpha_1 \nabla \varphi \cdot \nabla \varphi + \alpha_0 \varphi^2) \, dD \quad \text{field regularity}$$

# Analysis parameters are related to data

Non-dimensional version:

$$L = \text{length scale} \rightarrow \tilde{\nabla} = L \nabla \quad (1)$$

$$\rightarrow D = L^2 \tilde{D} \quad (2)$$

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- $\alpha_1 \rightarrow$  influence of gradients:  $\alpha_1 L^2 = 2\xi, \quad \xi = 1$
- $\mu_i L^2 \rightarrow$  weight on data:  $\mu_i L^2 = 4\pi \frac{\text{signal}}{\text{noise}_i}$

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Coefficients  $\alpha_0$ ,  $\alpha_1$  and  $\mu_i$  related to

- 1 Correlation length  $L$
- 2 Signal-to-noise  $\lambda$
- 3 Observational noise standard deviation  $\epsilon_i^2$

# Main analysis parameters

## Correlation length $L$ :

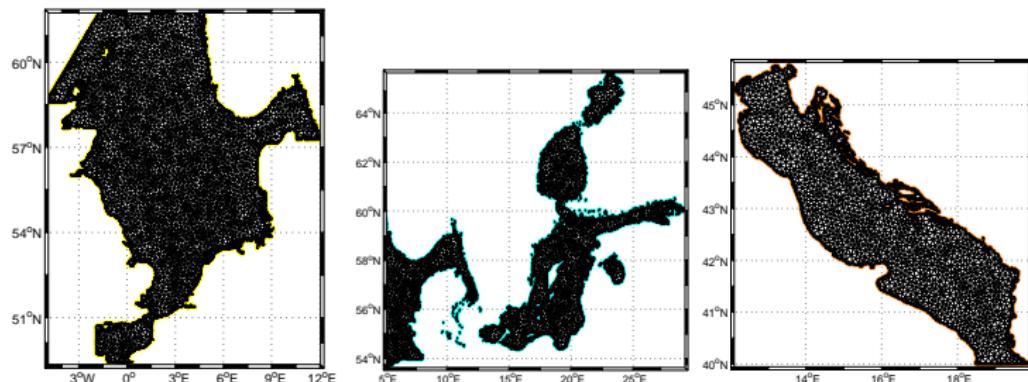
- Measure of the *influence* of data points
- Estimated by a least-square fit of the covariance function

## Signal-to-noise ratio $\lambda$ :

- Measure of the *confidence* in data
- Estimated with Generalized Cross Validation techniques

# Minimization with a finite-element method

Field regularity → plate bending problem → finite-element solver



## Advantages:

- boundaries taken into account
- numerical cost (almost independent on data number)
- no *a posteriori* masking (except if based on error level)

# Minimization with a finite-element method

Triangular FE only covers sea:

$$J[\varphi] = \sum_{e=1}^{N_e} J_e(\varphi_e) \quad (3)$$

In each element:  $\varphi_e(\mathbf{r}_e) = \mathbf{q}_e^T \mathbf{s}(\mathbf{r}_e)$  with

$$\begin{cases} \mathbf{s} & \rightarrow \text{shape functions} \\ \mathbf{q} & \rightarrow \text{connectors} \\ \mathbf{r}_e & \rightarrow \text{position} \end{cases} \quad (4)$$

(4) in (3) + variational principle

$$J_e(\mathbf{q}_e) = \mathbf{q}_e^T \mathbf{K}_e \mathbf{q}_e - 2\mathbf{q}_e^T \mathbf{g}_e + \sum_{i=1}^{N_{d_e}} \mu_i d_i \quad (5)$$

where

$$\begin{cases} \mathbf{K}_e & \rightarrow \text{local stiffness matrix} \\ \mathbf{g} & \rightarrow \text{vector depending on local data} \end{cases}$$

# Minimization with a finite-element method

On the whole domain:

$$J(\mathbf{q}) = \mathbf{q}^T \mathbf{K} \mathbf{q} - 2\mathbf{q}^T \mathbf{g} + \sum_{i=1}^{N_d} \mu_i d_i \quad (3)$$

Minimum:

$$\mathbf{q} = \mathbf{K}^{-1} \mathbf{g} \quad (4)$$

$$\mathbf{q} = \mathbf{K}^{-1} \mathbf{g} \quad (5)$$

- Stiffness matrix
- Connectors (new unknowns)
- Charge vector

Mapping of data on FEM → transfer operator  $\mathbf{T}_2 \rightarrow \mathbf{g} = \mathbf{T}_2(\mathbf{r})\mathbf{d}$

Solution at any location → transfer operator  $\mathbf{T}_1 \rightarrow \varphi(\mathbf{r}) = \mathbf{T}_1(\mathbf{r})\mathbf{q}$

Results obtained at any location →  $\varphi = \mathbf{T}_1(\mathbf{r})\mathbf{K}^{-1}\mathbf{T}_2(\mathbf{r})\mathbf{d}$

# Diva Cocktail Recipe

## Ingredients:

- 1 1/2 oz vodka
- 1/2 oz passion-fruit juice
- 1/2 oz lime juice
- 1 tbsp cherry juice
- fill with soda



# Diva Cocktail Recipe

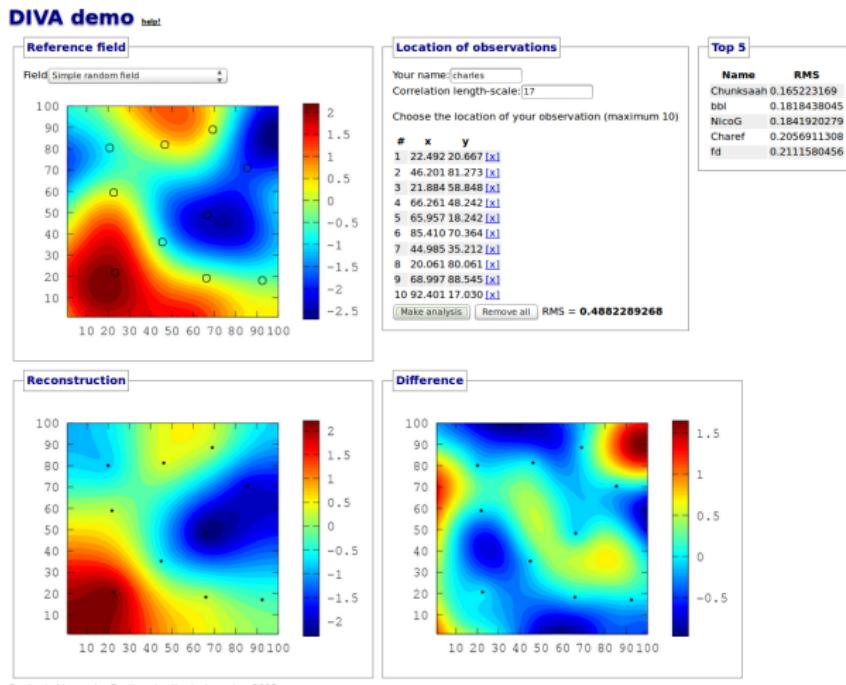
## Ingredients:

- Smoothness
- Observation constraint
- Behaviour constraint



# Want to use Diva?

Playing...

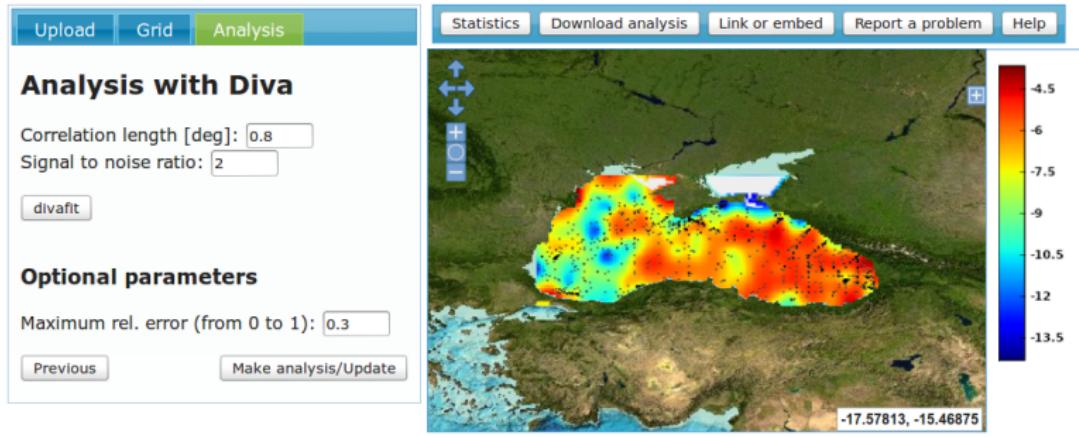


Contact: Alexander Barth, a.barth@ulg.ac.be, 2012.

[http://data-assimilation.net/Tools/divand\\_demo/html/](http://data-assimilation.net/Tools/divand_demo/html/)

# Want to use Diva?

With your own data...



<http://gher-diva.phys.ulg.ac.be/web-vis/diva.html> or ODV or matlab wrapper

# Want to use Diva?

For serious work:

2D version (for production), open source, GPL  
nD version (for research), open source, GPL

```
File Edit View Search Terminal Help
#####
#-----#
ready on diva.a
#####
#####
D.I.V.A. - 4.6.1 - Execution Track ...
#####

$55555555555555555555555555555555
CALL TO CLOUD MODULE: IMR = 1
$55555555555555555555555555555555

Coordinate change          0

$55555555555555555555555555555555
CALL TO MATHPR MODULE: IMR = 1
$55555555555555555555555555555555

Finite Element type =      2
Symmetric problem : isym =   0
Problem type :    ipb =      2
Parameter alphanl = 1.00000000000000
Parameter alphal = 2.00000000000000

$55555555555555555555555555555555
CALL TO TIPOLD MODULE: IMR = 1
$55555555555555555555555555555555

Total number of vertex nodes :       13949
Total number of interfaces :        81444
Total number of edges :            55593
Total number of elements :         27496
Total number of deg. of frd. :     83291

$55555555555555555555555555555555
CALL TO DATAPR MODULE: IMR = 1
$55555555555555555555555555555555

Total number of data constraint: ndata =      1
*** Optimisation is working 2 ***
#####

There are      0 data NDN localized in the mesh (and ignored)
\\\
No need to sort a single data point
\\\
There are      1 data localized in the mesh (and resorted)
\\\

$55555555555555555555555555555555
CALL TO SOLVER MODULE: IMR = 1
$55555555555555555555555555555555

into solver      1
*** Skyline direct  solver ===
\\\
```

<http://modb.oce.ulg.ac.be/mediawiki/index.php/DIVA>

## Running Diva in 2D: input files

- 1 `data.dat`: contains the observations

x|y|value

```
36.5500 45.163 17.7138
33.7500 44.167 18.135
32.7500 44.167 18.51
36.2500 43.833 18.5892
33.2500 45.083 18.2326
32.7833 43.917 18.477
32.7500 43.500 18.59
37.2433 44.833 18.1555
36.5000 44.000 18.19
35.8333 43.750 18.62
34.2500 43.832 18.29
35.6500 44.000 18.75
38.0000 44.000 18.155
37.8200 44.368 17.1916
39.0000 42.500 18.23
33.1333 44.433 18.001
33.0500 44.433 18.09
33.2500 44.167 18.231
32.5333 44.833 18.014
38.0167 44.447 18.0568
```

# Running Diva in 2D: input files

- 1 `data.dat`: contains the observations                                   x\ly\value
- 2 `coast.cont`: delimits land and sea                                   (coastline or isobaths)

```
7  
552  
27.4375000 40.3499985  
27.4500008 40.3375015  
27.4666672 40.3375015  
27.4833336 40.3375015  
27.5000000 40.3375015  
27.5166664 40.3375015  
27.5333328 40.3375015  
27.5499992 40.3375015  
27.5666676 40.3375015  
27.5791664 40.3499985  
27.5833340 40.3541679  
27.6000004 40.3541679  
27.6124992 40.3666649  
27.6166668 40.3708344  
27.6291676 40.3833351  
27.6291676 40.4000015  
27.6291676 40.4166679  
27.6291676 40.4333344  
27.6166668 40.4458351  
27.6124992 40.4500008
```

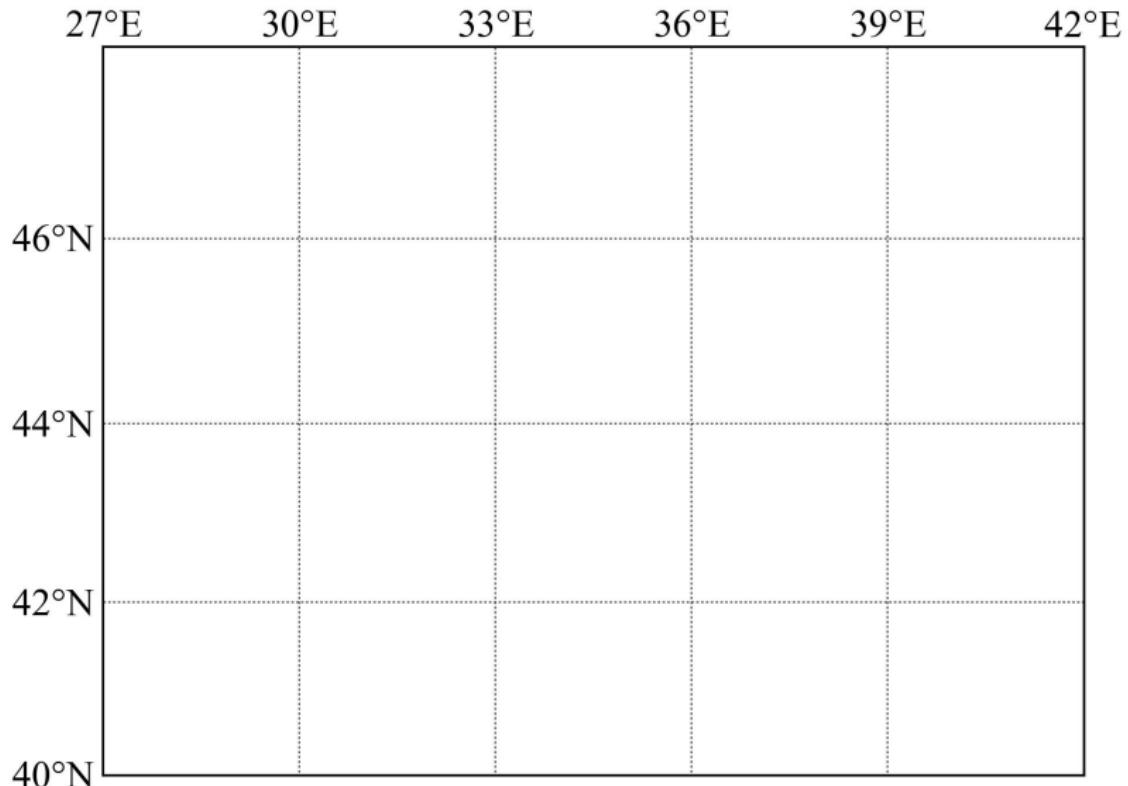
# Running Diva in 2D: input files

- 1 `data.dat`: contains the observations                               xly|value
- 2 `coast.cont`: delimits land and sea                                 (coastline or isobaths)
- 3 `param.par`: analysis parameters                                 $L$ ,  $\lambda$ , resolution, ...

```
# Lc: correlation length (in units coherent with your data)#
1.5
# icoordchange (=0 if no change of coordinates is to be performed; =1 if positions are in degree
2
# ispec: output files required#
0
# ireg: mode selected for background field: 0=null guess; 1=mean of data; 2=regression plan if a
2
# xori: x-coordinate of the first grid point of the output#
27
# yori: y-coordinate of the first grid point of the output#
40
# dx: step of output grid#
0.1
# dy: step of output grid#
0.1
# nx: number of grid points in the x-direction#
151
# ny: number of grid points in the y-direction#
76
# valex: exclusion value#
-99
# snr: signal to noise ratio of the whole dataset#
0.5
# varbak: variance of the background field. If zero, no error fields are produced. If one, relat
1.0
```

# Workflow in 2D

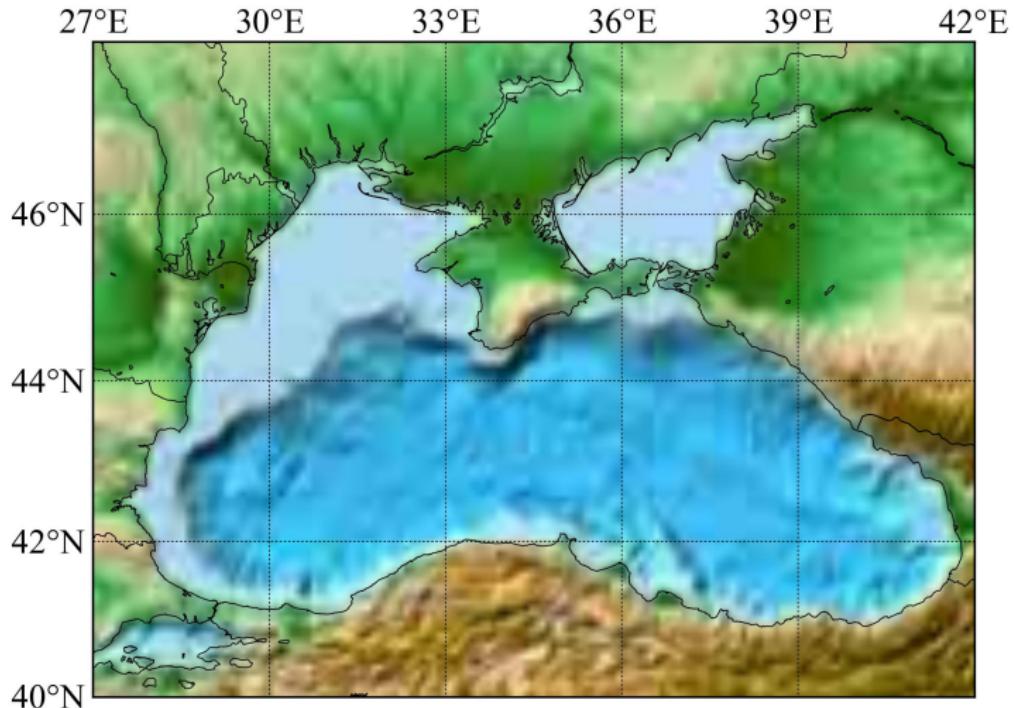
Select region of study



# Workflow in 2D

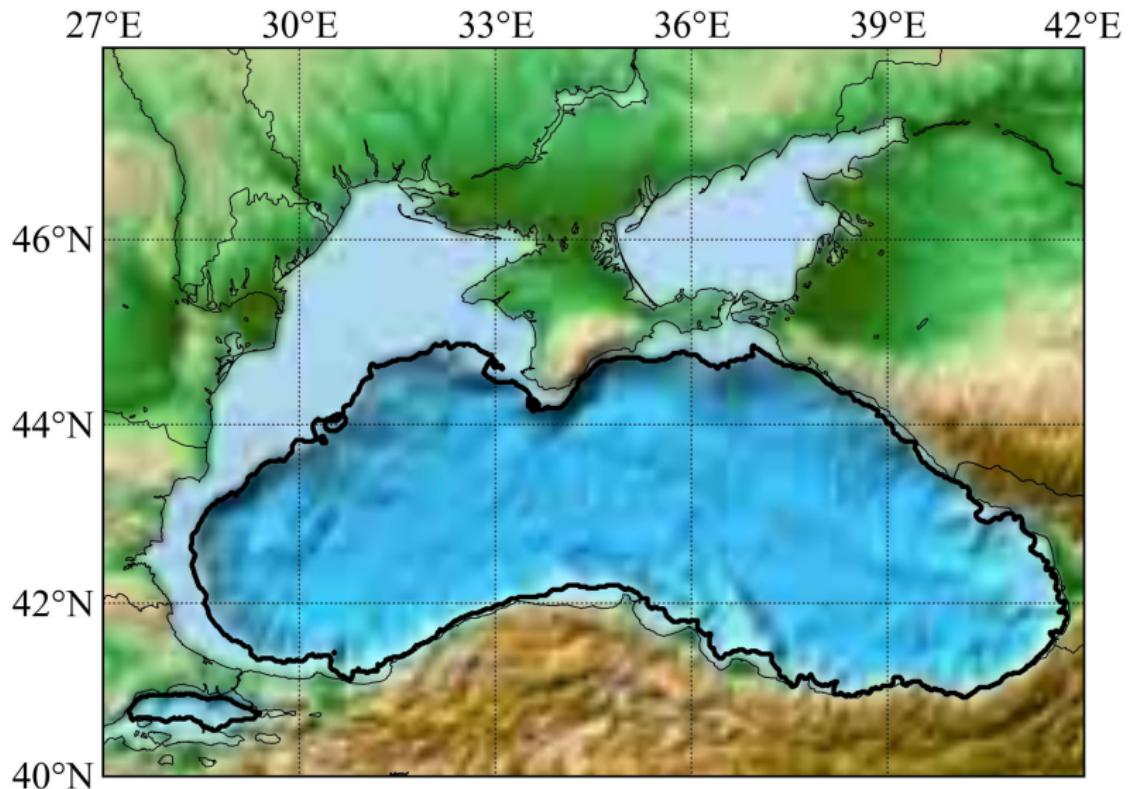
Extract topography, for example via

<http://gher-diva.phys.ulg.ac.be/web-vis/diva.html>



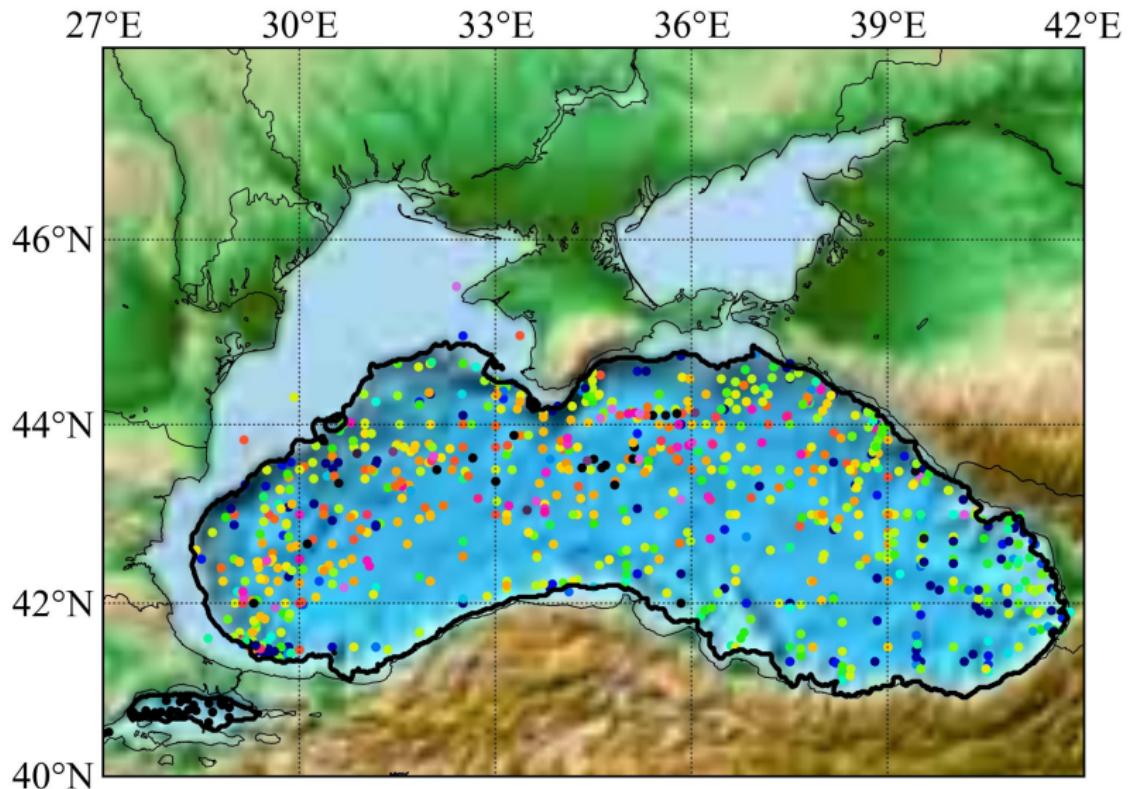
# Workflow in 2D

Generate [contour](#)



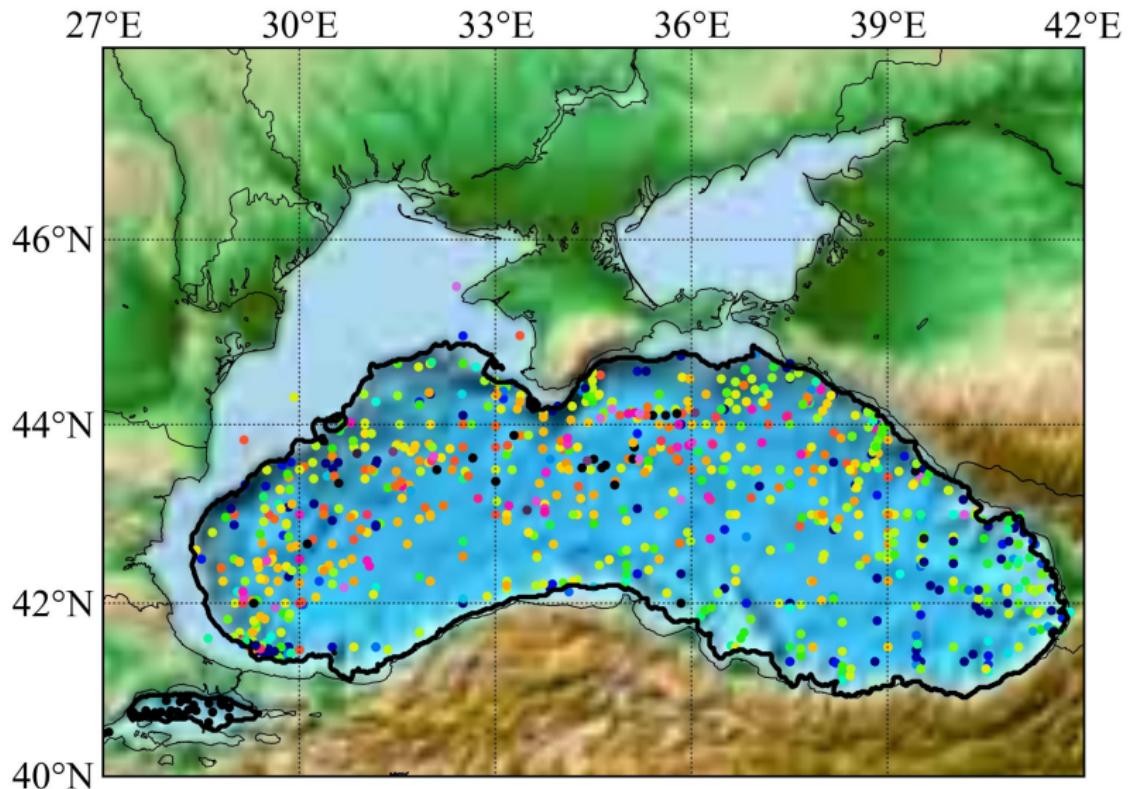
# Workflow in 2D

## Extract data



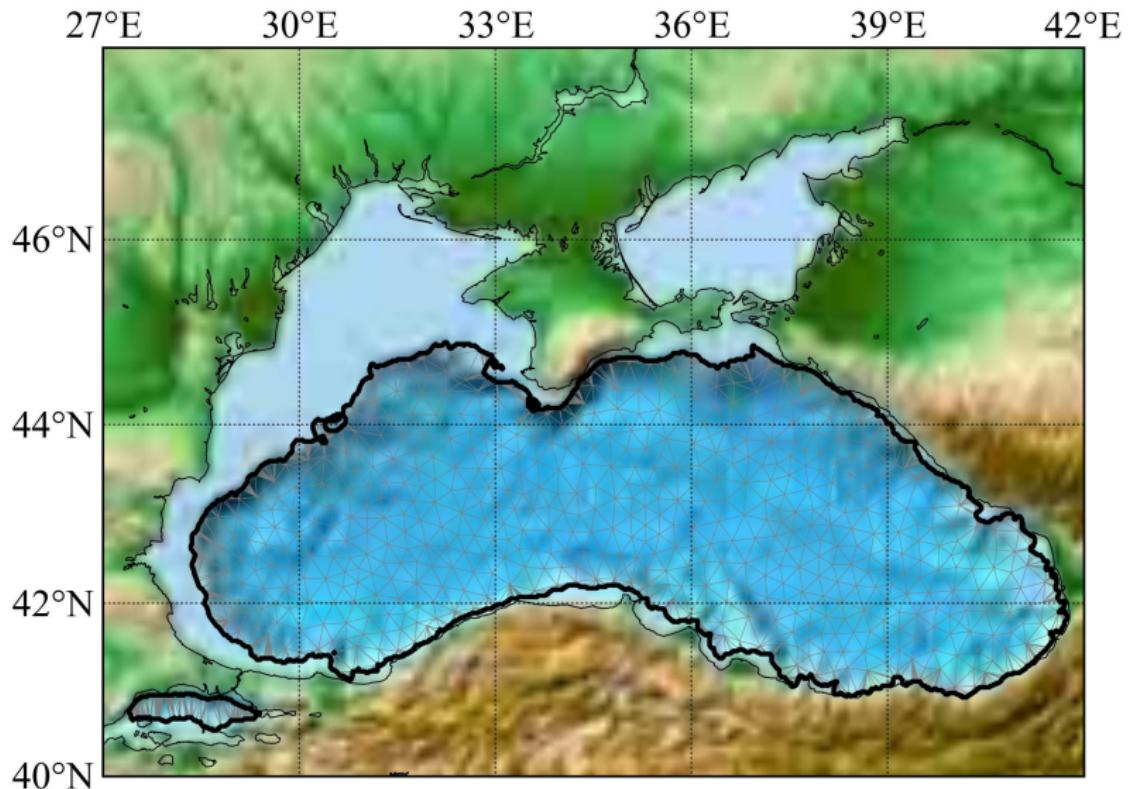
# Workflow in 2D

Evaluate analysis parameters



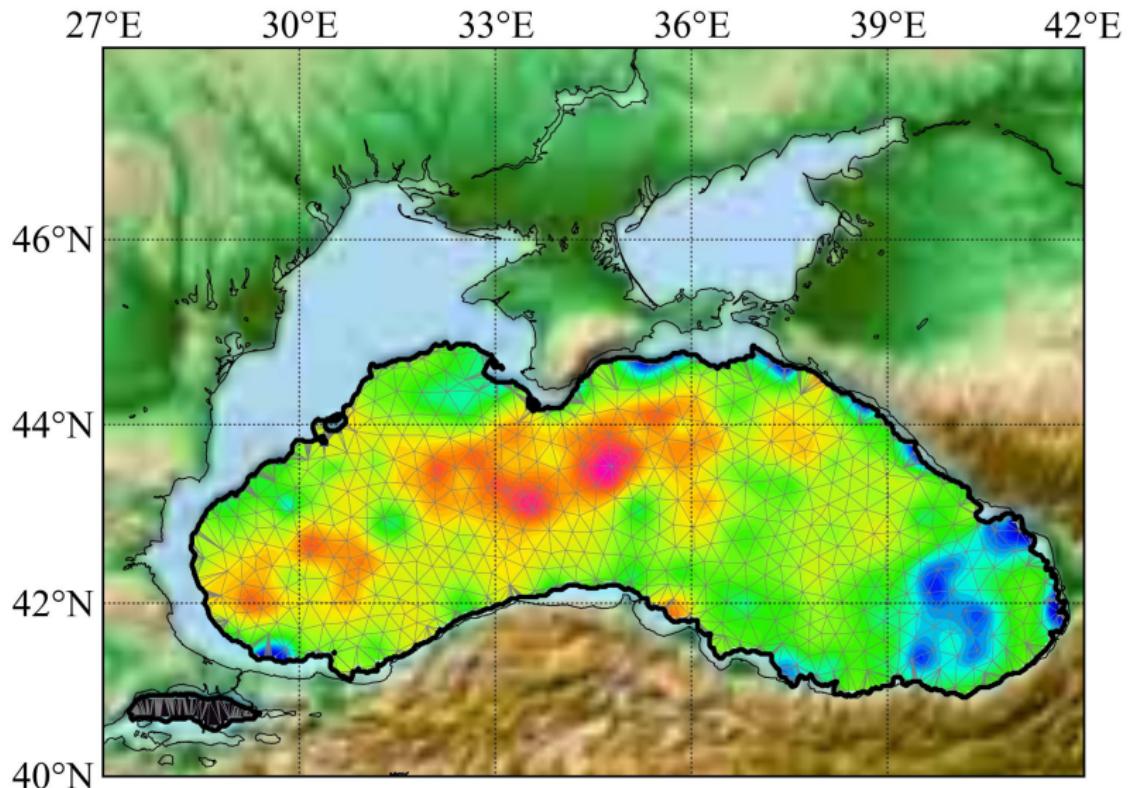
# Workflow in 2D

## Create finite-elementmesh



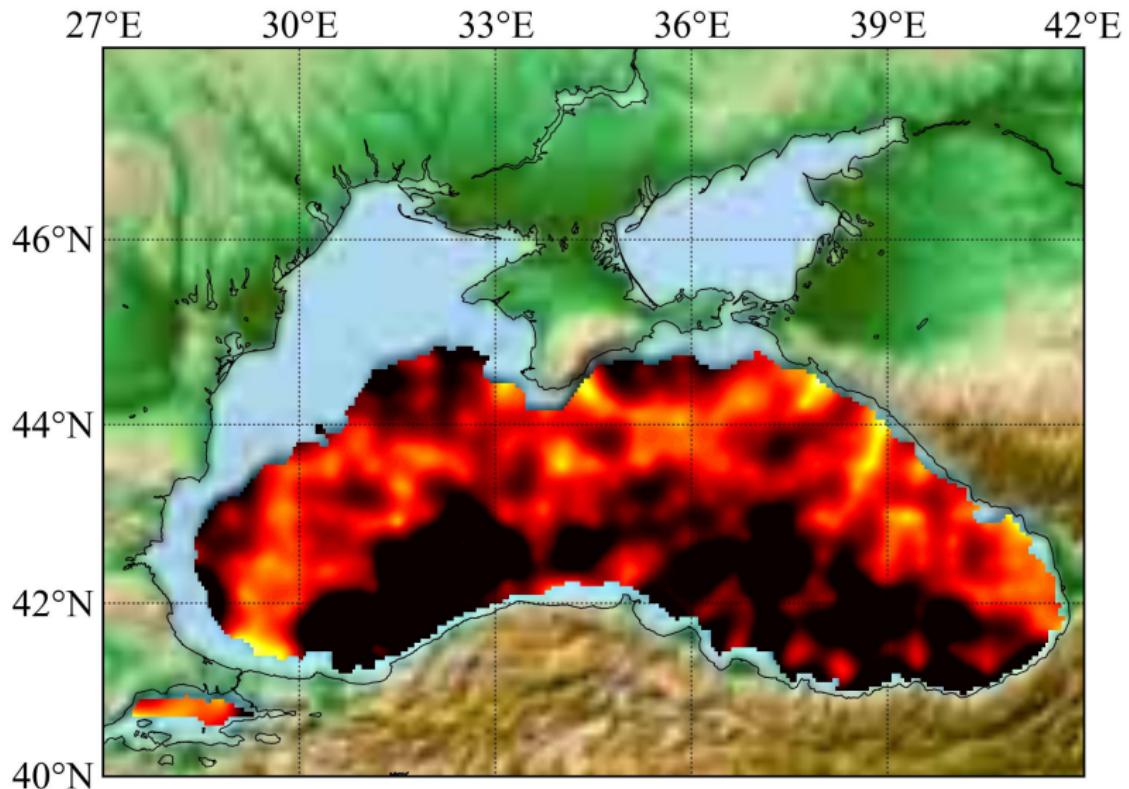
# Workflow in 2D

## Generate analysis



# Workflow in 2D

Generate error field



## When to use 2D version

- occasional use
- 2D fields like benthic properties
- for implementation of special features by your own (eg multiplicative bias correction, special background field creation based on habitats)
- ...

otherwise: use 3D or 4D version directly

Next...

# Diva in 4 dimensions