

Experimental modal analysis of a beam travelled by a moving mass using Hilbert Vibration Decomposition

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The research is focused on the identification of time-varying systems

$$\mathbf{M}(t) \ddot{\mathbf{x}}(t) + \mathbf{C}(t) \dot{\mathbf{x}}(t) + \mathbf{K}(t) \mathbf{x}(t) = \mathbf{f}(t)$$

Dynamics of such systems is characterized by :

- ▶ Non-stationary time series
- ▶ Instantaneous modal properties
 - ▶ Frequencies : $\omega_r(t)$
 - ▶ Damping ratio's : $\xi_r(t)$
 - ▶ Modal deformations : $\mathbf{q}_r(t)$

The Hilbert Transform

The Hilbert transform \mathcal{H} of a signal $x(t)$ is the convolution product of this signal with the impulse response $h(t) = \frac{1}{\pi t}$

$$\begin{aligned}\mathcal{H}(x(t)) &= (h(t) * x(t)) \\ &= \text{p.v.} \int_{-\infty}^{+\infty} x(\tau) h(t - \tau) d\tau \\ &= \frac{1}{\pi} \text{p.v.} \int_{-\infty}^{+\infty} \frac{x(\tau)}{t - \tau} d\tau\end{aligned}$$

It is a particular transform that **remains in the time domain**

It corresponds to a **phase shift of $-\frac{\pi}{2}$** of the signal

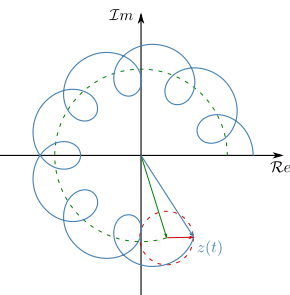
The Hilbert transform and the *analytic signal*

The analytic signal z is built as

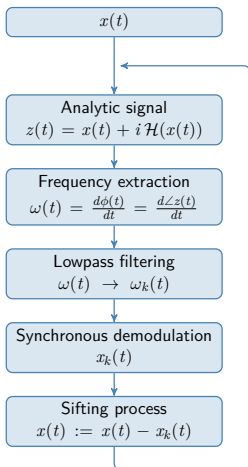
$$\begin{aligned}z(t) &= x(t) + i\mathcal{H}(x(t)) \\ &= A(t) e^{i\phi(t)}\end{aligned}$$

The instantaneous properties of the signal can then be obtained

$$\begin{cases} A(t) = |z(t)| \\ \phi(t) = \angle z(t) \\ \omega(t) = \frac{d\phi}{dt} \end{cases}$$



The *Hilbert Vibration Decomposition* (HVD) method



It is an iterative process

The sifting of the signal extracts monocomponents from higher to lower instantaneous amplitude

It is applicable to single channel measurement

Crossing monocomponents may be a problem

The experimental set-up

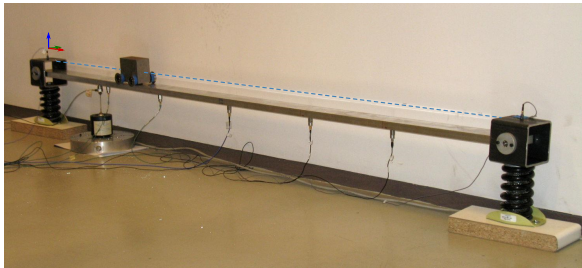
2.1 meter aluminum beam

Steel block (≈ 3.5 kg, 38.6%)

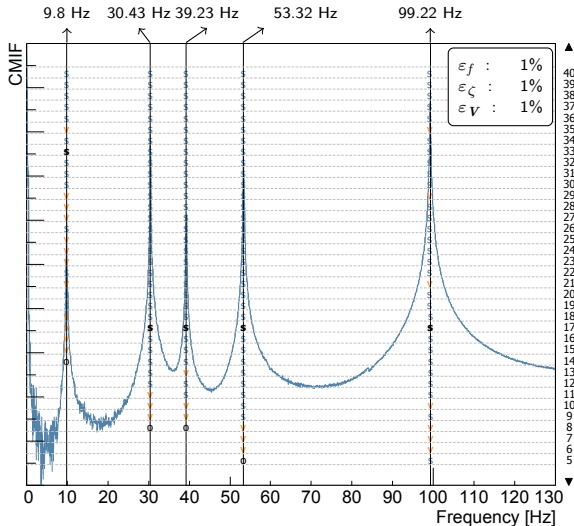
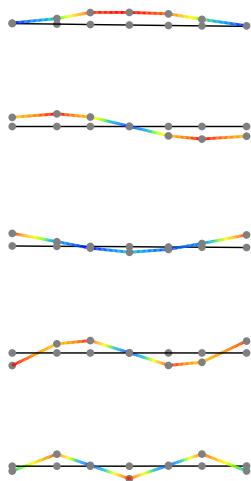
1 shaker (random force)

7 accelerometers

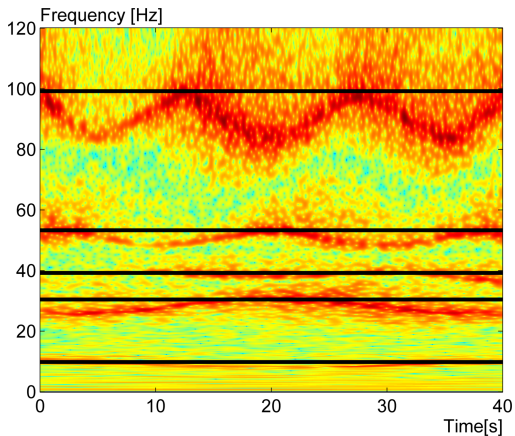
LMS SCADAS & LMS Test.Lab system



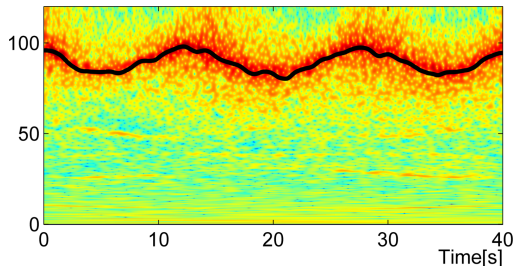
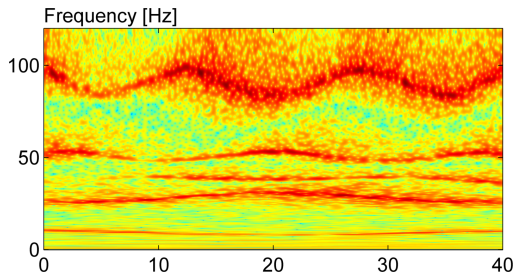
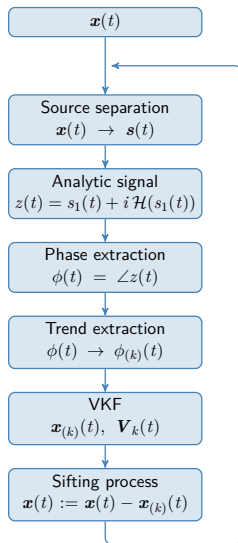
Time invariant modal identification of the beam subsystem



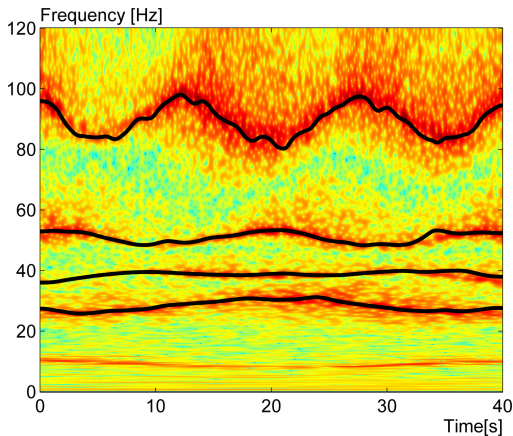
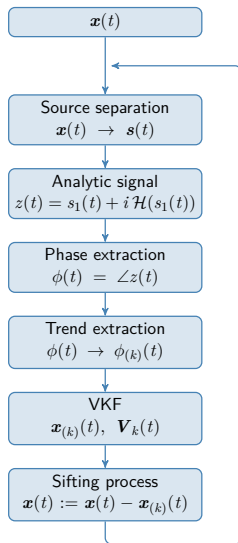
Time-varying dynamics of the system



The sifting process and the benefit of the source separation



Other modes are extracted after few iterations



Monocomponents and complex amplitudes are extracted with a Vold-Kalman filter

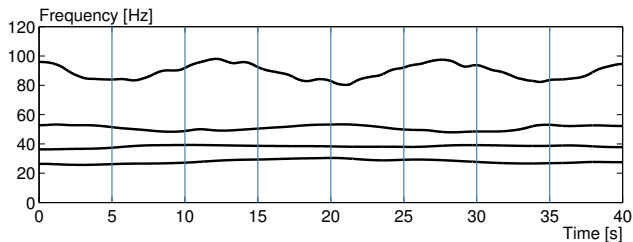
The Vold-Kalman model and the modal expansion are very similar.

The extracted complex amplitudes are then considered as **unscaled mode shapes**

$$\begin{array}{l} \text{Vold-Kalman filter: } \mathbf{x}(t) = \sum_k \mathbf{a}_k(t) e^{i\phi_k(t)} \\ \text{Modal expansion: } \mathbf{x}(t) = \sum_k \mathbf{V}_k(t) \eta_k(t) \end{array}$$

\updownarrow \updownarrow

The moving mass affects both frequencies and mode shapes



$t = 5$ s



$t = 10$ s



$t = 15$ s



$t = 20$ s



$t = 25$ s



$t = 30$ s



$t = 35$ s



Thank you for your
attention