



1. Introduction

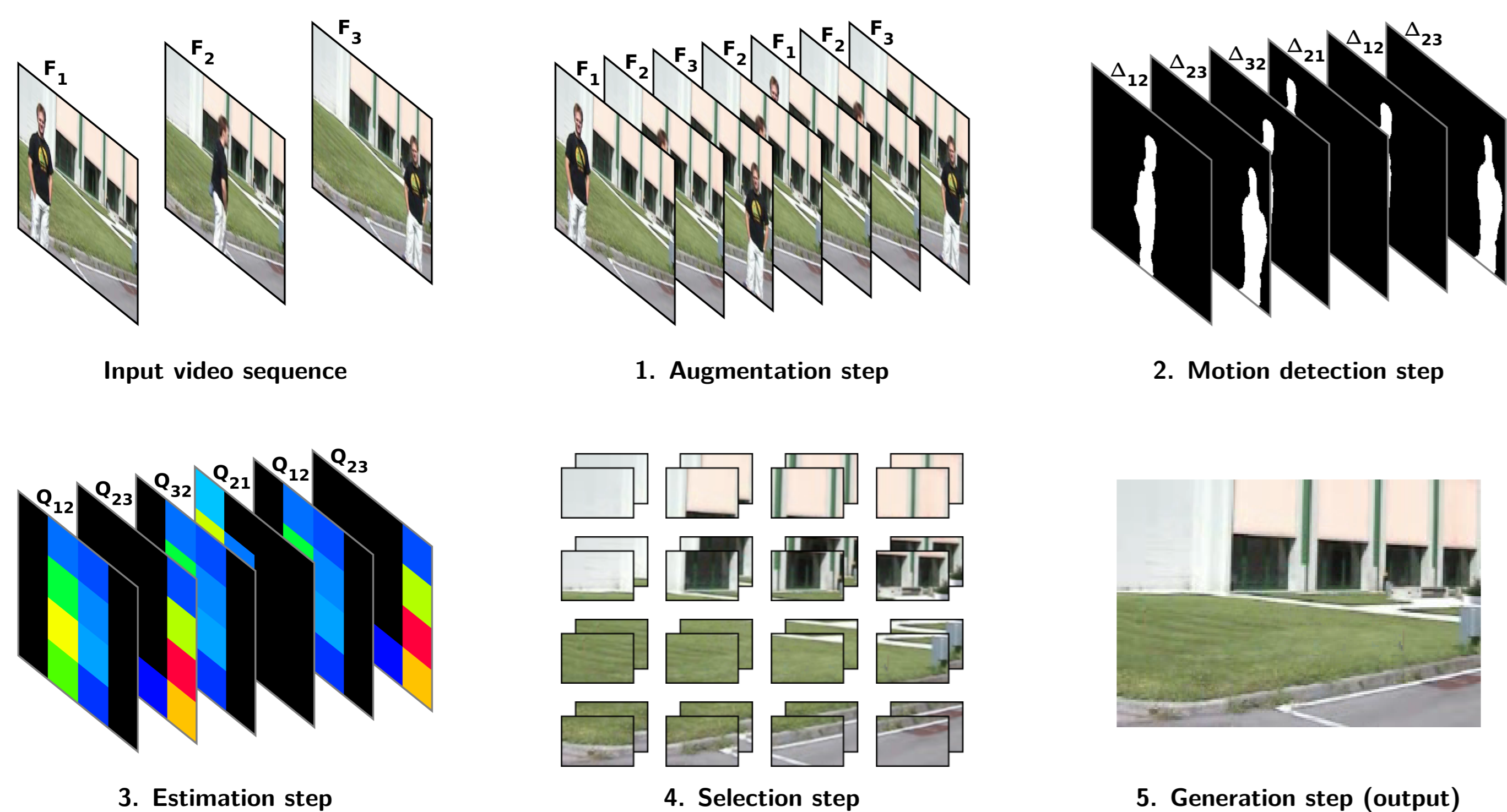
Given a video sequence acquired from a fixed viewpoint, the **stationary background generation** problem consists in generating a unique image representing the background.



- The **LaBGen background generation method** combines a pixel-wise median filter and a patch selection mechanism based on a motion detection performed by a background subtraction (BGS) algorithm.
- Surprisingly, the **frame difference algorithm** provides the most effective motion detection on average. Compared to other BGS algorithms, it detects motion between two frames without relying on additional past frames, and is therefore **memoryless**.
- In this work, we experimentally check whether the **memoryless property** is truly **relevant for LaBGen**, and whether the effective motion detection provided by the frame difference is not an isolated case.
- For this purpose, we introduce **LaBGen-OF**, a variant of LaBGen leverages memoryless dense optical flow (OF) algorithms for motion detection.

2. The LaBGen Background Generation Framework

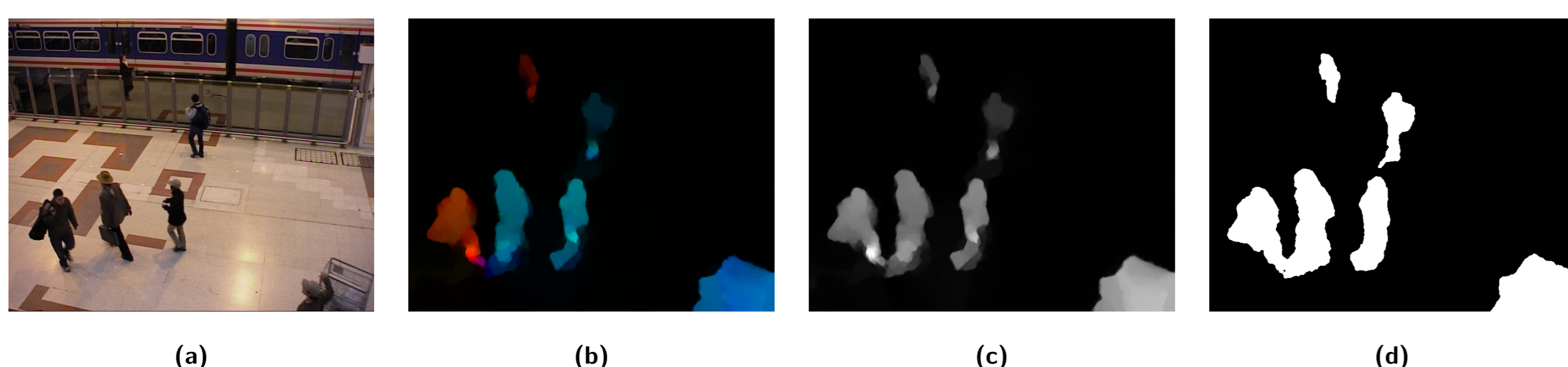
- 1 An **augmentation step** increases the length of the input video sequence according to a parameter \mathcal{P} . This is performed by duplicating the frames of the sequence in the forwards and backwards chronological orders alternatively.
- 2 For each frame of the augmented sequence, a **motion detection step** determines which pixels belong to the background using a BGS algorithm \mathcal{A} . The classification results are put in a binary **segmentation map**.
- 3 To estimate **quantities of motion** spatially, an **estimation step** divides the image plane into $\mathcal{N} \times \mathcal{N}$ spatial areas. Then, for each patch, quantities of motion are estimated by counting the number of pixels classified as foreground.
- 4 For each spatial area, a **selection step** builds a subset of \mathcal{S} patches. The elements belonging to this subset are the \mathcal{S} patches associated to the smallest quantities.
- 5 Finally, a **generation step** builds the background image by applying a pixel-wise median filter on each subset built during the previous step.



The figure above illustrates the different steps of LaBGen applied on a video sequence composed of three frames with $\mathcal{P} = 3$, $\mathcal{N} = 4$, $\mathcal{S} = 2$, and $\mathcal{A} = \text{Ground-truth}$.

3. LaBGen-OF: A Variant Incorporating Optical Flow

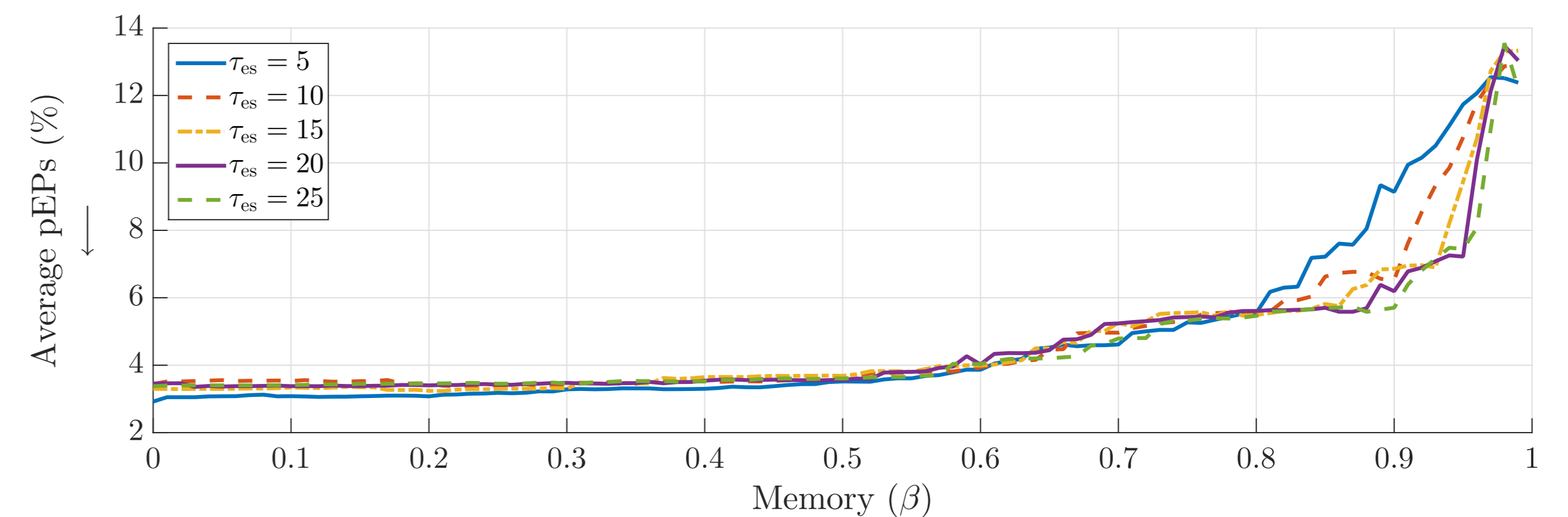
For incorporating an OF algorithm in the motion detection step of **LaBGen-OF**, we transform its output into a binary segmentation map as follows:



the application of a dense OF algorithm on the frame (a) and its successor produces a vector field such as (b) (the hue and saturation components represent the angle and magnitude, respectively). Then, the **spatially normalized ℓ^2 -norms** are computed (c), and **thresholded** according to a **parameter τ** (d), in order to get a binary segmentation map.

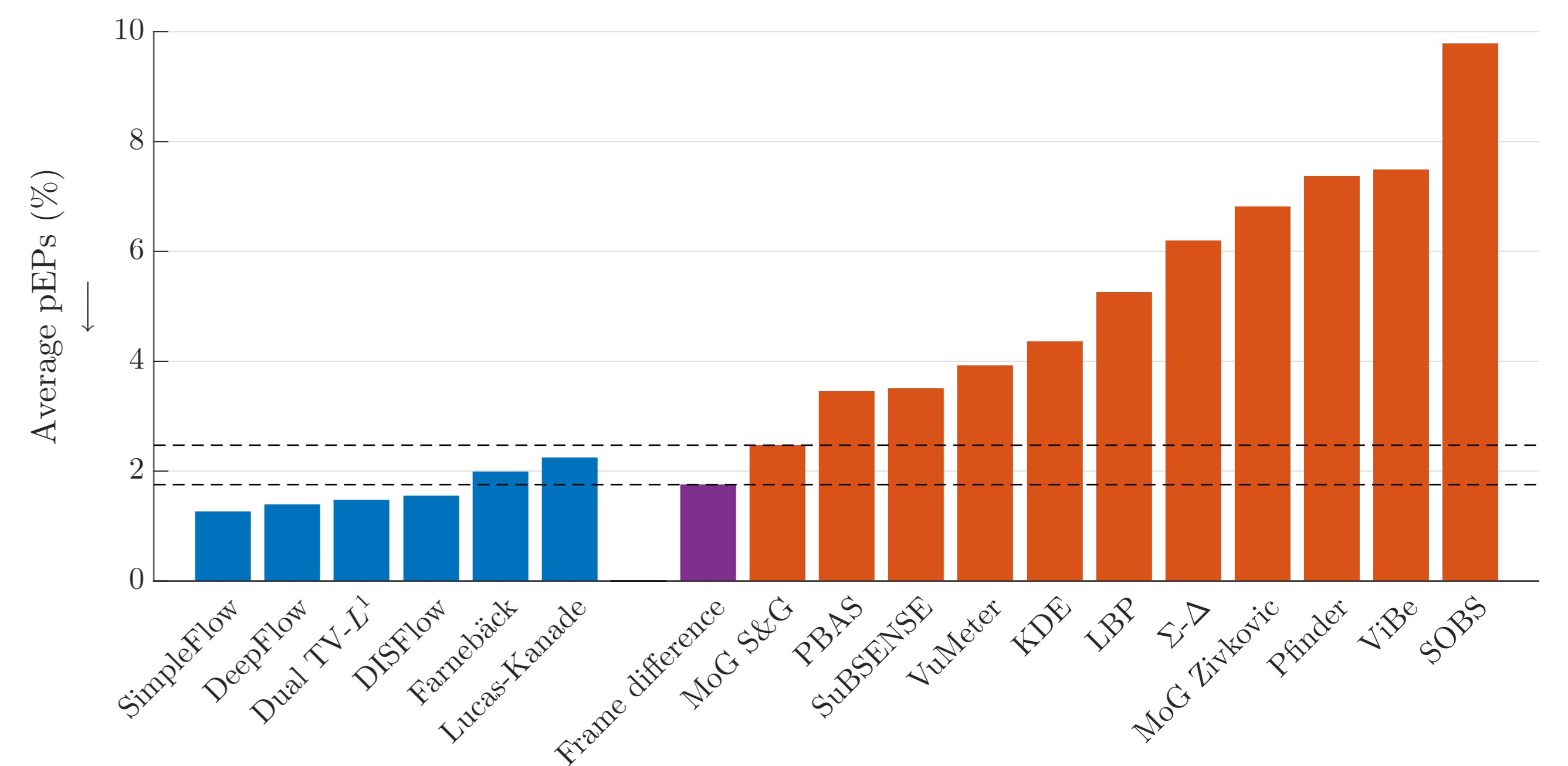
4. Impact of the Motion Detection Memory on the Performance

Our first experiment consists in **modeling the amount of memory** being used by the motion detection component to measure its impact on the performance of LaBGen. For that purpose, we use an **exponential smoothing** based BGS algorithm as a motion detector in LaBGen. Its parameter β allows us to tune the amount of memory being used. One can observe that the **performance of LaBGen decreases** as long as the **amount of memory increases**.



5. Comparison of Motion Detectors With or Without Memory

In this experiment, we compare on the SBI dataset the **average performance** achieved by LaBGen embedded with the **memoryless frame difference** and other **BGS algorithms with memory**, and LaBGen-OF with **memoryless OF algorithms**. One can observe that the average performance achieved by **LaBGen-OF** embedded with any OF algorithm is **always better** than the one with any BGS algorithm with memory.



6. Average Performance of LaBGen-OF on SBMnet

In this experiment, we finely **optimize the parameters of LaBGen-OF** on a larger set of video sequences composed of the SBI dataset, and the sequences of the SBMnet dataset provided with ground-truth. This optimization has been carried out with respect to each OF algorithm. One can observe that **most OF algorithms are adequate memoryless substitutes** for the frame difference algorithm in our background generation framework. However, the use of a good OF algorithm slows down the computational performance.

\mathcal{A}	Best parameters				Averaged metrics						Run time (fps) ↑
	\mathcal{P}	\mathcal{N}	\mathcal{S}	τ	AGE ↓	pEPs ↓	pCEPs ↓	MS-SSIM ↑	PSNR ↑	CQM ↑	
DeepFlow	3	8	119	0.04	4.0621	2.60%	1.20%	0.9708	33.1041	33.7400	5
Lucas-Kanade	1	6	63	0.03	4.2515	3.02%	1.60%	0.9718	32.8775	33.5150	44
DISFlow	1	3	57	0.02	4.7678	3.91%	2.15%	0.9520	32.3675	32.9819	124
Farneback	3	3	83	0.05	4.5974	3.42%	1.70%	0.9521	32.2720	32.8954	13
SimpleFlow	3	6	49	0.06	4.4212	2.94%	1.36%	0.9596	31.9124	32.5169	5
Dual TV-L ¹	5	10	75	0.06	4.3821	2.90%	1.41%	0.9669	31.8324	32.4793	2
LaBGen + Frame difference					4.5863	3.31%	1.63%	0.9464	31.8394	32.4585	1312

7. Comparison to Other Background Generation Methods

Here is the **Top-8 reported on the SBMnet web platform** the March 8th, 2017 in which the performance achieved by LaBGen-OF has been inserted (in blue). According to the **average ranking across categories** reported in the table below, **LaBGen-OF is now ranked first**.

Method	Average ranking ↓	A. r. across categories ↓	Average AGE ↓	Average pEPs ↓	Average pCEPs ↓	Average MS-SSIM ↑	Average PSNR ↑	Average CQM ↑	Run time (fps) ↑
MSCL (anon.)	1.17	4.75	5.9545	5.24%	1.71%	0.9410	30.8952	31.7049	unknown
LaBGen-OF	2.00	4.25	6.1897	5.66%	2.32%	0.9412	29.8957	30.7006	5
BEWiS	4.17	5.63	6.7094	5.92%	2.66%	0.9282	28.7728	29.6342	3
LaBGen	4.67	7.25	6.7090	6.31%	2.65%	0.9266	28.6396	29.4668	1312
LaBGen-P	5.83	8.00	7.0738	7.06%	3.19%	0.9278	28.4660	29.3196	126
Photomontage	6.33	10.38	7.1950	6.86%	2.57%	0.9189	28.0113	28.8719	unknown
SC-SOBS-C4	7.33	8.88	7.5183	7.11%	2.42%	0.9160	27.6533	28.5601	unknown
MAGRPCA	8.67	8.88	8.3132	9.94%	5.67%	0.9401	28.4556	29.3152	2.5
Temporal median	10.33	8.25	8.2731	9.84%	5.46%	0.9130	27.5364	28.4434	100

8. Conclusion

A **memoryless motion detection** helps reaching the **best achievable average performances** in our background generation framework. Moreover, using LaBGen-OF, we also learned that a memoryless motion detection algorithm enables to achieve a **better performance than several popular BGS algorithms** with memory. Finally, **LaBGen-OF outperforms LaBGen** embedded with the frame difference **and almost all state-of-the-art background generation methods** on the SBMnet dataset.