

TSP model for electric vehicle deliveries, considering speed, loading and road grades

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1 Introduction

In the current Transport White Paper [1], the European Union presents a roadmap for a more competitive and sustainable European transport system. Concerning Urban Freight Transport, responsible for about a quarter of CO_2 emissions of the transport sector, one of the goals of the EU is to achieve essentially CO_2 -free city logistics in major urban centers by 2030 by developing and deploying new and sustainable fuels and propulsion systems. The gradual phasing out of 'conventionally-fuelled' vehicles from the urban environment contributes to reduce oil dependency, greenhouse gas emissions and local air and noise pollution. To meet European air quality standards, authorities of some major European cities have already introduced Low Emissions Zones where access to urban areas is limited to freight vehicles that meet certain emissions standards.

A growing use of urban trucks based on electric, hydrogen and hybrid technologies helps reducing not only pollutant emissions, but also noise and road congestion by making night deliveries and avoiding morning and afternoon peak periods. In addition, the use of low-emission fleets also allows to mitigate the transportation sector dependency on volatile fuel prices [2] as electric engines may be powered using various energy sources including wind and solar energy.

The objective usually considered in sustainable transportation is to minimize pollution due to emissions, and equivalently energy consumption. Turning to electric mobility, pollution is related to electricity production technology, not considered in this research; driving range is the major concern nowadays, due to the limited capacity of batteries and long recharge times. Maximizing the driving range or the level of energy (state of charge of the battery) at destination leads to consider the main factors of energy consumption which are : vehicle weight, engine efficiency and consumption models, drive speed and acceleration, drive pattern, road grade, and payload ([3], [4], [5], [6]).

We define the electric vehicle travelling salesman problem (EV-TSP) and the electric vehicle routing problem (E-VRP) based on the classical TSP and on the Pollution Routing Problem (PRP) [4] and present models and preliminary results for those problems.

2 Research problem

This paper focus on the EV-TSP: given n cities find the directed cycle containing all cities that maximizes the level of available energy at the end of the route, knowing that there is no recharge operation on the tour. This objective equally maximizes the driving range of the vehicle. The classical objective of the TSP is to minimize the cost tour scheduling to fulfill delivery requests at each location. In this paper, we present an extension of the classical problem, the objective function accounts not just for travel distance and load of the vehicle on each part of the path, but also depends on electric mobility key factors: vehicle speed, slope of roads, and vehicle recharge ability while driving (as regenerative breaking and kinetic energy capture on downhill paths).

3 Mathematical programming formulation

The EV-TSP is defined on a complete graph $G = (N, A)$ where N is the set of nodes (representing cities) indexed by $i, j \in \{0, \dots, n\}$ and $A = \{(i, j) : i, j \in N, i \neq j\}$ is the set of arcs. The set $N \setminus \{0\}$ denotes the client locations (i.e. cities) while the unique depot is duplicated into an origin depot, identified as node 0 where the vehicle starts its tour, and a destination depot, identified as node $n + 1$, where the vehicle ends its tour. A tour thus becomes a Hamiltonian path starting at 0 and ending at $n + 1$. A distance d_{ij} , a road angle θ_{ij} and speed limits $(v_{ij}^{min}, v_{ij}^{max})$ are associated to all $(i, j) \in A$. The energy e_{ij} used (resp. produced) on the arc $(i, j) \in A$ equals the total power p_{ij} deployed (resp. captured) plus the power p_{ij}^{aux} used for auxiliary devices (such as air conditioner) during the course of the arc. The non-negative demand of each client $i \in N \setminus \{0\}$ is represented by q_i and there is no returning load to the depot. A vehicle, initially located at the depot, has a sufficient loading capacity and battery capacity to find a route and satisfy all demands. The battery level never exceeds the maximum capacity, C , and always has to be non negative since battery cannot be discharged below zero. The total travel time of the vehicle is limited to T . The technical parameters of the vehicle and the energy consumption model are given. The tour starts and ends at the depot, and every client is visited exactly once.

The decision variables used in the formulation are a set of binary variables x_{ij} equal to 1 if and only if arc (i, j) is in the tour; a set of binary variables $y_{ij}^l = 1$ if and only if arc (i, j) is in the tour and the demand of client l , q_l , is transported on this arc; and a set of variables v_{ij} , associated to the speed of the vehicle on arc (i, j) , which range from v_{min} to v_{max} .

The objective of the EV-TSP is to maximize the level L of available energy (or state of charge of the battery) at the end of the tour. This level is defined using a generic Energy Consumption Model proposed and tested in the literature ([4],[7]) where vehicle weight, speed and road slope are considered.

At the beginning of the tour, the current available energy level L_0 is known. The level of energy is limited by the maximum capacity of the battery and never exceeds it even if more energy is available due to recovery. Moreover, the level L_j of available energy at each node $j \in N \cup \{n + 1\}$ cannot fall below zero. Therefore the level of energy can be calculated as:

$$L_j = \begin{cases} 0 & \text{if } L_i - e_{ij} x_{i,j} \leq 0 \\ C & \text{if } L_i - e_{ij} x_{i,j} \geq 0 \\ L_i - e_{ij} x_{i,j} & \text{otherwise.} \end{cases}$$

The EV-TSP mathematical model states as follows :

$$\text{maximize } L_{n+1} \quad (1)$$

$$\text{subject to :} \quad \sum_{i=0}^n x_{ij} = 1 \quad \forall j \in N \setminus \{0\} \quad (2)$$

$$\sum_{j=1}^{n+1} x_{ij} = 1 \quad \forall i \in N \quad (3)$$

$$u_0 = 1; u_{n+1} = n + 2 \quad (4)$$

$$2 \leq u_i \leq n + 1 \quad \forall i \in N \setminus \{0\} \quad (5)$$

$$u_i - u_j + 1 \leq n(1 - x_{ij}) \quad \forall i, j \in N, \forall (i, j) \in A \quad (6)$$

$$y_{ij}^l \leq x_{ij} \quad \forall (i, j) \in A, \forall l \in N \setminus \{0\} \quad (7)$$

$$u_j - u_i + y_{ij}^l n + (1 - x_{ij}) 2n \geq 0 \quad \forall (i, j) \in A, \forall j, l \in N \setminus \{0\} \quad (8)$$

$$e_{ij} = (p_{ij} + p_{ij}^{aux}) \frac{d_{ij}}{v_{ij}} \quad \forall (i, j) \in A \quad (9)$$

$$p_{ij} = M_{ij} g v_{ij} \sin\theta_{ij} + 0.5 c_d \rho A v_{ij}^3 + c_r M_{ij} g v_{ij} \cos\theta_{ij} \quad \forall (i, j) \in A \quad (10)$$

$$0 \leq L_i \leq C \quad \forall i \in N \cup \{n + 1\} \quad (11)$$

$$L_j = L_i - e_{ij} x_{ij} - s_j \quad \forall j \in N \setminus \{0\}, \forall (i, j) \in A \quad (12)$$

$$\sum_{i=0}^n \sum_{j=1}^{n+1} x_{ij} \frac{d_{ij}}{v_{ij}} \leq T \quad (13)$$

$$v_{min} \leq v_{ij} \leq v_{max} \quad \forall (i, j) \in A \quad (14)$$

$$x_{ij}, y_{ij}^l \in \{0, 1\} \quad \forall (i, j) \in A \quad (15)$$

$$u_i \in \mathbb{N}, s_j \in \mathbb{R}_+ \quad \forall i \in N, \forall j \in N \setminus \{0\} \quad (16)$$

The objective function (1) consists in maximizing the level of available energy at the end of the route. Constraints (2) indicate that the vehicle leaves each node i exactly once, and constraints (3) state that a vehicle enters each node j exactly once. Constraints (4)-(6) ensure to exclude subtours using integer variable u_i , $i \in N \cup \{n + 1\}$, that determine the sequence number in which node i is visited as in the formulation of Miller-Tucker-Zemlin [8]. Constraints (4) ensure that the starting and arrival nodes are the depot. Constraints (5) ensure that for each node i , excluding the depot, the integer variable u_i ranges from 2 to $n + 1$. Constraints (6) define each node rank : if $x_{ij} = 1$, the next node j has to satisfy constraints $u_j \geq u_i + 1$; otherwise if $x_{ij} = 0$, constraints (6) become $u_i - u_j \leq n - 1$ that is always true, as $2 \leq u_j$ and $u_i \leq n + 1$. Constraints (7) guarantee that if $x_{ij} = 0$ (i.e. arc (i, j) is not in the tour) then there is no load transported on this arc: $y_{ij}^l = 0$. Otherwise, if $x_{ij} = 1$, constraints (8) ensure that $y_{ij}^l = 1$ for all arcs (i, j) such that $u_i > u_j$. Note that for nodes already visited, $u_i \leq u_j$, $y_{ij}^l = 0$ due to the objective function.

Constraints (9) represent the energy e_{ij} required (resp. produced) when the vehicle travels the arc, and constraints (10) define the instantaneous power p_{ij} needed to overcome gravity, drag and rolling resistance forces (cfr. [4]), p_{ij} is negative when energy is recovered. In this model we consider that speed is constant on any arc (acceleration is null). In (10) $M_{ij} = M_E + \sum_{l=1}^n q_l y_{ij}^l$ is the mass of the vehicle (in kg), i.e. the empty vehicle weight, M_E , plus carried load on arc (i, j) ; g is the gravitational constant ($9.81m/s^2$), ρ is the air density (kg/m^3), A is the frontal surface area of the vehicle (in m^2), and c_r and c_d are the dimensionless coefficients of rolling resistance and drag, respectively. As in [4] all parameters are constant on a given arc but load and speed may change from one arc to another.

Battery-relative constraints (11)-(12) imply that the level of energy in the battery, L_i , cannot fall below zero nor exceed the capacity of the battery, s is a non negative slack variable that allows to include in the tour arcs for which energy gain would overcome the battery capacity (but no storage is performed beyond the limit), and excludes arcs for which energy is missing. As the energy function is monotonic on each arc, the constraints at each node imply that this property is valid at any point of the arc.

Constraint (13) ensures that travel time limit is not exceeded. Constraints (14) define lower and upper bounds for the speed on each arc. Finally, constraints (15)-(16) define binary and non-negativity conditions on the variables.

4 Results and perspectives

This paper presents a new TSP model for transportation using electric vehicles. The problem is to deliver each customer order, and optimize the battery state of charge at the end of the route. It deals with orders weights, road characteristics and vehicle specifications. An important feature of our approach is the generic formulation adaptable to all types of vehicles.

In order to test the model, we build small instances to represent real-life cases. The distances between the nodes, the altitude of different locations, etc. have been taken into account to ensure the consistency of the data. The goal is to check the validity of the model and obtain useful insights for the development of algorithms for realistic large size problems. Preliminary results guide future work towards optimization methods combining heuristics and exact algorithms.

References

- [1] European Commission. “White Paper - Roadmap to a Single European Transport Area - Towards a competitive and Resource Efficient Transport System”. *COM(2011)-144*.
- [2] Gonçalves, G., Bravo, J., Baptista, P., Silva, C., and Farias, T. “Monitoring and simulation of fuel cell electric vehicles”, *World Electric Vehicle Journal*, 3, 0-100 (2009).
- [3] Baum, M. Dibbelt, J., Pajor, T. and Wagner, D. “Energy-Optimal Routes for Electric Vehicles”, in *Proceedings of the 21st ACM SIGSPATIAL International Conference on Advances in Geographic Information Systems*, *ACM Press* (2013).
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- [6] Touati-Moungla, N., V. Jost. “Combinatorial optimization for electric vehicles management”, *Journal of Energy and Power Engineering* 6(5) 738-743 (2012).
- [7] Prins, R., Hurlbrink, R. and Winslow, L. “Electric Vehicle Energy Usage Modeling and Measurement”, *International Journal of Modern Engineering* 13(1) (2013).
- [8] Miller, C. E., Tucker, A. W. and Zemlin, R. A. “Integer programming formulations and traveling salesman problems”, *J. ACM* Vol. 7, pp. 326-329 (1960).



5th International Workshop on Freight Transportation and Logistics

May 21 - 25, Mykonos, Greece

Workshop Schedule



ATHENS UNIVERSITY
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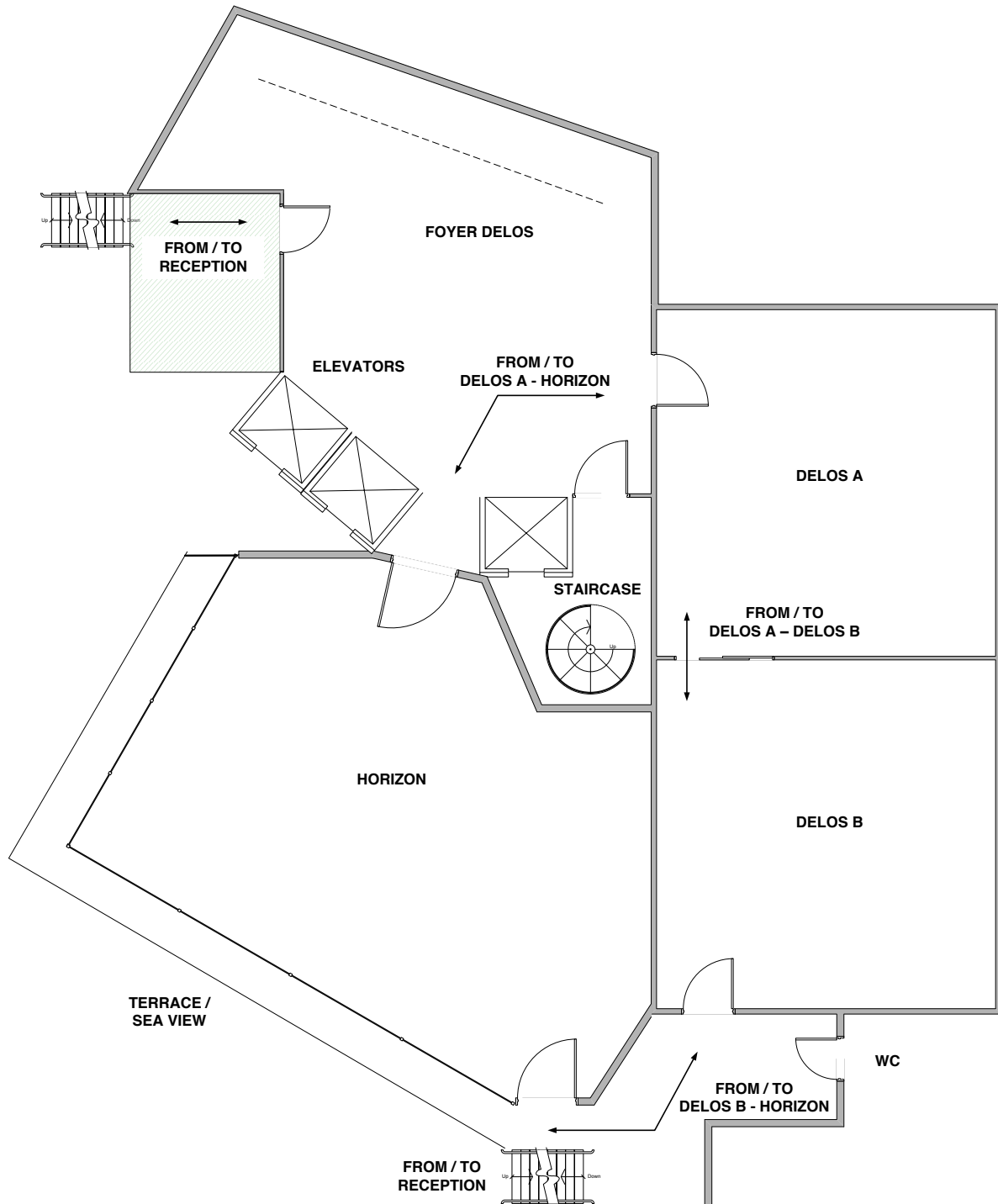
Event Timeline

DATE		TIME	EVENT
May 20	Sunday	20:00	Welcome Reception
May 21	Monday	08:30 – 08:50	Opening Session
		09:00 – 10:30	Sessions Mo.1.(a,b,c)
		10:30 – 11:00	Coffee Break
		11:00 – 12:30	Sessions Mo.2.(a,b,c)
		12:30 – 14:30	Lunch
		14:30 – 16:00	Sessions Mo.3.(a,b,c)
		16:00 – 16:30	Coffee Break
		16:30 – 18:00	Sessions Mo.4.(a,b,c)
May 22	Tuesday	09:00 – 10:30	Sessions Tu.1.(a,b,c)
		10:30 – 11:00	Coffee Break
		11:00 – 12:30	Sessions Tu.2.(a,b,c)
		12:30 – 14:30	Lunch
		14:30 – 16:00	Sessions Tu.3.(a,b,c)
		16:00 – 16:30	Coffee Break
		16:30 – 18:00	Sessions Tu.4.(a,b,c)
May 23	Wednesday	07:45 – 15:00	Excursion to Delos
		15:00 – 16:00	Lunch
May 24	Thursday	09:00 – 10:30	Sessions Th.1.(a,b,c)
		10:30 – 11:00	Coffee Break
		11:00 – 12:30	Sessions Th.2.(a,b,c)
		12:30 – 14:00	Lunch
		14:00 – 15:30	Sessions Th.3.(a,b,c)
		15:30 – 16:00	Coffee Break
		16:00 – 18:00	Sessions Th.4.(a,b,c)
		20:30	Workshop Dinner and Party
May 25	Friday	09:00 – 10:30	Sessions Fr.1.(a,b,c)
		10:30 – 11:00	Coffee Break
		11:00 – 12:30	Sessions Fr.2.(a,b,c)
		12:30 – 14:30	Lunch
		14:30 – 16:00	Sessions Fr.3.(a,b,c)
		16:00 – 16:30	Coffee Break
		16:30 – 18:00	Sessions Fr.4.(a,b)
		20:00	Farewell Drinks

Facilities Layout

Event	Meeting Room
Opening Session	DELOS A + DELOS B (joined)
Sessions ".a"	DELOS A
Sessions ".b"	DELOS B
Sessions ".c"	HORIZON

All meeting rooms are located one level above the Reception Desk of the *Royal Myconian Resort*.



ODYSSEUS 2012 Workshop Schedule

Regular Sessions

TIME SLOT \ ROOM	DELOS A	DELOS B	HORIZON	
Monday	09:00 – 10:30	Vehicle Routing I	Railway Logistics	Ship Routing and Scheduling
	11:00 – 12:30	Stochastic Routing I	Capacitated Vehicle Routing Problem	City Logistics I
	14:30 – 16:00	Inventory Routing I	Network Models for Humanitarian Logistics	Maritime Logistics I
	16:30 – 18:00	Network Design I	Dial-a-Ride Routing	Stochastic Routing II
Tuesday	09:00 – 10:30	Multi-Period Routing	Maritime Logistics II	Vehicle Routing II
	11:00 – 12:30	Arc Routing I	City Logistics II	Sustainable Routing
	14:30 – 16:00	Two-Echelon Routing	Vehicle Routing III	Routing and Scheduling I
	16:30 – 18:00	Arc Routing II	Home Health Care Logistics	Routing and Scheduling II
Thursday	09:00 – 10:30	Traveling Salesman Problem Variants	Container Logistics	Routing I
	11:00 – 12:30	Transportation Risk	Packing Logistics	Dynamic Routing
	14:00 – 15:30	Time-Dependent Routing	Scheduling	Inventory Routing II
	16:00 – 18:00	Production -- Distribution	Freight Transportation Networks	Vehicle Routing IV
Friday	09:00 – 10:30	Vehicle Routing V	Maritime Transportation I	Network Design II
	11:00 – 12:30	Maritime Transportation II	Emergency Logistics	Dynamic Vehicle Routing
	14:30 – 16:00	Routing with Loading Constraints	Routing II	Network Design and Uncertainty
	16:30 – 18:00	Location-Routing	Supply Chain Logistics	–

Monday, 09:00 – 10:30

Session Mo.1.a: Vehicle Routing I

DELOS A

Chair: *Frédéric Semet, École Centrale de Lille*

09:00 – 09:30 A Continuous Approximation Model for the Fleet Composition Problem
Ola Jabali, Gilbert Laporte and Michel Gendreau

09:30 – 10:00 A Polyhedral Approach for Generalizing the Miller-Tucker-Zemlin Subtour Elimination Constraints for Routing Problems
Tolga Bektaş and Luis Gouveia

10:00 – 10:30 An Exact Method to Solve the Multi-trip Vehicle Routing Problem with Multi Time Windows
Florent Hernandez, Frédéric Semet, Rodolphe Giroudeau and Olivier Naud

Session Mo.1.b: Railway Logistics

DELOS B

Chair: *Michel Bierlaire, École Polytechnique Fédérale de Lausanne*

09:00 – 09:30 Optimal Loading Plan for Multiple Trains in Container Terminals
Davide Anghinolfi, Lorenzo Foti, Marco Maratea, Massimo Paolucci and Silvia Siri

09:30 – 10:00 The Locomotive Fleet Fueling Problem
Mor Kaspi and Tal Raviv

10:00 – 10:30 Cost Optimization for the Capacitated Railroad Blocking and Train Design Problem
Burak Boyaci, Viswanathan Prem Kumar, Stefan Binder and Michel Bierlaire

Session Mo.1.c: Ship Routing and Scheduling

HORIZON

Chair: *Kjetil Fagerholt, Norwegian University of Science and Technology*

09:00 – 09:30 Robust Planning of Refinery Operations with Uncertain Ship Arrivals
Jens Bengtsson, David Bredström, Patrik Flisberg and Mikael Rönnqvist

09:30 – 10:00 A Branch-and-Price Method for a Ship Routing and Scheduling Problem with Coupling and Synchronization Constraints
Magnus Stålhane, Henrik Andersson and Marielle Christiansen

10:00 – 10:30 A Branch-and-Price Algorithm for a Fleet Deployment Problem with Fairly Evenly Spread Voyages
Inge Norstad, Henrik Andersson, Kjetil Fagerholt and Magnus Stålhane

Monday, 11:00 – 12:30

Session Mo.2.a: Stochastic Routing I

DELOS A

Chair: *Patrick Jaillet, Massachusetts Institute of Technology*

11:00 – 11:30 The Robust Rounded Capacity Inequalities
Chrysanthos E. Gounaris, Wolfram Wiesemann and Christodoulos A. Floudas

11:30 – 12:00 A Pickup and Delivery Single Vehicle Routing Problem with Stochastic Demands
Dimitrios G. Pandelis, Constantinos C. Karamatsoukis and Epaminondas G. Kyriakidis

12:00 – 12:30 Routing Optimization with Deadlines under Uncertainty
Patrick Jaillet, Jin Qi and Melvyn Sim

Session Mo.2.b: Capacitated Vehicle Routing Problem

DELOS B

Chair: *Jens Lysgaard, Aarhus University*

11:00 – 11:30 An Exact Approach for the Clustered Vehicle Routing Problem
Maria Battarra, Güneş Erdoğan and Daniele Vigo

11:30 – 12:00 Circuit based formulations for the Unit Demand Vehicle Routing Problem
Luis Gouveia, Pierre Pesneau and Maria Teresa Godinho

12:00 – 12:30 Dual-Optimal Inequalities for the Capacitated Vehicle Routing Problem
Jens Lysgaard

Session Mo.2.c: City Logistics I

HORIZON

Chair: *Teodor Gabriel Crainic, Université du Québec à Montréal and CIRRELT*

11:00 – 11:30 A Collaborative Freight Transportation System in City Logistics
Frédéric Semet, Luce Brotcorne and Alexandre Huart

11:30 – 12:00 The City Logistics Facility Location Problem
Nabil Absi, Dominique Feillet, Thierry Garaix and Olivier Guyon

12:00 – 12:30 Modelling Demand Uncertainty in Two-Tiered City Logistics Planning – A Monte Carlo Study
Fausto Errico, Walter Rei, Nicoletta Ricciardi and Teodor Gabriel Crainic

Monday, 14:30 – 16:00

Session Mo.3.a: Inventory Routing I

DELOS A

Chair: *Ann Melissa Campbell, University of Iowa*

- 14:30 – 15:00 A Two-Stage Decomposition Algorithm for Single Product Maritime Inventory Routing
Dimitri J. Papageorgiou, George L. Nemhauser, Joel Sokol and Ahmet B. Keha
- 15:00 – 15:30 Efficient Inventory Routing in an Automated Teller Machine Network
Roel G. van Anholt and Iris F.A. Vis
- 15:30 – 16:00 The Use of Telemetry to Improve Routing Costs
Ann Melissa Campbell and Amit Verma

Session Mo.3.b: Network Models for Humanitarian Logistics

DELOS B

Chair: *Tadashi Yamada, Kyoto University*

- 14:30 – 15:00 Flow-based Mathematical Formulation and Strengthening Cuts for the Cumulative CVRP
Sandra Ulrich Ngueveu and Mathieu Lacroix
- 15:00 – 15:30 Exact and Heuristics Strategies for Solving the Generalized Vehicle Routing Problem
H. Murat Afsar, Christian Prins and Andréa Cynthia Santos
- 15:30 – 16:00 Designing Supply Chain–Transport Supernetworks within the Framework of MPEC
Tadashi Yamada, Yuki Nakamura and Eiichi Taniguchi

Session Mo.3.c: Maritime Logistics I

HORIZON

Chair: *Marielle Christiansen, Norwegian University of Science and Technology*

- 14:30 – 15:00 A Hybrid Approach for Loading Liquid Bulk Vessels
Rowan Van Schaeren, Wout Dullaert, Birger Raa and Pierre Schaus
- 15:00 – 15:30 Ship Scheduling with Time-Varying Draft
Elena Kelareva, Philip Kilby, Sylvie Thiébaux and Mark Wallace
- 15:30 – 16:00 Branch-and-Price for Creating an Annual Delivery Program of Multi-Product Liquefied Natural Gas
Jørgen Glomvik Rakke, Henrik Andersson, Marielle Christiansen and Guy Desaulniers

Monday, 16:30 – 18:00

Session Mo.4.a: Network Design I

DELOS A

Chair: *Tolga Bektaş, University of Southampton*

16:30 – 17:00 Designing Service Networks in Liner Shipping
Judith Mulder and Rommert Dekker

17:00 – 17:30 A Hybrid Evolutionary Algorithm for the Fixed-Charge Capacitated Multicommodity Network Design Problem
Dimitris Paraskevopoulos, Tolga Bektaş, Chris N. Potts and Teodor Gabriel Crainic

17:30 – 18:00 The Congested Multicommodity Network Design Problem
Dimitris Paraskevopoulos, Sinan Gürel and Tolga Bektaş

Session Mo.4.b: Dial-a-Ride Routing

DELOS B

Chair: *Stefan Irnich, Johannes Gutenberg University Mainz*

16:30 – 17:00 The Dial-a-Ride Problem with Split Requests and Profits
Sophie N. Parragh, Bernardo Almada-Lobo and Jorge Pinho de Sousa

17:00 – 17:30 Hybrid Variable Neighborhood Search for the Dial-a-Ride Problem
Verena Schmid and Sophie N. Parragh

17:30 – 18:00 Efficient Handling of Ride-Time Constraints in Column Generation Subproblems for the Dial-a-Ride Problem
Timo Gschwind and Stefan Irnich

Session Mo.4.c: Stochastic Routing II

HORIZON

Chair: *Michel Gendreau, École Polytechnique de Montréal and CIRRELT*

16:30 – 17:00 A Stochastic Inventory Routing Problem for Infectious Medical Waste Collection
Pamela C. Nolz, Nabil Absi and Dominique Feillet

17:00 – 17:30 Real-World Patient Transportation
Ulrike Ritzinger, Jakob Puchinger, Christian Rudloff and Richard F. Hartl

17:30 – 18:00 Vehicle Routing with Soft Time Windows and Stochastic Travel Times: A Column Generation and Branch-and-Price Solution Approach
Duygu Taş, Michel Gendreau, Nico P. Dellaert, Tom van Woensel and A.G. de Kok

Tuesday, 09:00 – 10:30

Session Tu.1.a: Multi-Period Routing

DELOS A

Chair: *Claudia Archetti, University of Brescia*

09:00 – 09:30 A Column Generation Algorithm to Solve a Synchronized Log-Truck Scheduling Problem

Rix Greg, Louis-Martin Rousseau and Gilles Pesant

09:30 – 10:00 Collaborative Template-based Tabu Search and Branch-and-Cut Methods for the Consistent Vehicle Routing Problem

Panagiotis P. Repoussis, Chrysanthos E. Gounaris, Foteini Stavropoulou, Christos D. Tarantilis and Christodoulos A. Floudas

10:00 – 10:30 Free Newspaper Delivery Optimisation

Claudia Archetti, Karl F. Doerner and Fabien Tricoire

Session Tu.1.b: Maritime Logistics II

DELOS B

Chair: *Rommert Dekker, Erasmus University Rotterdam*

09:00 – 09:30 Modeling the Maritime Fleet Size and Mix Problem: A Case Study

Giovanni Pantuso, Kjetil Fagerholt and Stein W. Wallace

09:30 – 10:00 A Bi-Level Modeling Approach Capturing Interactions between Shippers and Carriers

Hyangsook Lee, Maria Boile and Sotirios Theofanis

10:00 – 10:30 Optimizing Recovery Actions and Buffer Times in Liner Shipping Networks

Judith Mulder, Mehdi Sharifyazdi and Rommert Dekker

Session Tu.1.c: Vehicle Routing II

HORIZON

Chair: *Ulrich Derigs, University of Cologne*

09:00 – 09:30 Constraint Violation in Real-World Vehicle Routing

Matteo Salani, Lorenzo Ruinelli and Luca Maria Gambardella

09:30 – 10:00 Milk Collection in Western Norway Using Trucks and Trailers

Arild Hoff

10:00 – 10:30 On a Multi-Trip Tractor and Trailer Vehicle Routing Problem with Driver Regulations

Ulrich Vogel and Ulrich Derigs

Tuesday, 11:00 – 12:30

Session Tu.2.a: Arc Routing I

DELOS A

Chair: *Ángel Corberán, University of Valencia*

11:00 – 11:30 Analysis of Pricing Problem Relaxations for the Capacitated Arc Routing Problem

Claudia Bode and Stefan Irnich

11:30 – 12:00 Profitable Mixed Capacitated Arc Routing and Related Problems

Enrique Benavent, Ángel Corberán, Luis Gouveia, Maria Cândida Mourão and Leonor Santiago Pinto

12:00 – 12:30 A Branch-and-Cut Algorithm for the Team Orienteering Arc Routing Problem

Claudia Archetti, Ángel Corberán, Isaac Plana, Maria Grazia Speranza and José María Sanchis

Session Tu.2.b: City Logistics II

DELOS B

Chair: *Angélica Lozano, National Autonomous University of Mexico*

11:00 – 11:30 Impact of Time-Dependent Travel Times on Routing in City Logistics

Jan Fabian Ehmke, Carsten Tilger and Dirk Christian Mattfeld

11:30 – 12:00 Optimization of a Shared Passengers and Goods Urban Transportation Network

Renaud Masson, Anna Trentini, Fabien Lehuédé, Olivier Péton, Houda Tlahig and Nicolas Malhéné

12:00 – 12:30 Impacts of Time Windows Restrictions on Urban Freight Corridors: Mexico City Case

Liliana Lyons, Angélica Lozano, Francisco Granados, Alejandro Guzmán and Juan Pablo Antún

Session Tu.2.c: Sustainable Routing

HORIZON

Chair: *Gilbert Laporte, HEC Montréal and CIRRELT*

11:00 – 11:30 A Real-life Application of the Dynamic Waste Collection Vehicle Routing Problem with Time Windows

Allan Larsen, Kristian Milo Hauge, Allan Olsen and Stefan Ropke

11:30 – 12:00 Modeling and Solving the Time Dependent Vehicle Routing and Scheduling Problem with Environmental Considerations

Konstantinos G. Zografos and Konstantinos N. Androusoyopoulos

12:00 – 12:30 The Time-Dependent Pollution Routing Problem

Anna Franceschetti, Tom van Woensel, Dorothée Honhon, Tolga Bektaş and Gilbert Laporte

Tuesday, 14:30 – 16:00

Session Tu.3.a: Two-Echelon Routing

DELOS A

Chair: *Roberto Tadei, Politecnico di Torino*

14:30 – 15:00 A Branch-and-Cut Algorithm for the Two-Echelon Location-Routing Problem
Viet Phuong Nguyen, Christian Prins, Caroline Prodhon and Juan Guillermo Villegas

15:00 – 15:30 Solving the Two-Echelon Capacitated Vehicle Routing Problem to Optimality
Aristide Mingozzi, Roberto Roberti, Roberto Wolfler Calvo and Roberto Baldacci

15:30 – 16:00 A Reactive GRASP with Path Relinking for the Two-Echelon Vehicle Routing Problem
Teodor Gabriel Crainic, Simona Mancini, Roberto Tadei and Guido Perboli

Session Tu.3.b: Vehicle Routing III

DELOS B

Chair: *Fabien Tricoire, University of New South Wales*

14:30 – 15:00 Operational Transportation Planning of Freight Forwarding Companies in Carrier Coalitions
Xin Wang, Herbert Kopfer and Michel Gendreau

15:00 – 15:30 Joint Demand Management and Vehicle Routing in E-fulfillment
Christine Currie, Richard Eglese and Arne K. Strauss

15:30 – 16:00 An Adaptive Metaheuristic Framework for Vehicle Routing Problems with Fixed Fleet Size
Stefanie Kritzinger, Karl F. Doerner, Richard F. Hartl and Fabien Tricoire

Session Tu.3.c: Routing and Scheduling I

HORIZON

Chair: *Jacques Desrosiers, HEC Montréal and GERAD*

14:30 – 15:00 Logistics of Clinical Testing: A Prioritized Bicriteria Heuristic for Collection for Processing Problem
F. Sibel Salman, Eda Yücel, E. Lerzan Örmeci and Esma S. Gel

15:00 – 15:30 Vehicle Routing with Time Windows Considering Driving and Working Hour Regulations
Maryam Steadie Seifi, Said Dabia, Tom van Woensel and Nico P. Dellaert

15:30 – 16:00 Workforce Routing and Scheduling for Maintenance Operations in Electricity Networks
Frank Meisel and Asvin Goel

Tuesday, 16:30 – 18:00

Session Tu.4.a: Arc Routing II

DELOS A

Chair: *Bruce Golden, University of Maryland*

16:30 – 17:00 The Road Marking Problem with Refill Operations
Maria Angélica Salazar-Aguilar, André Langevin and Gilbert Laporte

17:00 – 17:30 A Matheuristic for the Team Orienteering Arc Routing Problem
Ángel Corberán, Isaac Plana, José María Sanchis, Maria Grazia Speranza and Claudia Archetti

17:30 – 18:00 The Downhill Plowing Problem with Multiple Plows
Benjamin Dussault, Bruce Golden and Edward Wasil

Session Tu.4.b: Home Health Care Logistics

DELOS B

Chair: *Mike Hewitt, Rochester Institute of Technology*

16:30 – 17:00 Routing of Home Care Staff Members with Synchronization Requirements
Dorota Slawa Mankowska, Christian Bierwirth and Frank Meisel

17:00 – 17:30 Medium Term Planning for Home Health Care Services
Andrea Trautsamwieser and Patrick Hirsch

17:30 – 18:00 Estimating the Cost of Continuity of Care in Home Health Care Delivery
Mike Hewitt and Maciek Nowak

Session Tu.4.c: Routing and Scheduling II

HORIZON

Chair: *Guy Desaulniers, École Polytechnique de Montréal and GERAD*

16:30 – 17:00 A Branch-and-Cut Algorithm for the Single Truck and Trailer Routing Problem with Satellite Depots
José M. Belenguer, Antonio Martínez, Christian Prins, Caroline Prodhon, Juan G. Villegas and Enrique Benavent

17:00 – 17:30 Stabilized Dynamic Constraint Aggregation for Solving Set Partitioning Problems
Pascal Benchimol, Guy Desaulniers and Jacques Desrosiers

17:30 – 18:00 A Branch-Price-and-Cut Algorithm for the Workover Rig Routing Problem
Guy Desaulniers, Glaydston Mattos Ribeiro and Jacques Desrosiers

Thursday, 09:00 – 10:30

Session Th.1.a: Traveling Salesman Problem Variants

DELOS A

Chair: *Renata Mansini, University of Brescia*

09:00 – 09:30 The Bicycle Repositioning Problem with Demand Intervals
Güneş Erdoğan, Gilbert Laporte and Roberto Wolfler Calvo

09:30 – 10:00 The Clustered Orienteering Problem
Enrico Angelelli, Claudia Archetti and Michele Vindigni

10:00 – 10:30 The Capacitated Traveling Purchaser Problem with Total Quantity Discount
Renata Mansini and Daniele Manerba

Session Th.1.b: Container Logistics

DELOS B

Chair: *Der-Horng Lee, National University of Singapore*

09:00 – 09:30 Real-Time Container Storage Location Assignment at a Seaport Container Transshipment Terminal Part II
Matthew E.H. Petering

09:30 – 10:00 An Optimization Model for Container Distribution with Inventory and Time Constraints
Kristina Sharypova, Teodor Gabriel Crainic, Tom van Woensel and Jan Fransoo

10:00 – 10:30 Tactical Feeder Scheduling Problem in a Container Transshipment Hub
Der-Horng Lee and Jian Gang Jin

Session Th.1.c: Routing I

HORIZON

Chair: *Giovanni Righini, University of Milan*

09:00 – 09:30 An Iterated Local Search to solve the Node, Edge and Arc Routing Problem
Mauro Dell'Amico, José Carlos Díaz Díaz, Geir Hasle and Manuel Iori

09:30 – 10:00 Integrating Return Flows in Warehouse Order Picking
Susanne Wruck, Kees Jan Roodbergen, Iris F.A. Vis and Jaap Boter

10:00 – 10:30 Optimizing Waste Collection: A Branch-and-Cut-and-Price Algorithm
Alberto Ceselli, Giovanni Righini and Emanuele Tresoldi

Thursday, 11:00 – 12:30

Session Th.2.a: Transportation Risk

DELOS A

Chair: *Irina Gribkovskaia, Molde University College*

11:00 – 11:30 A Lagrangean Decomposition for Tunnel Interdiction in Hazmat Transportation
Edoardo Amaldi, Maurizio Bruglieri, Roberto Maja and Alessandro Laurita

11:30 – 12:00 Risk based Routing and Scheduling of Hazardous Material in Urban Areas
Rojee Pradhananga, Eiichi Taniguchi and Tadashi Yamada

12:00 – 12:30 Passenger and Pilot Risk Minimization in Offshore Helicopter Transportation
Fubin Qian, Irina Gribkovskaia, Gilbert Laporte and Øyvind Halskau sr.

Session Th.2.b: Packing Logistics

DELOS B

Chair: *Guido Perboli, Politecnico di Torino*

11:00 – 11:30 An Exact Algorithm for Bin Packing Problems with Item Fragmentation
Marco Casazza and Alberto Ceselli

11:30 – 12:00 The Generalized Bin Packing Problem: Models and Bounds
Teodor Gabriel Crainic, Roberto Tadei, Guido Perboli and Mauro Maria Baldi

12:00 – 12:30 A Stochastic Bin Packing Model for Logistical Capacity Planning
Teodor Gabriel Crainic, Guido Perboli, Jean-Paul Watson, David L. Woodruff and Walter Rei

Session Th.2.c: Dynamic Routing

HORIZON

Chair: *Alan Erera, Georgia Institute of Technology*

11:00 – 11:30 Heuristics for Stochastic and Dynamic Maritime Pickup and Delivery Problems
Gregorio Tirado, Lars Magnus Hvattum, Kjetil Fagerholt and Jean-François Cordeau

11:30 – 12:00 Dynamic Tracking and Rerouting Strategies with Real-Time Traffic Information
Jesús-Arturo Orozco and Jaume Barcelo

12:00 – 12:30 Improved Tour Determination for the Dynamic Traveling Salesman Problem
Taesu Cheong, Alan Erera and Chelsea C. White III

Thursday, 14:00 – 15:30

Session Th.3.a: Time-Dependent Routing

DELOS A

Chair: *Richard Eglese, Lancaster University*

14:00 – 14:30 A Note on the Ichoua *et al.* (2003) Travel Time Model
Gianpaolo Ghiani and Emanuela Guerriero

14:30 – 15:00 A Tabu Search Approach for Daily Scheduling of Home Health Care Services using Multi-Modal Transport
Klaus-Dieter Rest and Patrick Hirsch

15:00 – 15:30 Variable Neighborhood Search for the Time-Dependent Prize-Collecting Arc Routing Problem
Sanne Wøhlk, Daniel Black and Richard Eglese

Session Th.3.b: Scheduling

DELOS B

Chair: *L. Douglas Smith, University of Missouri-St. Louis*

14:00 – 14:30 Refuel Decisions and Driver Time Management in Long-Haul Freight Transportation
Alexandra Hartmann, Teresa Melo, Thomas Bousonville and Herbert Kopfer

14:30 – 15:00 The Influence of Accurate Travel Times on a Home Health Care Scheduling Problem
Matthias Prandtstetter, Andrea Rendl and Jakob Puchinger

15:00 – 15:30 Scheduling Transportation and Logistics Events in Staged Queues
L. Douglas Smith, Robert M. Nauss, Jan Fabian Ehmke, Florian Bahr and Dirk Christian Mattfeld

Session Th.3.c: Inventory Routing II

HORIZON

Chair: *Maria Grazia Speranza, University of Brescia*

14:00 – 14:30 Hybrid Heuristic for the Inventory Location-Routing Problem with Deterministic Demand
William J. Guerrero, Caroline Prodhon, Nubia Velasco and Ciro Alberto Amaya

14:30 – 15:00 Designing Nested Routes for Cyclic Inventory Routing Problems
Birger Raa

15:00 – 15:30 Exact Solution of an IRP with Multiple Vehicles
Claudia Archetti, Nicola Bianchessi, Stefan Irnich and Maria Grazia Speranza

Thursday, 16:00 – 18:00

Session Th.4.a: Production – Distribution

DELOS A

Chair: *Jean-François Cordeau, HEC Montréal and CIRRELT*

16:00 – 16:30 Multi-Period Vehicle Loading with Stochastic Release Dates
Yasemin Arda, Yves Crama, David Kronus, Thierry Pironet and Pascal Van Hentenryck

16:30 – 17:00 Divergent Supply Chain in an Oil Company - Decoupled and Integrated Planning
Mario Guajardo, Martin Kylinger and Mikael Rönnqvist

17:00 – 17:30 Optimization-Based Adaptive Large Neighborhood Search for the Production Routing Problem
Yossiri Adulyasak, Jean-François Cordeau and Raf Jans

17:30 – 18:00 –

Session Th.4.b: Freight Transportation Networks

DELOS B

Chair: *Bernard Gendron, Université de Montréal and CIRRELT*

16:00 – 16:30 Robust Empty Repositioning in Large-scale Freight Consolidation Networks
Antonio Carbajal, Martin Savelsbergh and Alan Erera

16:30 – 17:00 Transport Mode Selection for Hazardous Materials
Vedat Verter, Morteza Bagheri and Manish Verma

17:00 – 17:30 Hazmat Transportation by Game Theory
Lucio Bianco, Massimiliano Caramia, Stefano Giordani and Veronica Piccialli

17:30 – 18:00 A Lagrangian-Based Branch-and-Bound Algorithm for the Two-Level Uncapacitated Facility Location Problem
Paul-Virak Khuong, Bernard Gendron and Frédéric Semet

Session Th.4.c: Vehicle Routing IV

HORIZON

Chair: *Roberto Wolfler Calvo, Université Paris 13*

16:00 – 16:30 The Distance-Constrained Vehicle Purchaser Problem
Nicola Bianchessi, Maria Grazia Speranza and Renata Mansini

16:30 – 17:00 Incomplete Service and Split Deliveries in a Routing Problem with Profits
Claudia Archetti, Alain Hertz, Maria Grazia Speranza and Nicola Bianchessi

17:00 – 17:30 The Static Multi Vehicles Rebalancing Problem
Daniel Chemla, Frédéric Meunier and Roberto Wolfler Calvo

17:30 – 18:00 –

Friday, 09:00 – 10:30

Session Fr.1.a: Vehicle Routing V

DELOS A

Chair: *Christian Prins, Université de Technologie de Troyes*

09:00 – 09:30 Load Balancing for the Skill Vehicle Routing Problem
Silvia Schwarze and Stefan Voss

09:30 – 10:00 The Bi-Objective Multi-Vehicle Covering Tour Problem: Formulation and Lower Bound
Boadu Mensah Sarpong, Christian Artigues and Nicolas Jozefowicz

10:00 – 10:30 Towards a General Heuristic for Multi-Attribute Vehicle Routing Problems
Thibaut Vidal, Teodor Gabriel Crainic, Michel Gendreau and Christian Prins

Session Fr.1.b: Maritime Transportation I

DELOS B

Chair: *Harilaos Psaraftis, National Technical University of Athens*

09:00 – 09:30 *A Fleet Deployment Problem in Liner Shipping*
Henrik Andersson, Kjetil Fagerholt and Kirsti Hobbesland

09:30 – 10:00 Reducing Emissions in Offshore Supply Vessel Planning by Speed Optimization
Ellen Karoline Norlund and Irina Gribkovskaia

10:00 – 10:30 A Ship Pickup and Delivery Model with Multiple Commodities, Variable Speeds, Cargo Inventory Costs and Freight Rates
Harilaos N. Psaraftis

Session Fr.1.c: Network Design II

HORIZON

Chair: *Nicoletta Ricciardi, Sapienza University of Rome*

09:00 – 09:30 A CAT Metaheuristic for the Design of Activity-Based Supply Chain Networks Under Uncertainty
Marc-André Carle and Alain Martel

09:30 – 10:00 Incremental Network Design with Shortest Paths
Matthew Baxter, Tarek Elgindy, Andreas Ernst, Thomas Kalinowski and Martin Savelsbergh

10:00 – 10:30 Modelling Dry-Port-based Freight Distribution through Service Network Design
Teodor Gabriel Crainic, Paolo Dell'Olmo, Nicoletta Ricciardi and Antonino Sgalambro

Friday, 11:00 – 12:30

Session Fr.2.a: Maritime Transportation II

DELOS A

Chair: *Mikael Rönnqvist, Université Laval*

11:00 – 11:30 Dynamic Vessel Navigation
Irina S. Dolinskaya and Robert L. Smith

11:30 – 12:00 Large Scale Robust Optimization of Bulk Seaport Operations
Nitish Umang and Michel Bierlaire

12:00 – 12:30 Vessel Routing and Scheduling under Uncertainty in the Liquefied Natural Gas Business
Elin Espeland Halvorsen-Weare, Kjetil Fagerholt and Mikael Rönnqvist

Session Fr.2.b: Emergency Logistics

DELOS B

Chair: *Alain Martel, Université Laval and CIRRELT*

11:00 – 11:30 A Bilevel Partial Interdiction Problem With Capacitated Facilities and Demand Outsourcing
Sema Şengül Akca, Necati Aras and Deniz Aksent

11:30 – 12:00 Stochastic Optimization for Warehouse Location for Flood Disaster Relief Preparation in Brazil
Adriana Leiras, Irineu de Brito Junior and Hugo Yoshizaki

12:00 – 12:30 Designing Emergency Supply Networks for Responsive Disaster Support
Walid Klibi, Soumia Ichoua and Alain Martel

Session Fr.2.c: Dynamic Vehicle Routing

HORIZON

Chair: *Cristián Cortés, University of Chile*

11:00 – 11:30 On the Dynamic Technician Routing and Scheduling Problem
Victor Pillac, Christelle Guéret and Andrés L. Medaglia

11:30 – 12:00 Rollout Algorithms with Restocking for Dynamic Vehicle Routing with Stochastic Demand and Duration Limits
Justin C. Goodson, Barrett W. Thomas and Jeffrey W. Ohlmann

12:00 – 12:30 Dynamic Column Generation Approach for Space Covering and Time-Space Covering Traveling Technician Problem
Cristián E. Cortés, Michel Gendreau, José Rojas, Louis-Martin Rousseau and Andrés Weintraub

Friday, 14:30 – 16:00

Session Fr.3.a: Routing with Loading Constraints

DELOS A

Chair: *Manuel Iori, University of Modena and Reggio Emilia*

14:30 – 15:00 An Exact Algorithm for the Double Traveling Salesman Problem with Multiple Stacks

Alberto Ceselli and Roberto Wolfler Calvo

15:00 – 15:30 A Strategic Oscillation Heuristic for the Double Traveling Salesman Problem with Multiple Stacks

Sebastián Urrutia, Anolan Milanés and Arne Løkketangen

15:30 – 16:00 A Rich Vehicle Routing Problem with Three-Dimensional Loading Aspects

Emmanouil E. Zachariadis, Christos D. Tarantilis and Chris T. Kiranoudis

Session Fr.3.b: Routing II

DELOS B

Chair: *Sanne Wøhlk, Aarhus University*

14:30 – 15:00 Column Generation for the Multiple Vehicle Covering Tour Problem

Nicolas Jozefowicz

15:00 – 15:30 An Aggregate Multi-Step Model of the Urban Freight Delivery Tours

Agostino Nuzzolo and Antonio Comi

15:30 – 16:00 Lower Bound for the Node, Edge and Arc Routing Problem

Lukas Bach, Geir Hasle and Sanne Wøhlk

Session Fr.3.c: Network Design and Uncertainty

HORIZON

Chair: *Stein W. Wallace, Lancaster University*

14:30 – 15:00 The Impact of Uncertainty on Closed-Loop Supply Chains

Beste Kucukyazici Verter, Wenyi Chen and Vedat Verter

15:00 – 15:30 Demand Uncertainty in Network Design Problems

Teodor Gabriel Crainic, Walter Rei and Mike Hewitt

15:30 – 16:00 Multi-Commodity Stochastic Network Design: Dynamic Formulation without Conservation-of-Flow on the Design Variables

Stein W. Wallace and Xin Wang

Friday, 16:30 – 18:00

Session Fr.4.a: Location-Routing

DELOS A

Chair: *Louis-Martin Rousseau, École Polytechnique de Montréal and CIRRELT*

16:30 – 17:00 A Comparison of Three Metaheuristic Algorithms for the Capacitated Location-Routing Problem

John W. Escobar, Rodrigo Linfati, Paolo Toth and Maria Gulnara Baldoquin

17:00 – 17:30 Solving Network Design and Routing Problems for Urban Freight Distribution

Paolo Gianessi, Laurent Alfandari, Lucas Létocart and Roberto Wolfler Calvo

17:30 – 18:00 Location-Routing Problems with Pickup and Delivery and Time Windows constraints

Thomas Capelle, Cristián E. Cortés, Michel Gendreau, Louis-Martin Rousseau and Pablo A. Rey

Session Fr.4.b: Supply Chain Logistics

DELOS B

Chair: *Barrett Thomas, University of Iowa*

16:30 – 17:00 Solving the Raw Materials Reception Problem using Revenue Management Principles: An Application to a Portuguese Pulp Mill

Mikael Rönnqvist, Sophie D'Amours, Andrés Weintraub, João Gonçalves, Jose G. Borges and Alexandra F. Marques

17:00 – 17:30 A Stockyard Planning Problem

Natashia Boland, Damon Gulczynski and Martin Savelsbergh

17:30 – 18:00 Coordinated Logistics for Sugarcane Harvests in Brazil

Barrett W. Thomas, Kamal Lamsal and Philip C. Jones

ODYSSEUS 2012 Workshop Schedule

Social Program

Welcome Reception

SUNDAY

Starts at: 20:00

Place: Lobby Veranda

Features: Drinks and light snacks

Excursion to Delos

WEDNESDAY

Timeline:

07:45 Departure from *Royal Myconian Resort*

08:20 Arrival at Chora of Mykonos, rendezvous with our guides and walk towards the old harbor

08:40 Embarkation

09:00 Ferry departure

09:25 Arrival at Delos and disembarkation

09:30 Start of the guided tour

13:20 End of visit and embarkation

13:30 Ferry departure

14:00 Arrival at Chora of Mykonos, disembarkation and walk to the buses

14:15 Departure from Chora of Mykonos

14:45 Arrival at *Royal Myconian Resort*

Workshop Dinner and Party

THURSDAY

Starts at: 20:30

Place: Horizon room and terrace

Features: Drink reception
Full course dinner
ODYSSEUS 2015 candidacies and vote
Music and dancing

Farewell Drinks

FRIDAY

Starts at: 20:00

Place: Sunset Veranda

Features: Drinks and light snacks

ODYSSEUS



2012



Farewell!