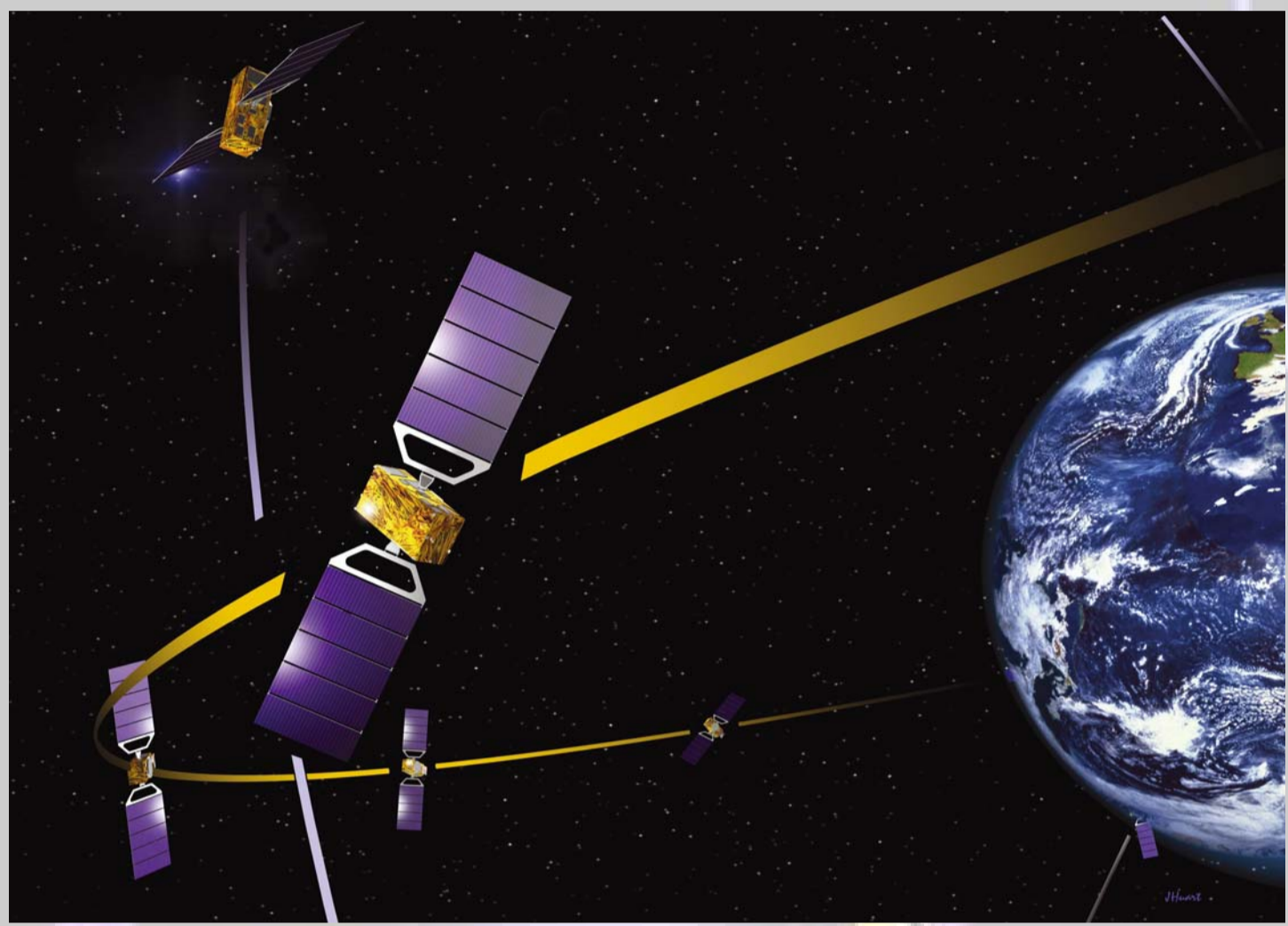


GALILEO

- **European GNSS** (Global Navigation Satellite System) under development
- Several advantages e.g.
 - **interoperability** with existing systems mainly GPS (Global Positioning System) = combination of signals from various constellations possible in order to improve performances of measurements
 - **guaranteed precision** as it will broadcast related information contrary to the preceding systems



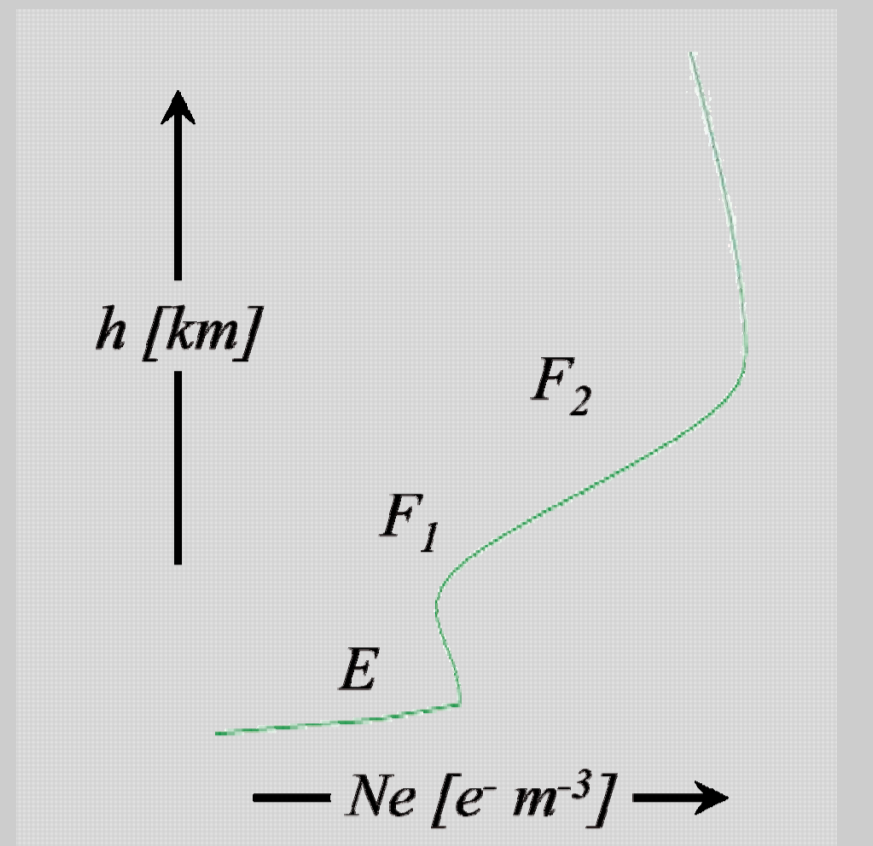
GALILEO constellation (credits: ESA)

Basic obedience	Civilian
Number of services	5
Number of carrier frequencies	3
Horizontal accuracy for civilian users [m]	15
Number of satellites (operational/in orbit)	27/3
Average altitude [km]	23222
Number of orbital planes	3
Inclination [°]	56
Period [hours]	14

- **Development:**
 - space segment of 30 satellites to be launched, beginning with experimental ones (the first, GIOVE-A, in December 2005 and the second, GIOVE-B, in December 2007)
 - ground segment including 40 sensor stations
 - completion foreseen for **2013**

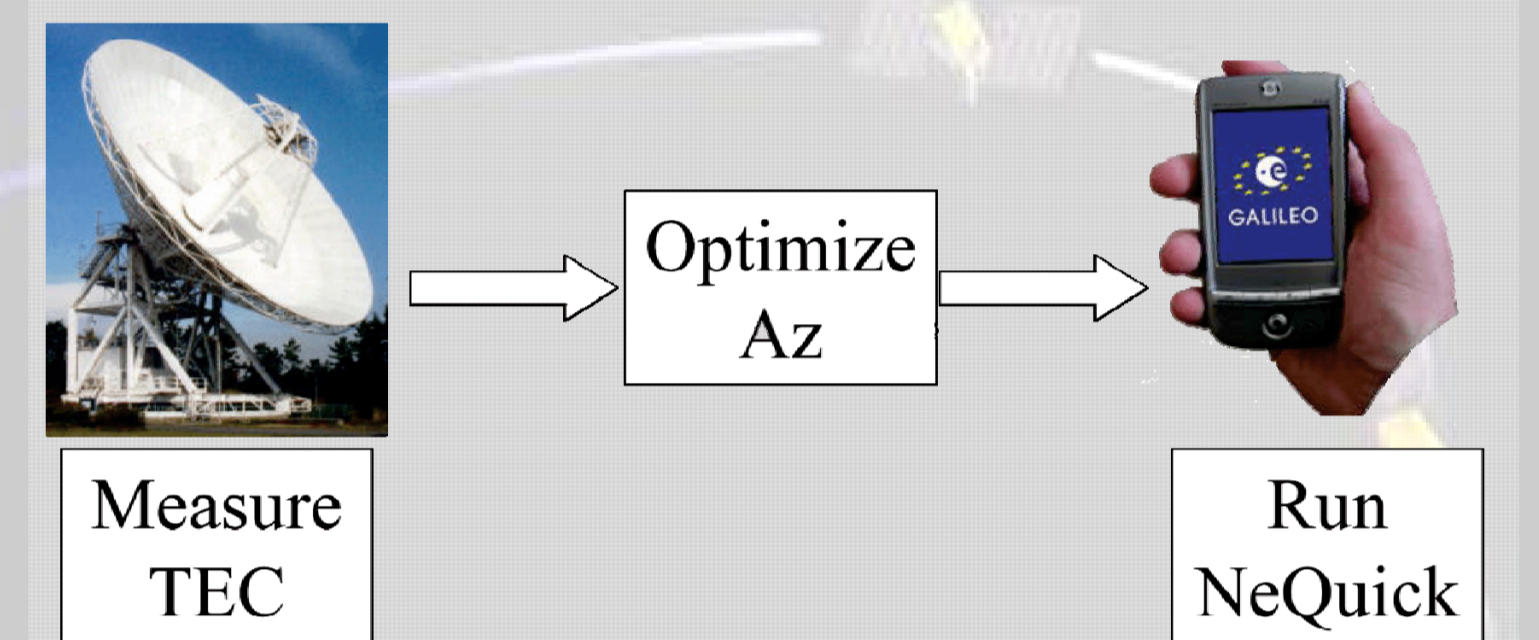
NeQuick

- Empirical model of the electron density N_e :
 - “**profiler**” = several mathematical functions fitted on anchor points corresponding to the maxima of the layers of the ionosphere
 - peaks and profile characteristics calculated on the basis of **monthly median measurements**
 - adaptation to given ionospheric conditions by means of input parameters e.g. the monthly solar radio flux at 10.7 cm



Electron density profile

- GALILEO single frequency ionospheric correction algorithm:
 - “**refreshment**” at a daily rate by replacing the input solar flux by a daily parameter called effective ionization level (A_z)
 - based on TEC measurements performed by the tracking stations of the GALILEO network
 - A_z determined on a daily basis and on a worldwide scale (optimization)
 - A_z broadcast to the receiver through the navigation message
 - objective = **30% RMS residual error** or 20 TECu whichever is larger

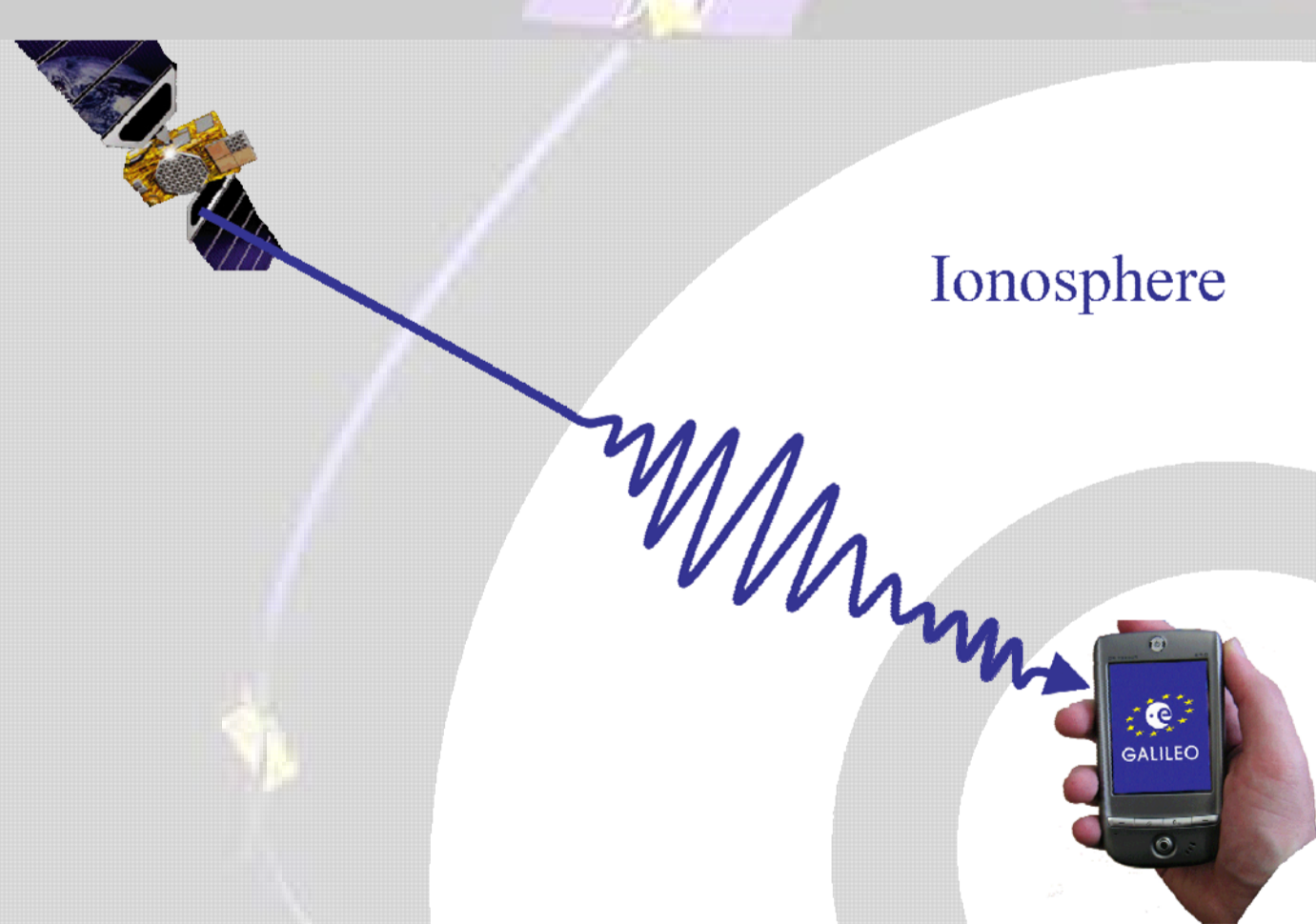


GALILEO single frequency algorithm

- **Research issues**
 - about the model itself e.g. not realistic too simple description of the **higher part of the ionosphere** (“topside”)
 - about GALILEO algorithm e.g. **formulation of A_z** chosen to compensate for the observed residual errors

Influence of the Ionosphere

- Different effects **affecting precision** one of which induced by the ionosphere, the electrically charged part of the atmosphere → positioning errors exceeding 100 m in extreme cases



$$I = 40.3 \cdot \frac{TEC}{f^2}$$

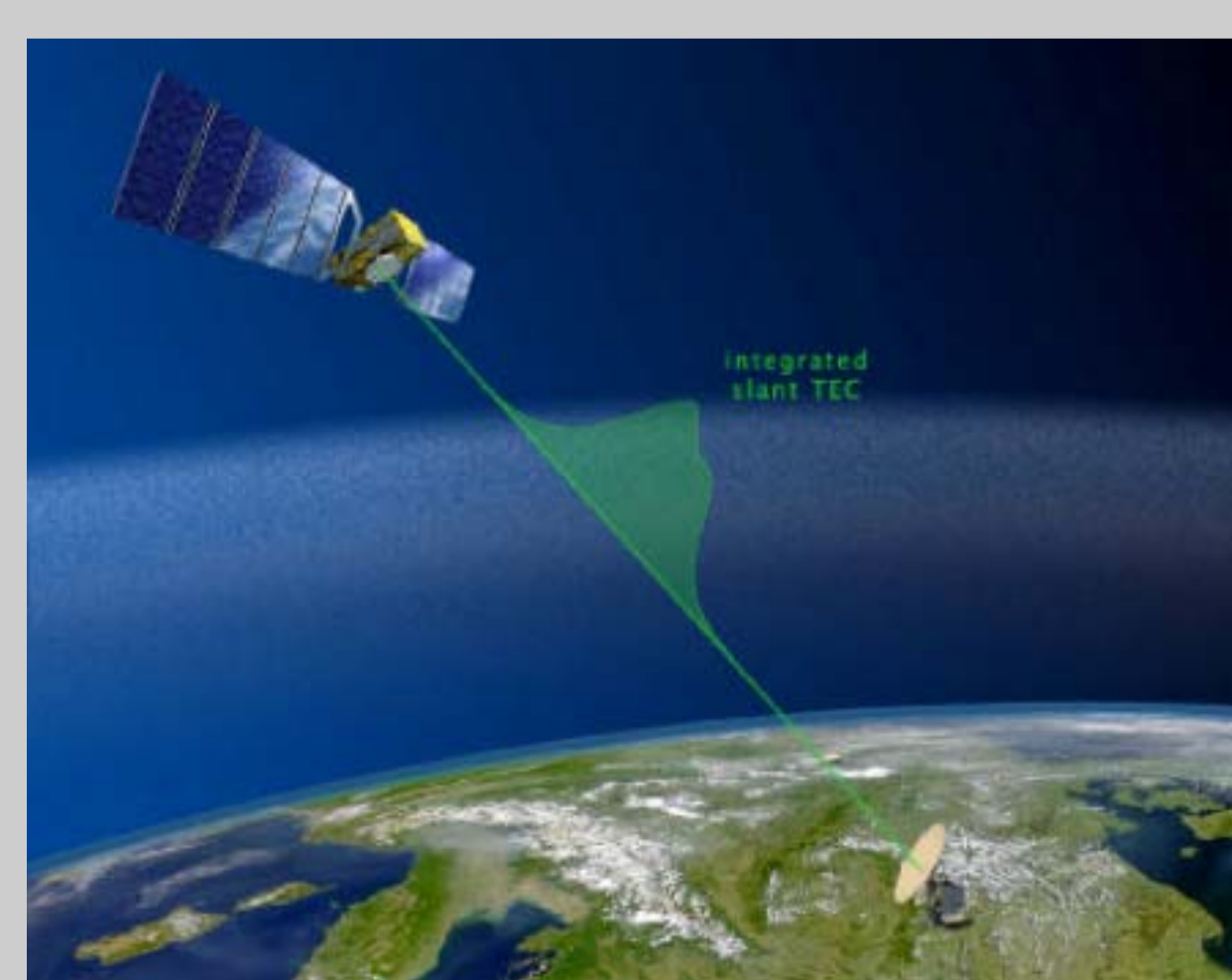
I [m] = ionospheric range error
 TEC [TECu] = total electron content
 f [MHz] = signal frequency

1 TECu on L_1 [1575.46 MHz] → $I = 16$ cm

Signals propagating through the ionosphere

- Ionospheric effect I depending at first approximation
 - on the frequency f of the incident signal (dispersive property)
 - on the total content in free electrons of the ionosphere (“**total electron content**”, TEC) = integral of the electron density N_e on the path between the satellite and the receiver

- **TEC modelling**
 - crucial in particular for **single frequency receivers**, the most common ones constituting the mass market
 - also for multiple frequency devices (fallback mode in single frequency for critical applications e.g. civil aviation)
 - by means of a 3D method using the NeQuick model for GALILEO



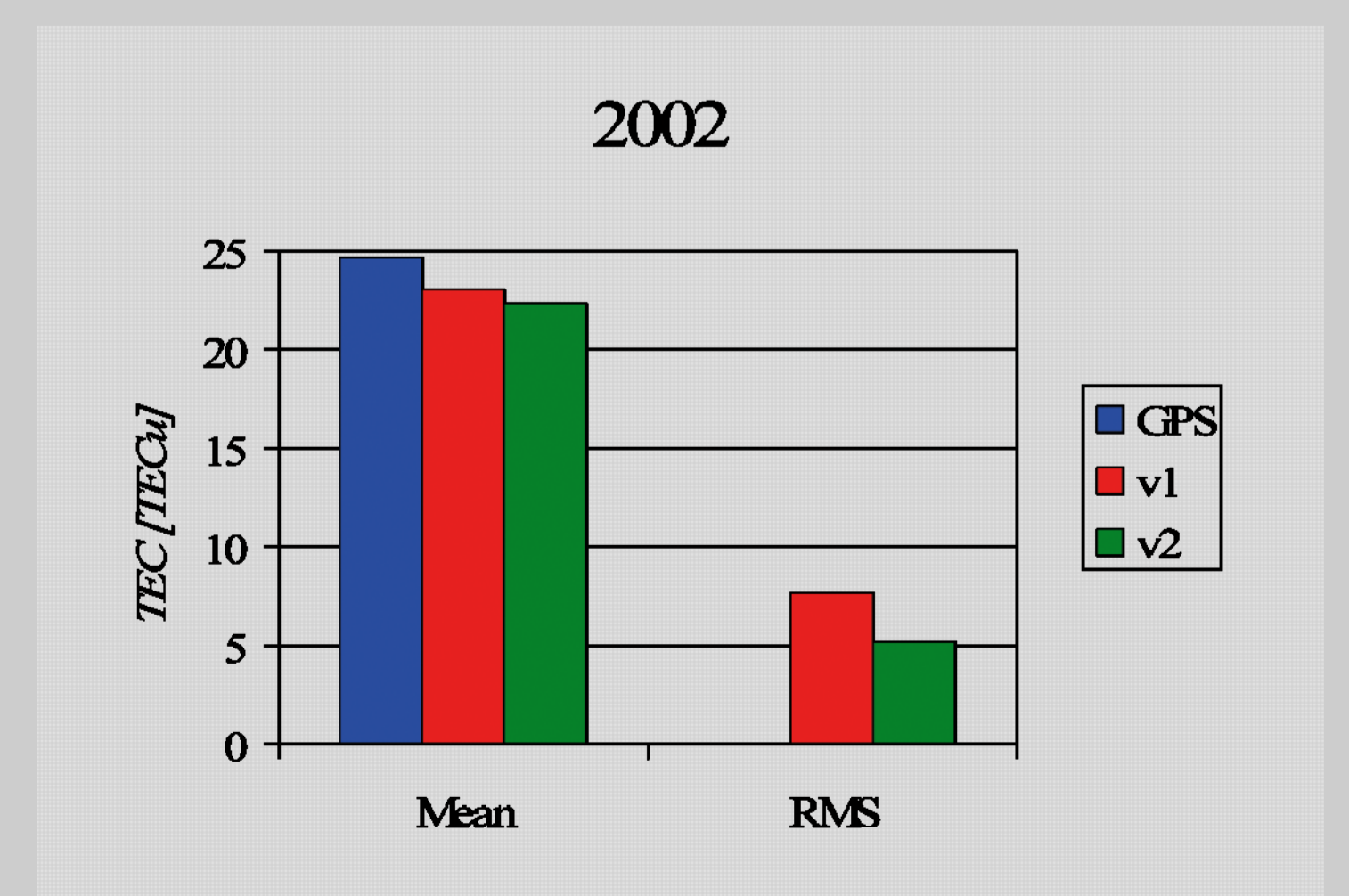
3D method scheme (credits: ICTP)



PhD Thesis

- **Objectives**
 1. Analysis of NeQuick **weaknesses** and results: development of a software and gathering of reference measurements among which those of Belgian GPS stations and the ionosonde of the RMI
 2. **Intrinsic** improvement: analysis of more realistic TEC representation techniques and investigation of the topside formulation
 3. Study of NeQuick best use for satellite navigation: focus on techniques of data **ingestion** (adaptation of modelled values to measured ones by minimizing their difference by means of A_z)
 4. Study of **implementation** e.g. evaluation of cost in data-processing resources

- **First results:**
 - test of NeQuick profile formulation at **mid-latitudes**
 - model constrained by means of ionosonde data and compared to GPS TEC data
 - evolution between official baseline version (v1) and latest release (v2) including an improved topside
 - comparison for Dourbes location (50.1N, 4.6E) and two solar activity levels (2002 for high and 2006 for low)
 - **improvement from v2**



TEC comparison for Dourbes in 2002