

# Clinical data based optimal STI strategies for HIV: a reinforcement learning approach

Damien Ernst

Department of Electrical Engineering and Computer Science  
University of Liège

Montefiore - March 9, 2006

Presentation based on the paper: “Clinical data based optimal STI strategies for HIV: a reinforcement learning approach”. D. Ernst, G.B. Stan, J. Gonçalves and L. Wehenkel

- ▶ *Human Immunodeficiency Virus (HIV) is a retrovirus at the source of the Acquired Immune Deficiency Syndrome (AIDS)*
- ▶ HIV particles target cells of the immune system (mostly CD4<sup>+</sup> lymphocytes and macrophages)
- ▶ Inclusion of HIV particles in immune cells lead to massive production of new viral particles, death of the infected cells and, ultimately, devastation of the immune system

# Current anti-HIV drugs

Two main categories:

1. Reverse Transcriptase Inhibitors (RTI)
2. Protease Inhibitor (PI)



Figure: Taken from <http://www.cellsalive.com/hiv0.htm>

# Treatments for infected patients

- ▶ Highly Active Anti-Retroviral Therapy (HAART): combination of two or more drugs. Usually one or more RTIs in combinations with a PI.
- ▶ Two main concerns about the long-term use of anti retroviral drugs: undesirable side effects (leading to poor compliance) and mutation of the virus (need to change drugs or even inability to find appropriate pharmaceutical treatments).
- ▶ Need for efficient drug scheduling strategies.
- ▶ Idealistically, a drug-scheduling strategy should bring the system to a state where the immune system has control over the virus (with low amount of drugs and low systemic effects).

# Structured Treatment Interruption (STI)

- ▶ STI: to cycle the patient on and off drug therapy
- ▶ STI strategies often well received by patients since they offer them period of relief from treatment
- ▶ In some remarkable cases, STI strategies have enabled the patients to maintain immune control over the virus in the absence of treatment

*Goal of this research: to compute optimal STI strategies*

# STI: A glimpse at today's practice

If CD4+ cell count falls below a certain threshold, put the patient on drugs. Otherwise put him off. This practice has met **some problems**:

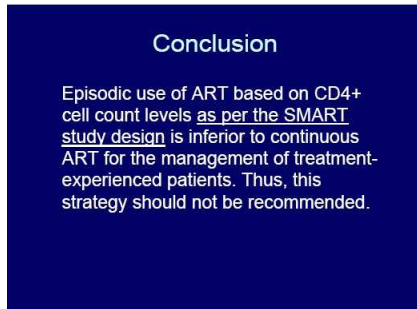


Figure: Taken from  
<http://www.cpcra.org/docs/pubs/2006/croi2006-smart.pdf>

## More advanced techniques (not clinically tested)

- ▶ Some authors have proposed to design STI treatments by exploiting mathematical models of the HIV infection.
- ▶ Models are under the form of a set of Ordinary Differential Equations (ODEs)
- ▶ Deduction of STI strategies is done by using methods from the control theory.

But modelling of the HIV dynamics is a difficult task. Indeed, one has

- ▶ to select the right parametric system of ODEs
- ▶ to fit the parameters to reflect quantitatively biological observations

# An interesting alternative

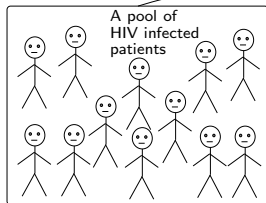
- ▶ Infer directly from clinical data good STI strategies, without modelling the HIV infection dynamics.
- ▶ Clinical data: time evolution of patient's state ( $CD4^+$  T cell count, systemic costs of the drugs, etc) recorded at discrete-time instant and sequence of drugs administered.
- ▶ Clinical data can be seen as **trajectories** of the immune system responding to treatment.



# Inferring policies from trajectories

- ▶ Problem of inferring from trajectories appropriate control policy has been studied in control theory and computer science.
- ▶ One way to approach it: **state an optimality criterion** and search for strategies optimizing this criterion.
- ▶ Classical approach: infer a model and derive from it and the optimality criterion an optimal strategy.
- ▶ Reinforcement learning approach: compute optimal strategies directly from the trajectory, without identifying a model.

The patients follow some (possibly suboptimal) STI protocols and are monitored at regular intervals



The monitoring of each patient generates a trajectory for the optimal STI problem which typically contains the following information:

*state of the patient at time  $t_0$*   
*drugs taken by the patient between  $t_0$  and  $t_1 = t_0 + n$  days*  
*state of the patient at time  $t_1$*   
*drugs taken by the patient between  $t_1$  and  $t_2 = t_1 + n$  days*  
*state of the patient at time  $t_2$*   
*drugs taken by the patient between  $t_2$  and  $t_3 = t_2 + n$  days*  
⋮

Processing of the trajectories gives some (near) optimal STI strategies, often under the form of a mapping between the state of the patient at a given time and the drugs he has to take till the next time his state is monitored.

The trajectories are processed by using *reinforcement learning* techniques

**Figure:** Determination of optimal STI strategies from clinical data by using reinforcement learning algorithms: the overall principle.

# Learning from a sample of trajectories: the RL approach

## Problem formulation

Discrete-time dynamics:

$$x_{t+1} = f(x_t, u_t) \quad t = 0, 1, \dots$$

where  $x_t \in X$  and  $u_t \in U$ .

Cost function:  $c(x, u) : X \times U \rightarrow \mathbf{R}$ .  $c(x, u)$  bounded by  $B_c$ .

Discounted infinite horizon cost associated to stationary policy

$$\mu : X \rightarrow U: J^\mu(x) = \lim_{N \rightarrow \infty} \sum_{t=0}^{N-1} \gamma^t c(x_t, \mu(x_t))$$

Optimal stationary policy  $\mu^*$  : Policy that minimizes  $J^\mu$  for all  $x$ .

Objective: Find an optimal policy  $\mu^*$ .

**We do not know:** The discrete-time dynamics.

**We know instead:** A set of trajectories  $(x_0, u_0, x_1, \dots, u_{T-1}, x_T)$ .

## Some dynamic programming results

Sequence of functions  $Q_N: X \times U \rightarrow \mathbb{R}$

$$Q_N(x, u) = c(x, u) + \gamma \min_{u' \in U} Q_{N-1}(f(x, u), u'), \quad \forall N > 1$$

with  $Q_1(x, u) \equiv c(x, u)$ , converges to the **Q-function**, unique solution of the Bellman equation:

$$Q(x, u) = c(x, u) + \gamma \min_{u' \in U} Q(f(x, u), u').$$

Necessary and sufficient optimality condition:

$$\mu^*(x) \in \arg \min_{u \in U} Q(x, u)$$

Stationary policy  $\mu_N^*$ :

$$\mu_N^*(x) \in \arg \min_{u \in U} Q_N(x, u).$$

Bound on the suboptimality of  $\mu_N^*$ :

$$J^{\mu_N^*} - J^{\mu^*} \leq \frac{2\gamma^N B_c}{(1-\gamma)^2}.$$

## Fitted Q iteration

Trajectories  $(x_0, u_0, x_1, \dots, u_{T-1}, x_T)$  transformed into a set of one-step system transitions  $\mathcal{F} = \{(x_t^l, u_t^l, x_{t+1}^l)\}_{l=1}^{\#\mathcal{F}}$ .

Fitted Q iteration computes from  $\mathcal{F}$  the functions  $\hat{Q}_1, \hat{Q}_2, \dots, \hat{Q}_N$ , approximations of  $Q_1, Q_2, \dots, Q_N$ .

Computation done iteratively by solving a sequence of standard supervised learning (SL) problems. Training sample for the  $k^{\text{th}}$  ( $k \geq 2$ ) problem is

$$\left\{ \left( (x_t^l, u_t^l), c(x_t^l, u_t^l) + \gamma \min_{u \in U} \hat{Q}_{k-1}(x_{t+1}^l, u) \right) \right\}_{l=1}^{\#\mathcal{F}} \text{ with}$$

$\hat{Q}_1(x, u) \equiv c(x, u)$ . From the  $k^{\text{th}}$  training sample, the supervised learning algorithm outputs  $\hat{Q}_k$ .

$\hat{\mu}_N^*(x) \in \arg \min_{u \in U} \hat{Q}_N(x, u)$  is taken as approximation of  $\mu^*(x)$ .

In our simulations, SL method used is an ensemble of regression trees method named **Extra-Trees**.

- ▶ We present results we have obtained by using the RL-based approach on artificially generated data.
- ▶ The example is directly inspired from B.M. Adams, H.T. Banks, Hee-Dae Kwon and H.T. Tran. (2004). “Dynamic multidrug therapies for HIV: Optimal and STI Control Approaches”. *Mathematical Biosciences and Engineering*, 1, 223-241.

# Illustration: Kinds of STI strategies targeted

Bi-therapy treatments combining a fixed RTI and a fixed PI.  
Revise drug administration every five days based on clinical measurements.

Four possible on-off combinations for the next five days: RTI and PI on, only RTI on, only STI on, RTI and PI off

We seek STI strategies that minimize  $J^\mu$ .

Instantaneous cost at time  $t$ :

$$c(x_t, u_t) = 0.1V_t + 20000\epsilon_{1t}^2 + 2000\epsilon_{2t}^2 - 1000E_t$$

$\epsilon_{1t} = 0.7$  (resp.  $\epsilon_{1t} = 0$ ) if the RTI is cycled on (resp. off) at  $t$

$\epsilon_{2t} = 0.3$  (resp.  $\epsilon_{2t} = 0$ ) if the PI is cycled on (resp. off) at time  $t$

$V$ : number of free HI viruses

$E$ : number of cytotoxic  $T$ -lymphocytes

Decay factor  $\gamma$ : chosen equal to 0.98.

## Illustration: A mathematical model as substitute for real-life patients

$$\dot{T}_1 = \lambda_1 - d_1 T_1 - (1 - \epsilon_1) k_1 V T_1$$

$$\dot{T}_2 = \lambda_2 - d_2 T_2 - (1 - f\epsilon_1) k_2 V T_2$$

$$\dot{T}_1^* = (1 - \epsilon_1) k_1 V T_1 - \delta T_1^* - m_1 E T_1^*$$

$$\dot{T}_2^* = (1 - f\epsilon_1) k_2 V T_2 - \delta T_2^* - m_2 E T_2^*$$

$$\dot{V} = (1 - \epsilon_2) N_T \delta (T_1^* + T_2^*) - cV - [(1 - \epsilon_1) \rho_1 k_1 T_1 + (1 - f\epsilon_1) \rho_2 k_2 T_2] V$$

$$\dot{E} = \lambda_E + \frac{b_E (T_1^* + T_2^*)}{(T_1^* + T_2^*) + K_b} E - \frac{d_E (T_1^* + T_2^*)}{(T_1^* + T_2^*) + K_d} E - \delta_E E$$

$T_1$  ( $T_1^*$ ) = number of non-infected (infected) CD4<sup>+</sup> lymphocytes

$T_2$  ( $T_2^*$ ) = non-infected (infected) macrophages

$V$  = number of free HI viruses

$E$  = number of cytotoxic  $T$ -lymphocytes.

$\epsilon_1$  and  $\epsilon_2$  = control actions corresponding to RTI and the PI.

Period during which the RTI (resp. the PI) is administrated to the patient:  $\epsilon_1$  (resp.  $\epsilon_2$ ) is set equal to 0.7 (resp. 0.3).

RTI (resp. the PI) not administrated:  $\epsilon_1 = 0$  (resp.  $\epsilon_2 = 0$ ).



# Illustration: Some insight into this model

In absence of treatment, three physical equilibrium points:

1. uninfected state:

$$(T_1, T_2, T_1^*, T_2^*, V, E) = (10^6, 3198, 0, 0, 0, 10)$$

2. “healthy” locally stable equilibrium

$$(T_1, T_2, T_1^*, T_2^*, V, E) = (967839, 621, 76, 6, 415, 353108)$$

(small viral load, a high CD4<sup>+</sup> T-lymphocytes count, high HIV-specific cytotoxic T-cells count)

3. “non-healthy” locally stable equilibrium point

$$(T_1, T_2, T_1^*, T_2^*, V, E) = (163573, 5, 11945, 46, 63919, 24)$$

(T-cells depleted, viral load very high).

# Illustration: Protocol for artificially generating the clinical data

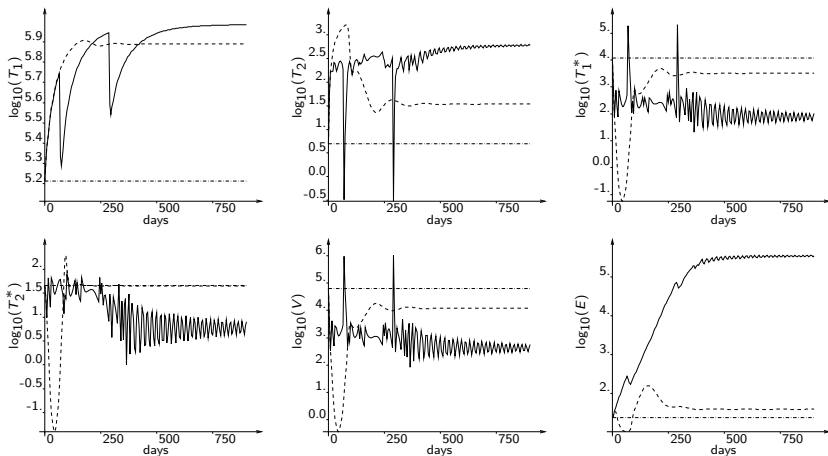
**Monitoring of patients:** every five days during 1000 days.

**Medication:** can be revised every five days based on the information generated by the monitoring.

**Iterative generation** of the clinical data (ten iterations):

- ▶ **First iteration.** Thirty patients in “non-healthy” steady-state. Physiological data ( $T_1, T_2, T_1^*, T_2^*, V, E$ ) recorded and a new type of medication randomly selected in  $U$  every five days. Monitoring of each patient generates a trajectory  $(x_0, u_0, x_1, \dots, x_{199}, u_{199}, x_{200})$ .
- ▶ **Second iteration.** Only difference with first iteration: medication determined by the following STI strategy: in 85% of the cases, use strategy  $\hat{\mu}_{400}^*$  computed by fitted  $Q$  iteration on previously generated trajectories; in the remaining 15% medication randomly selected in  $U$ .
- ▶ **Third-tenth iteration:** idem as second iteration.

# Illustration: Simulation results



**Figure:** Solid curve (—) corresponds = patient which follows STI strategies; dashed curves (---) = no interruption in the treatment; dotted curves (— ·) = no treatment

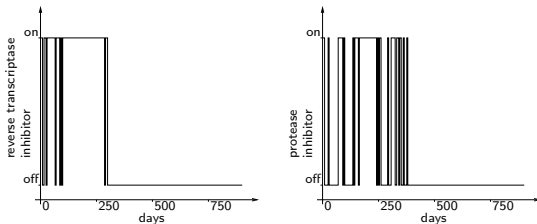


Figure: STI treatment for a patient treated from early stage of infection. Clinical data generated by 300 patients.

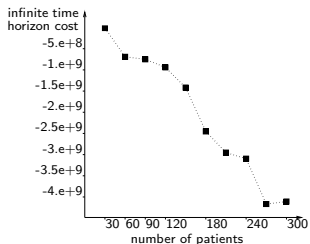


Figure: Influence of the number of patients on the infinite time horizon cost corresponding to the computed STI strategies.

We expect to face **four main difficulties**:

- ▶ The HIV/immune system dynamics may be different from one patient to the other.
- ▶ Difficulty to state properly the optimal control problem
- ▶ Partial observability
- ▶ Corrupted measurements

# Conclusions

- ▶ Reinforcement learning algorithms seem to be promising tools to extract from clinical data, good STI strategies.
- ▶ Lot of work is however still needed !!!
- ▶ But 40 millions of people are living with HIV/AIDS. Isn't it a good reason to keep working hard ?

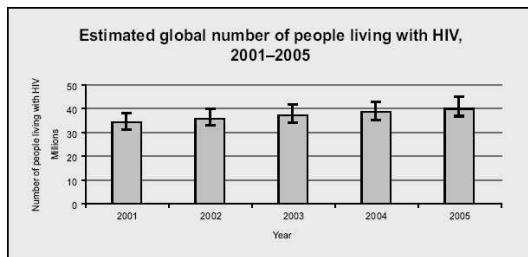


Figure: Taken from UNAIDS. AIDS epidemic update: December 2005. “UNAIDS/05.19E”