

Seamoc stochastic forecasting sy



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Introduction

Black assimilative ensemble run, The ensemble is built by a The GHER hydrodynamical model is implemented in the model runs Sea^{1,2} and daily in run operationally since free mode and 21/12/2011. as data-

forecast uncertainty. The ensemble is built by applying multiple, random physically consistent perturbations³ to the members. ensemble forecast allows to estimate the a priori but

When observations become available,

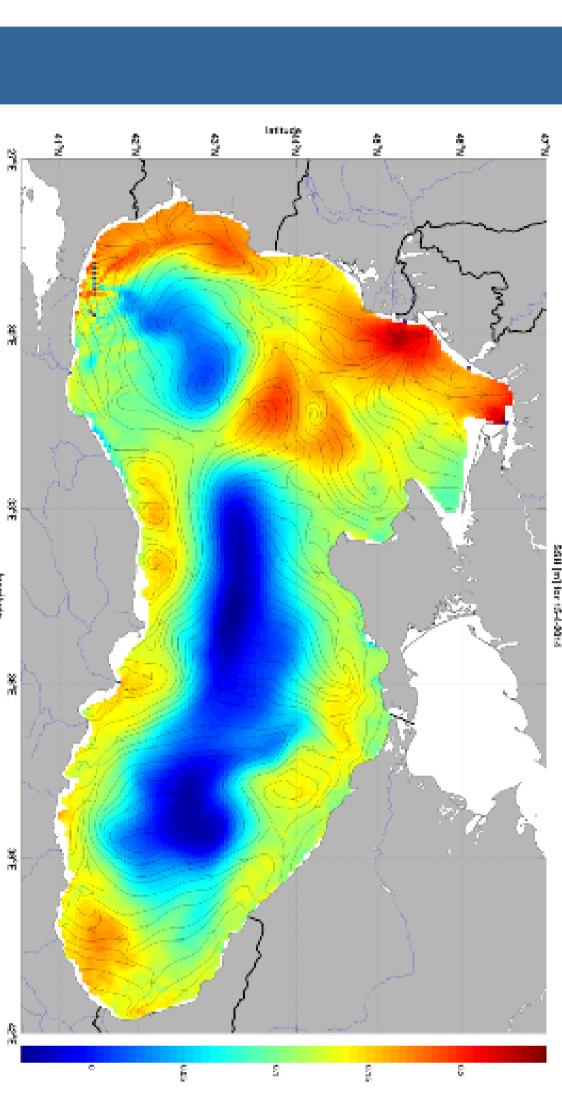
- ensemble mean) model performance <u>S</u>. assessed (validation of the
- (validation of the ensemble spread) observations are assimilated using an EnKF forecast uncertainty <u>S</u>. evaluated B posteriori

are publically available on http://www.seamod.ro expected uncertainty (as Operational forecasts of estimated with the the ocean ...r (OAK⁴) state 🤊 ensemble)

GHER hydrodynamic model

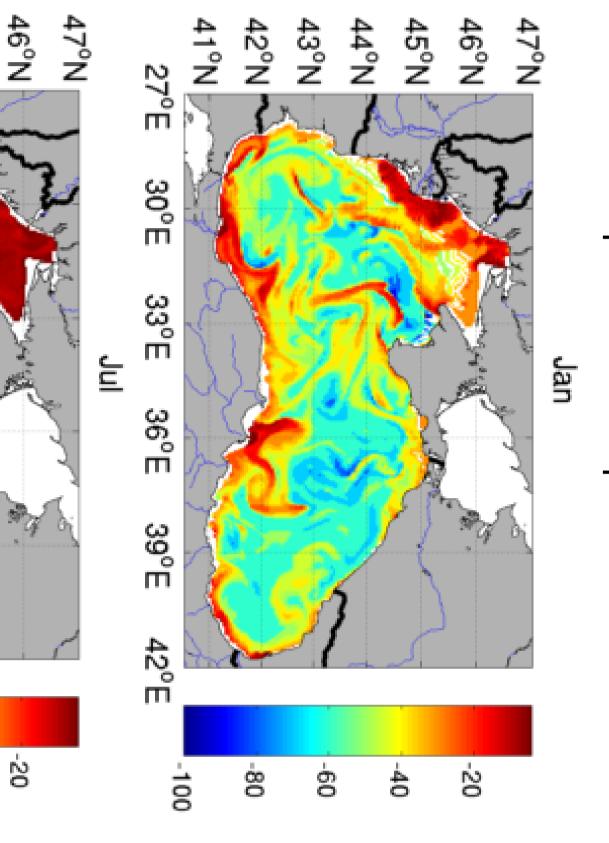
- the Black Sea model already implemented in different studies
- long-term, extensive validation (see
- horizontal resolution ~4km
- 31 vertical double-sigma levels
- Baroclinic timestep: 10 minuts
- 6 rivers, Bosphorus channel
- from NOAA NCEP GFS Bulk formulae using atmospheric fields downloaded

Model validation



- operational model simulates well the large scales:
- Rim current position
- elevation difference semi-permanent eddies from
- areas and open see 20 cm coastal
- surface and deep salinity values
- hydrodyanmic regime on the shelf
- Also simulates well shelf-open sea exchanges

- Also simulates well the mixed layed depth
- spatial and temporal evolution



- their rms error is set as 0.25°C and 0.05psu
- correction limited to 1°C (temperature), 0.3psu

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http://www.dat milation Kit	0,96	0,92	0,85	0,76	0,71	.ror
software	ر	4	U		⊢	Jays
4 Ocean Assir	П	_	ა	ა		

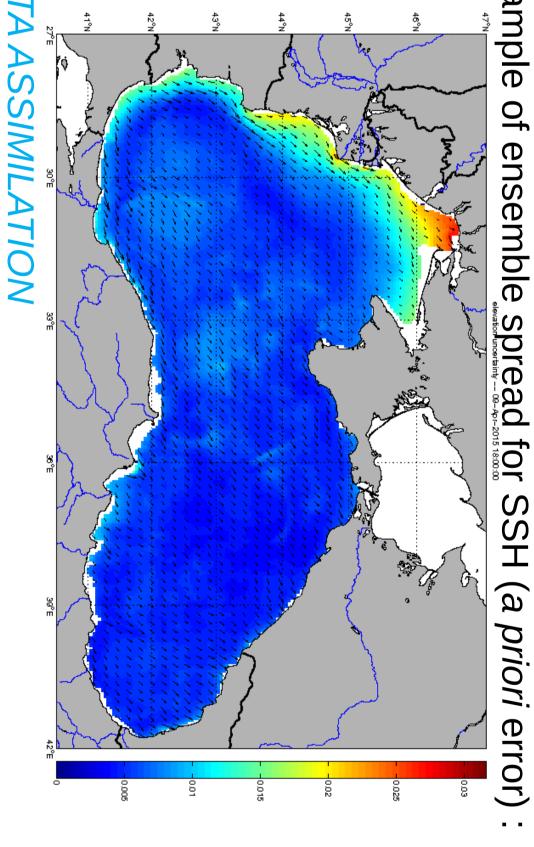
semble run and D A

ENSI EMBLE GENERATION

Mod are different in each ensemble member rivers flow and diffusion coefficients are perturbed el parameters, inputs... that are not perfectly known

- randomly, centred on our "best estimate"
- generated by applying :
 -current-aligned random perturbations on T, when creating a new member, initial conditions S fields
- in the open sea, surface elevation and velocity with different spatial correlation lengths on the shelf and in the open sea equilibrium with the density perturbation are applied the perturbation in geostrophic
- atmospheric forcing fields are perturbed so that:
 -perturbation intensity is, on average, of the same magnitude as the difference between NCEP and **ECMWF** forecasts
- -perturbations are obtained as a changing, random combination of EOFs of atmospheric timeseries

Exar



- daily assimilation of SST and ARGO profiles
- observations are supposed uncorrelated
- data assimilation localisation radius ~ 100km
- (salinity), 5cm/s (velocity), 3cm (elevation)

IPARISON W/ INDEPENDENT OBSERVATIONS

rms error	Lead days	lemperature rms error:
0,71	1	rms erro
0,76	2)r:
0,85	ω	
0,92	4	
0,96	Ŋ	

42°N

43°N

44°N

45°N

41°N

30°E

36°E

39°E

-100

80

60

6

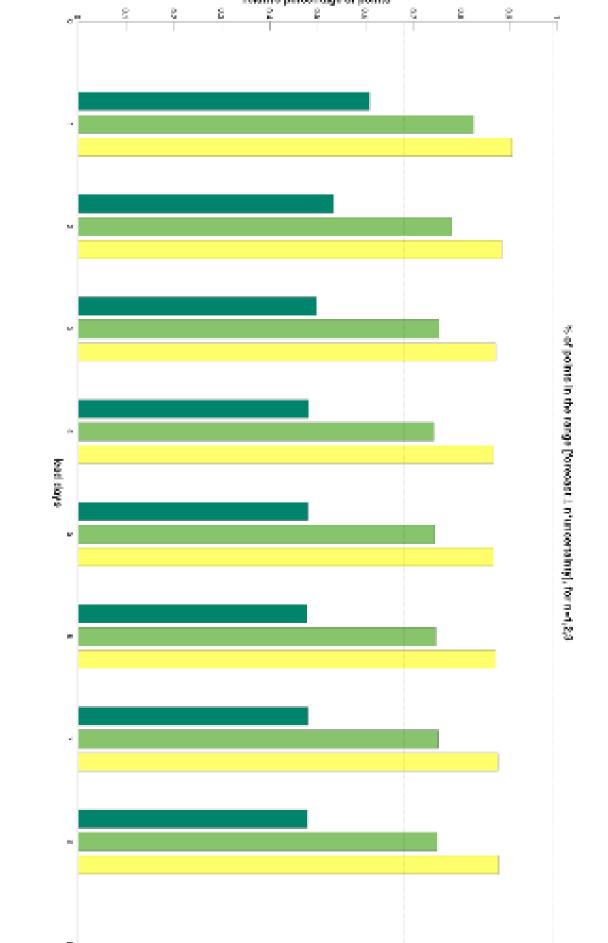
Valida ation Of the ensemble

minus The initialization corresponds sized relatively well. priori obsei ri error (estimated by the enserוועור כן. s well to the *a posteriori* error (ensemble mean יימתesting that the ensemble and rvations), well to the

that the Differences between a priori and a posteriori errors indicate 0.1° for temperature). ensemble slightly underestimates the error (e g

points If the mean. error distribution were Gaussian, would fall within 1,2, and 3 s 3 std.dev. 60,85 and 90% around the

The too low, points, again ensemb indicating that the ensemble spread is slightly simulation has slightly lower amounts



References

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