



Photogrammetry for forest inventory.

Marc Pierrot Deseilligny.
IGN/ENSG, France.

Jonathan Lisein.
Ulg Gembloux Agro-Bio Tech, Belgium.



1- Photogrammetry

2- Application to forestry

3- Tools and proposed actions

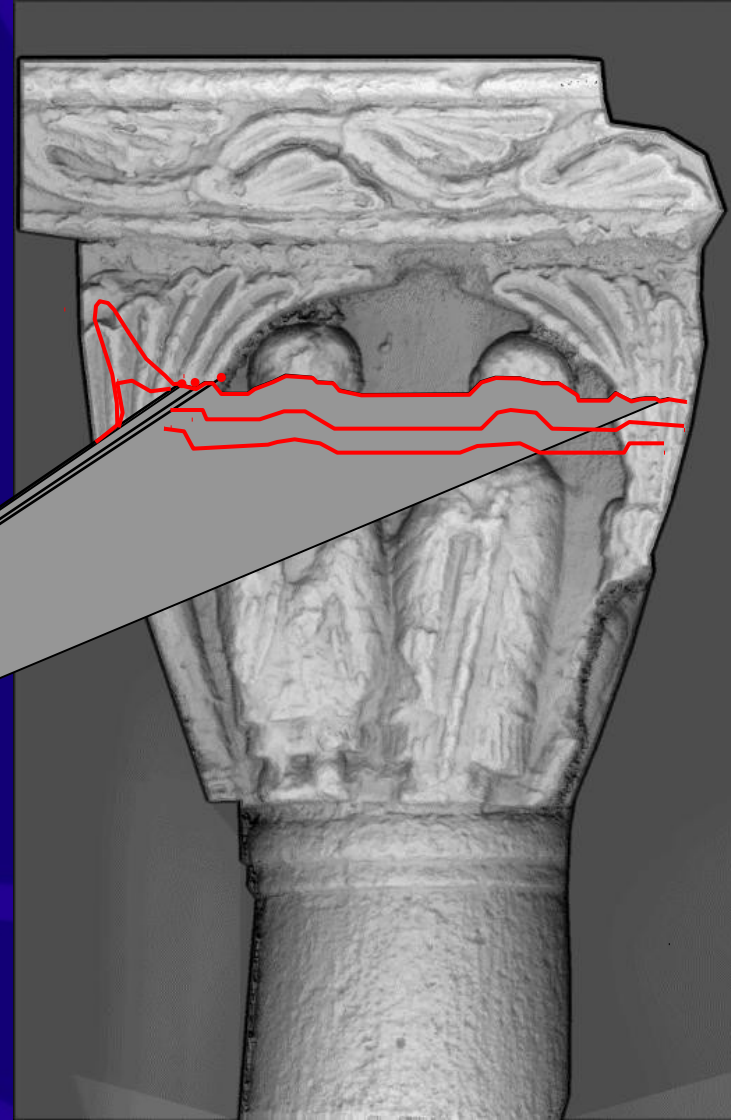
1- Photogrammetry

Photogrammetry vs lidar



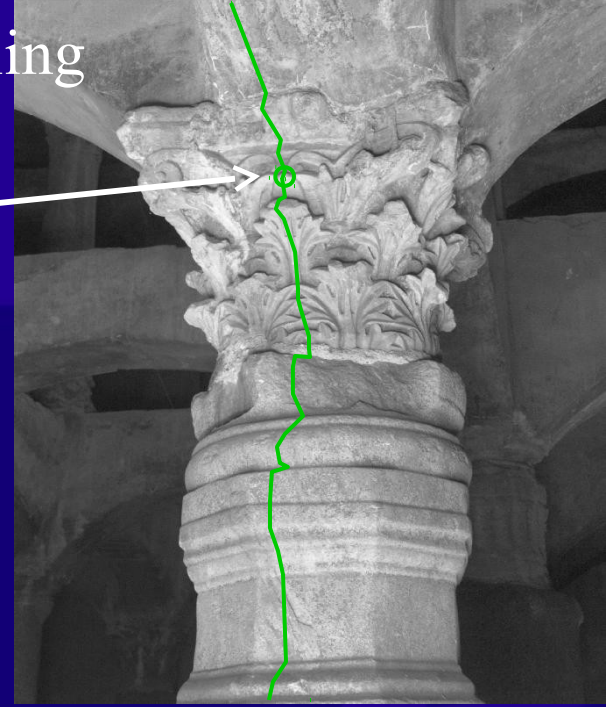
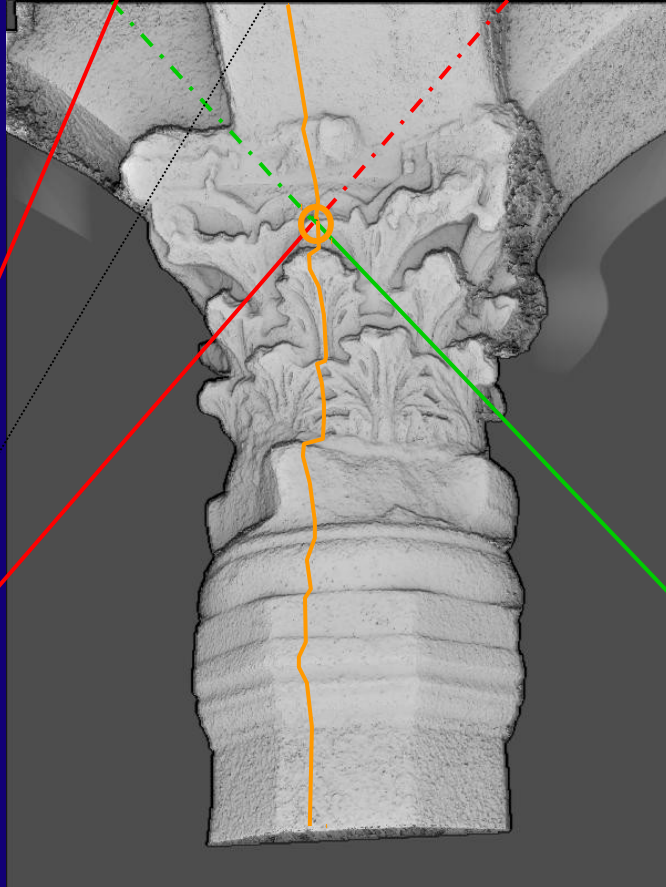
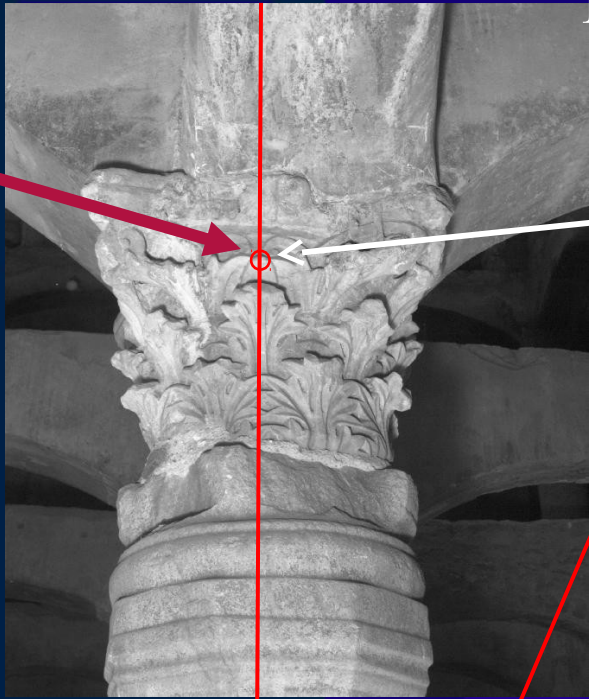
INSTITUT
GEOGRAPHIQUE
NATIONAL

LIDAR 3D modeling

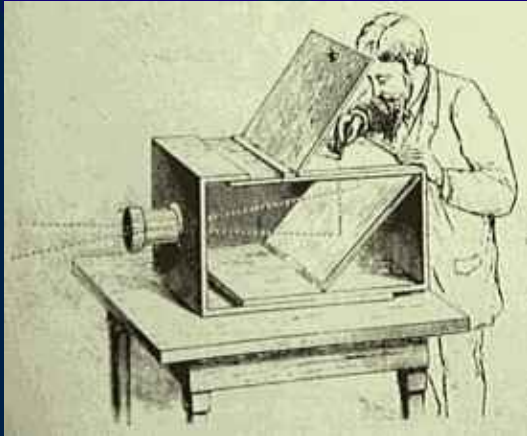


18/12/08
IGN /DT

Photogrammetry 3D modeling



Until recently, when one heard « photogrammetry »
what does come to mind ?



An old technique



**Requiring specialized
material and people**

But not fully automatic, precise and complete as lidar

**At the beginning of year 2000, most people thought
that photogrammetry was :**

**A respectable, old lady of the scientific
word**



**That should profit
of her well deserved
retirement**

**An make room for
« modern young people »
(LIDAR, RADAR...)**

But since, two major issues have change the story :

Digital photography :



Progress in image processing :



Result of sift algorithm

Digital photography : taking photo is free => take as many photo as you need :

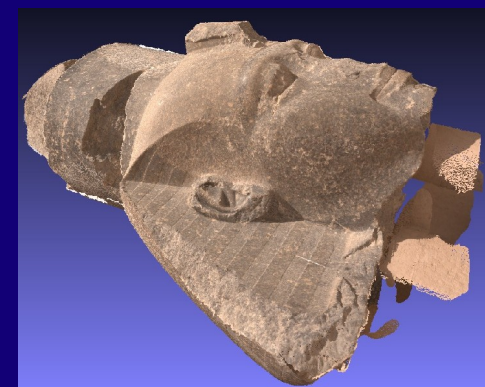


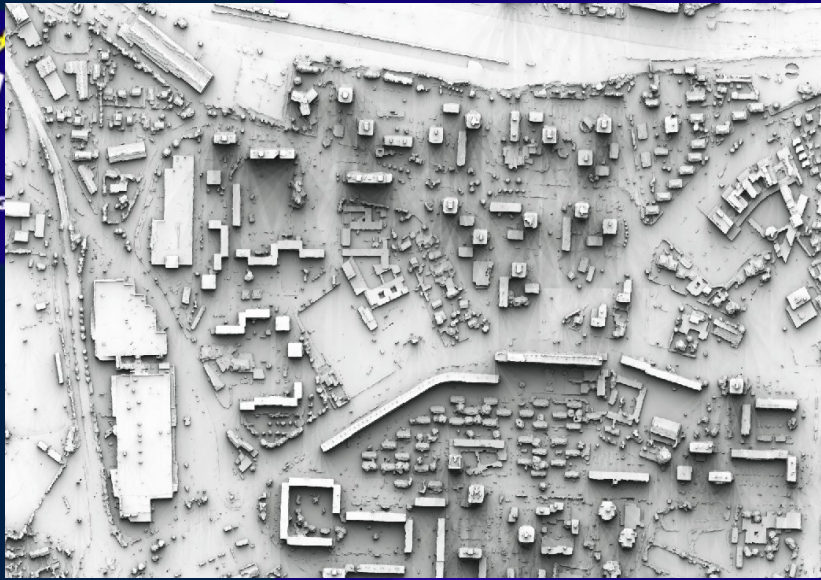
High quality of images, high redundancy of information :

(Potential) robustness :

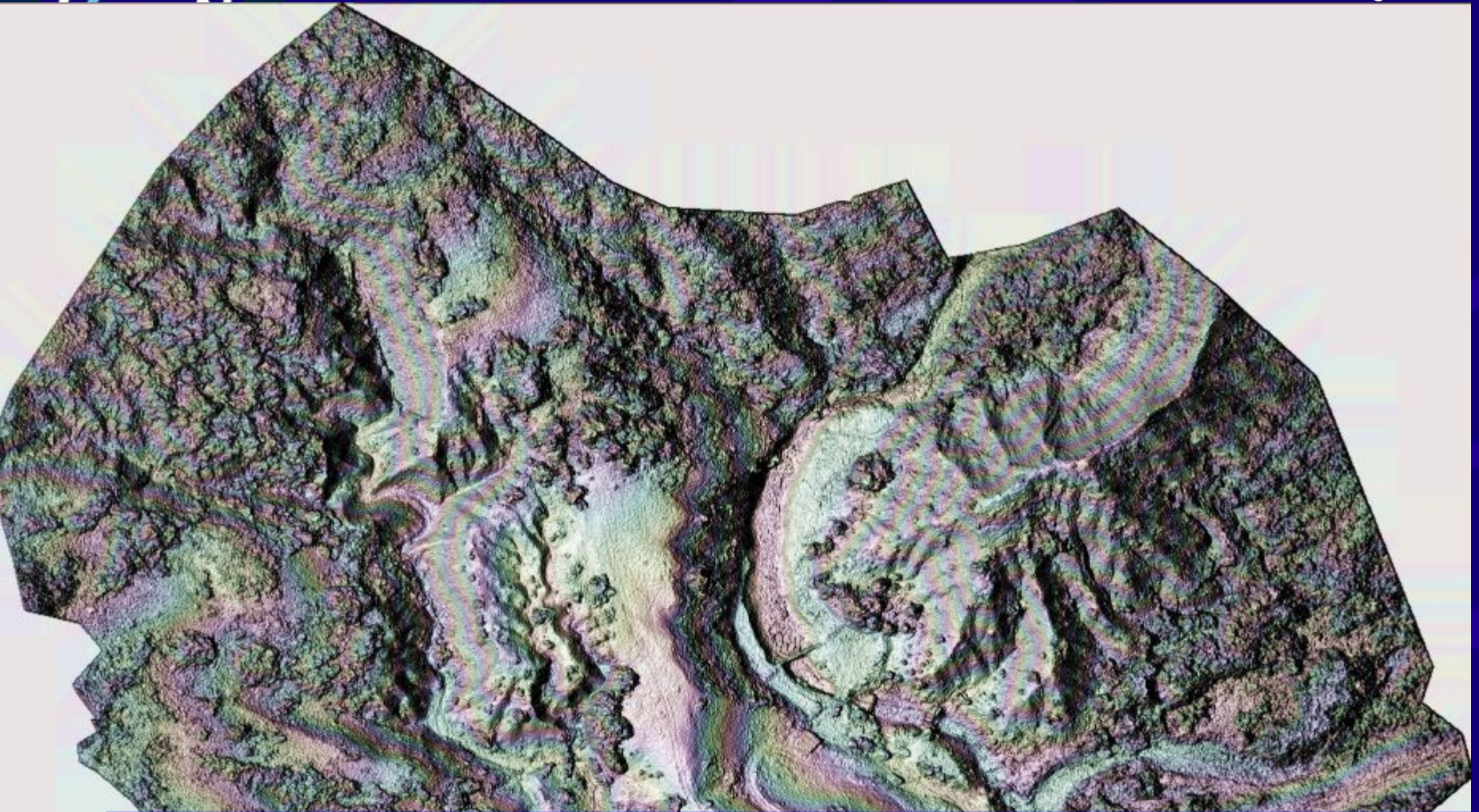
(Potential) accuracy

(Potential) automation





3D model for environmental survey:

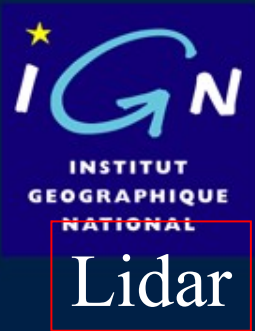


Example a 3D model of natural ground.
Computed from 150 images acquired by a very light UAV.

**Is the old lady photogrammetry back ? Ready to
take her revenge and throw away
the insolent young lidar ...**



Of course , that's not so simple



Lidar VS photogrammetry

Photogrammetry

More robust

Constant precision

Few processing (direct measurement)

Cheap material

Precision adaptable

Light weight and instantaneous

- Put it on UAV or a drone,
- Submarine application,
- quick acquisition,

Get the photo as an « extra »

Both are useful. Research on fusion is required.

For forestry application photogrammetry cannot replace LIDAR in all topics:

Aerial acquisition : photogrammetry wont give the DTM model under canopy as LIDAR can do;

Terrestrial acquisition : photogrammetry wont give Photorealistic 3D model of tree, as LIDAR can do.

But, it can still do a lot of thing for much lower cost:

Aerial photogrammetry can provide model of canopy

Terrestrial photogrammetry can provide main measurements :height, diameters of trees

2- Application to forestry



A few forestry domains in which photogrammetry may be utilized

National scale :

two stages sampling inventory
using aerial/satellite imagery

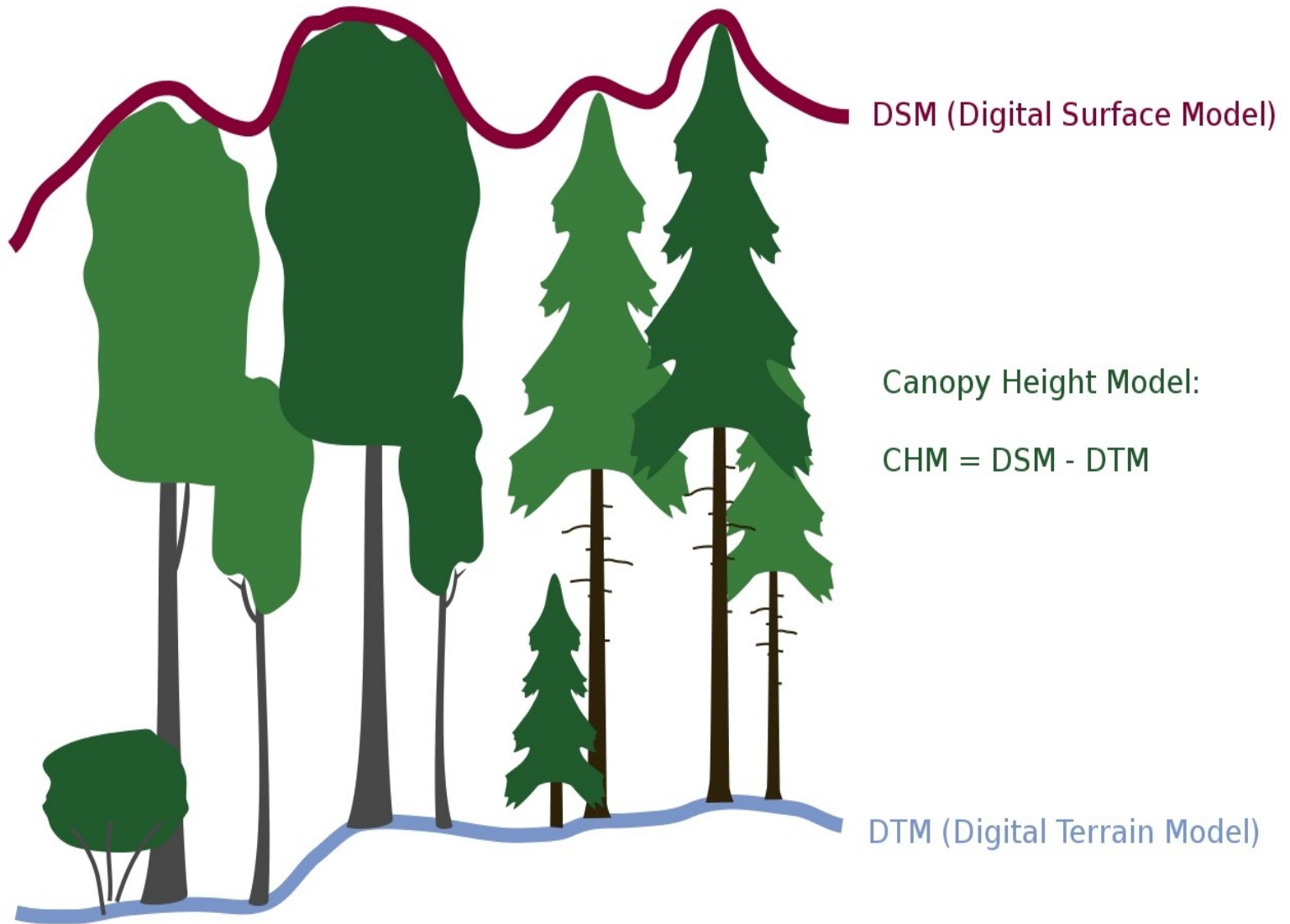
Local scale :

Aerial photogrammetry for
Precision forestry

Stand and tree levels :

Terrestrial photogrammetry

Forest canopy modelization



Use of canopy height model

- Information in term of **vertical and horizontal structure** (maturity, recrutement, irregularity)
- **Dominant height** and **Site Index** determination for even-aged stands
- Time serie of CHMs : height increment modelization

Creation of a forest canopy surface model from **aerial** imagery



Survey: IGN France

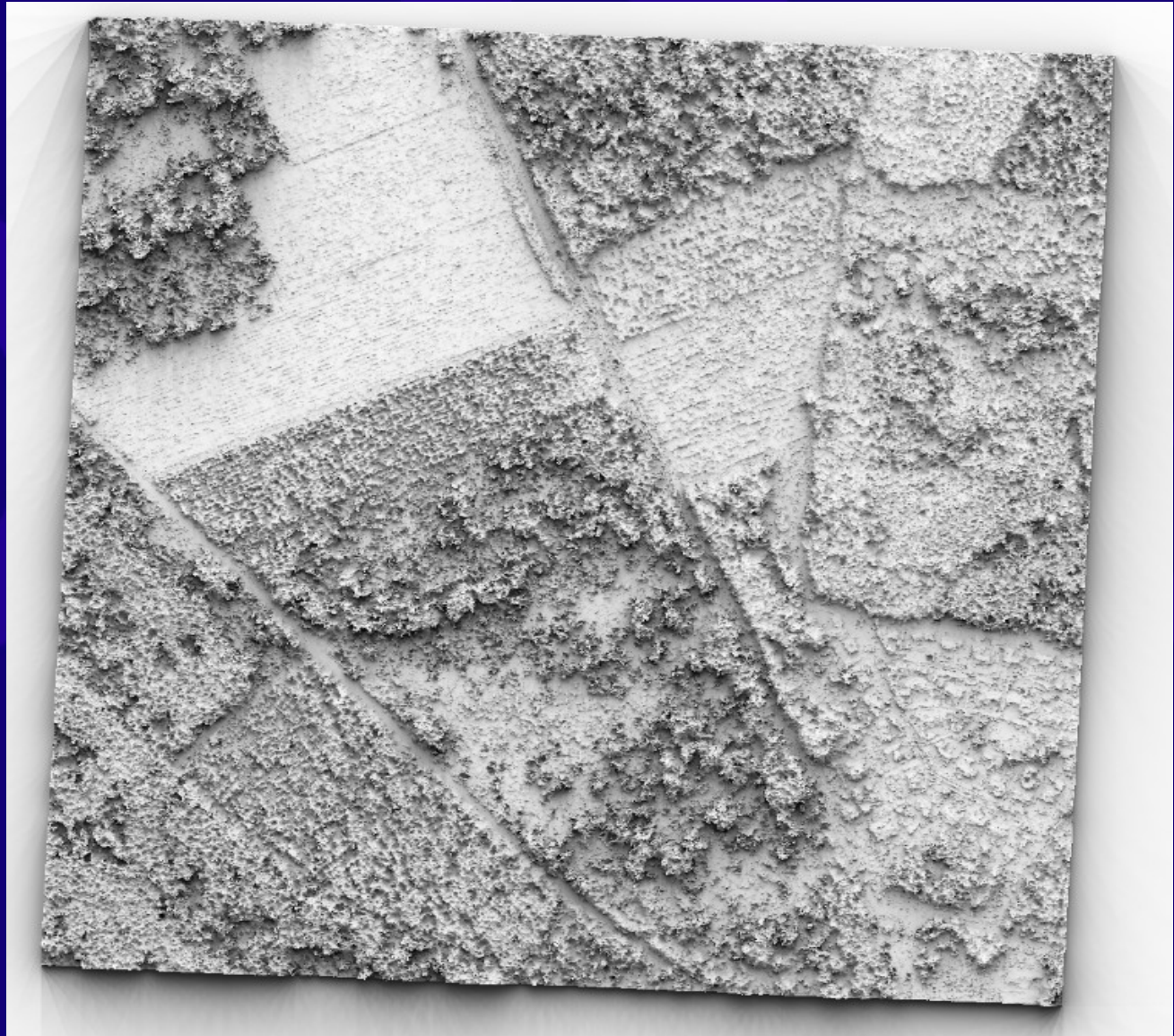
Spatial resolution : 25cm



Creation of a forest canopy surface model from **satellite** imagery

Satellite: Pleiade

Spatial resolution: 70cm



Difficulties in forest canopy photogrammetric restitution

(Baltsavias et al., 2008. High-quality image matching and automated generation of 3D tree)

- (1) little or not texture
- (2) object discontinuities
- (3) repetitive objects
- (4) moving objects (such as shadows)
- (5) **occlusions**
- (6) multi-layered or transparent objects
- (7) radiometric artifacts

Additionally, when constructing CHM with a lidar DTM :

- (8) co-registration of photo-DSM and lidar-DTM

These problems are even more present in **leave-off** situation.

Case study : Creation of a forest canopy height model from **mini-unmanned aerial system** imagery



Where: Felenne
(Belgium)

UAS : Gatewing X100

Flight altitude: 225 m

Camera : Ricoh GRIII

Spatial resolution : 8cm

Overlap: 75 %

Surface : 200 ha

Figure 2. Elements of orientation of individual areal images are computed by automatic aerotriangulation. Left: one of the 439 images. Right: the aerotriangulated model.

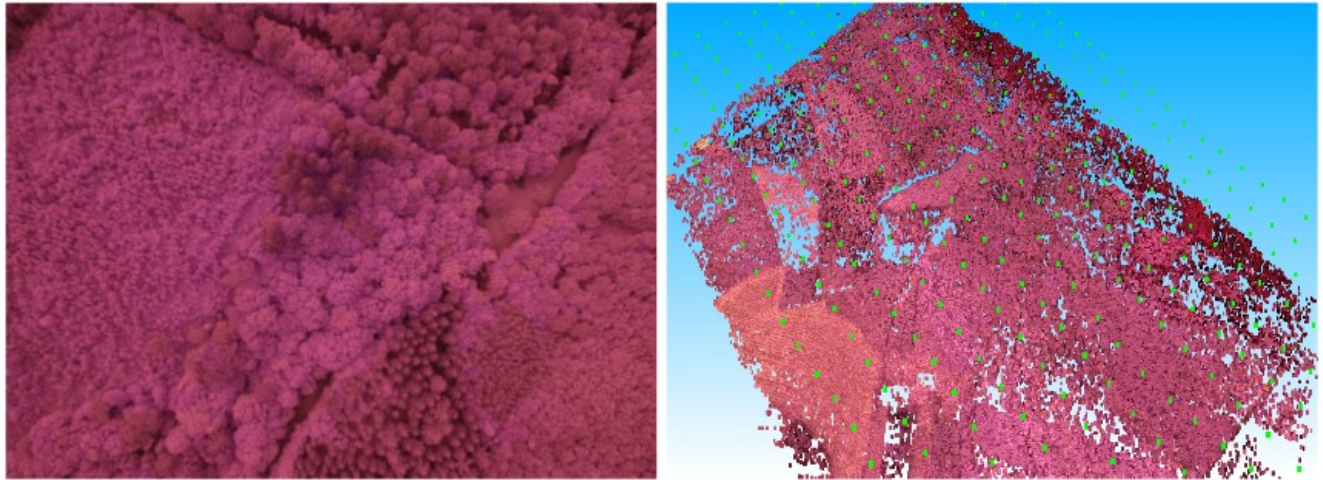
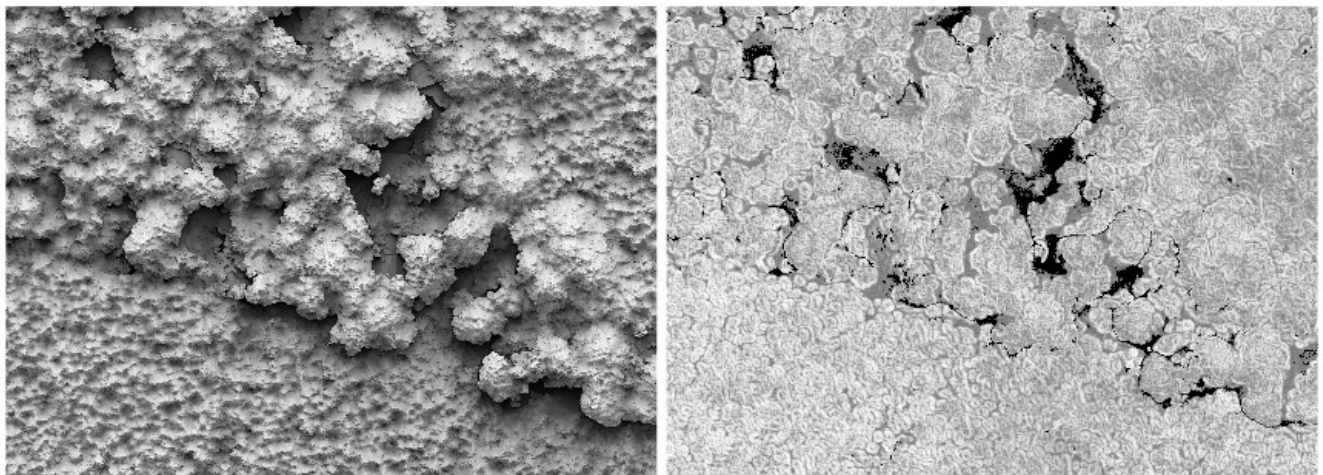
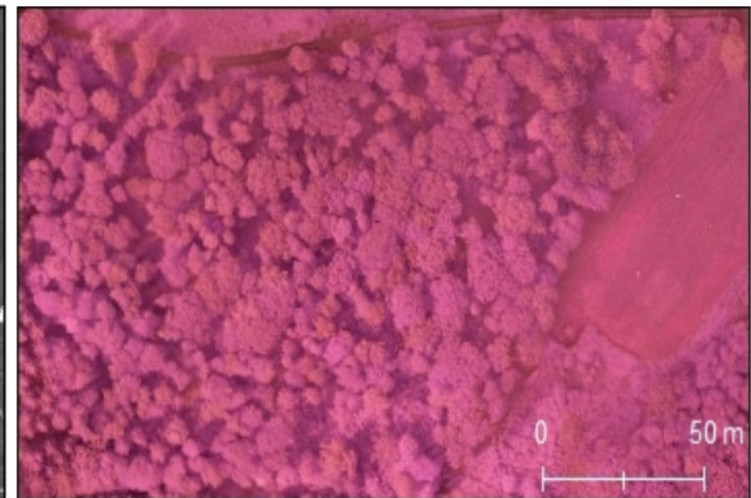
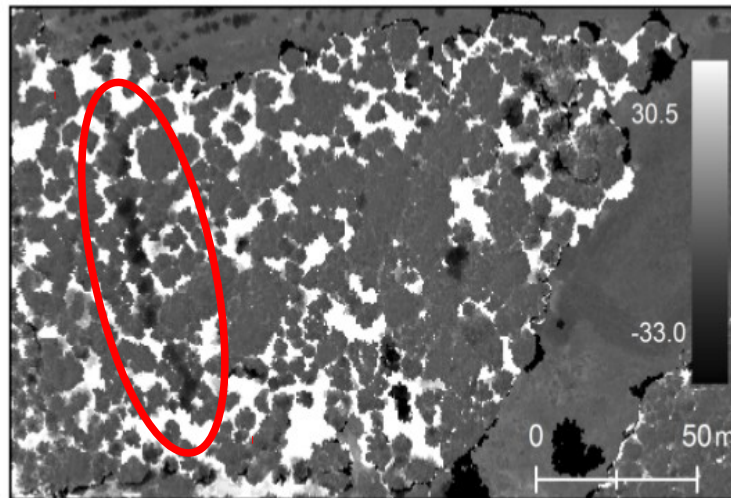
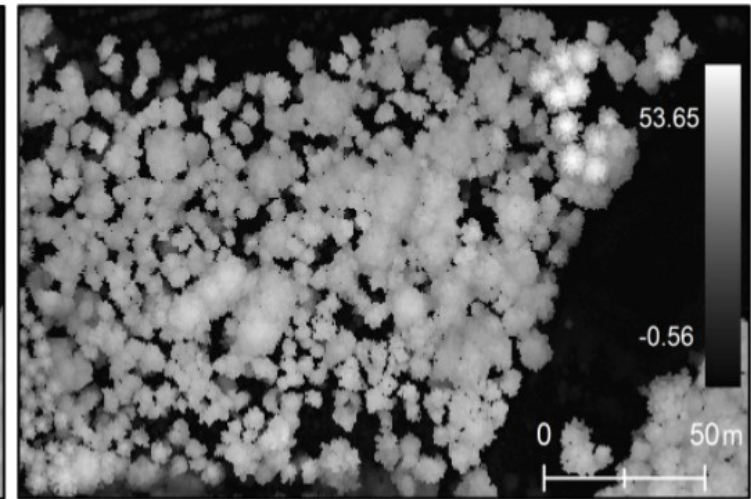
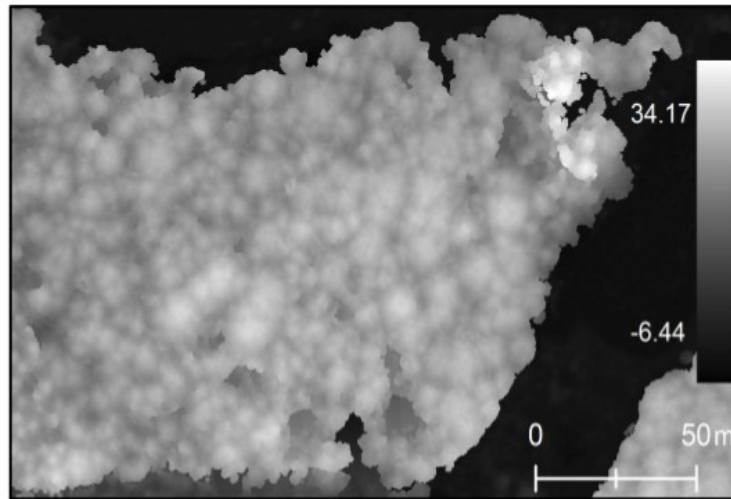


Figure 3. Close-up on the canopy surface model. Left: a shaded view of the surface model. Right: Map of normalized cross-correlation score.







Evaluation of lidar and photo **Canopy Height Models** difference:
Top left: photo-CHM (Ground Sampling Distance of **15cm**). Top right: lidar-CHM. Bottom left: elevation difference between photo-CHM and lidar-CHM. Bottom right: false color orthophotomosaic.

Comparison of photo-CHM with lidar-CHM:

Cloud to cloud distance shows that planimetric standard deviation is about **0.46 m**. Altimetric distance reveals the presence of a negative bias of 2.4 cm, attributable to the vegetation growth. Standard deviation in Z distance, for its part, is **0.48 cm**.

Correlation of metrics computed on a 20x20m windows:

Table 2. Correlation between photo-CHM and lidar-CHM window metrics.

		photo-CHM metrics								
		mean	p0	p25	p50	p75	p90	p95	p99	p100
lidar-CHM metrics	mean	0.95	0.75	0.90	0.92	0.89	0.85	0.83	0.80	0.79
	p0	0.14	0.19	0.16	0.12	0.09	0.07	0.06	0.05	0.04
	p25	0.82	0.75	0.86	0.78	0.69	0.62	0.60	0.57	0.55
	p50	0.93	0.72	0.89	0.93	0.87	0.81	0.79	0.76	0.75
	p75	0.93	0.62	0.81	0.92	0.97	0.95	0.93	0.91	0.90
	p90	0.89	0.56	0.74	0.85	0.95	0.98	0.98	0.97	0.96
	p95	0.86	0.54	0.71	0.83	0.93	0.98	0.98	0.98	0.97
	p99	0.84	0.51	0.69	0.80	0.90	0.96	0.97	0.98	0.98
	p100	0.80	0.49	0.66	0.76	0.87	0.92	0.94	0.95	0.96

Comparison of photo-CHM metrics with forest variables

(Dominant height in deciduous stand):

$$H_{dom} = a + b * p_{100} + c * p_{95} + d * p_{90}$$

Residual standard error: 1.531 m, (7.8%)

Multiple R-squared: 0.8599

Case study : Creation of a forest canopy height model from mini-unmanned aerial system imagery

Take home messages:

Photogrammetric canopy height model equivalent in Smoothed lidar-CHM (mainly due to occlusion)

Photogrammetry in vegetation area require specific Tuning of dense-matching algorithm

Dominant height may be predicted with an mean Residual of 1.5 m in deciduous stand.



3- Tools and proposed actions

Numerous existing softwares :

Open (and free)	Bundler PMVS Visual SFM MicMac-Apero
low-cost	Agisoft Photoscan
Upload (free)	Solution Arc3D Solution 123DCatch
Commercial	Solution acute3D Solution pix4D



IGN photogrammetry suite characteristics :

Intended for professionals (GIS experts, archaeologists, architects, geomorphologists ...)

More complex use , no « one bottom press » solution ;

Provide fine tuning opportunity for each steps ;

Handle large amount of data ;

Generate intermediate (and final) results in open format (can be used in separate pieces) ;



Background :

2003 : developpement of self-calibrating bundle block adjutment and urban DEM dense matching script

2005 : setting up XML user interface, software is called MicMac;

2007 : open source repository;

2008 : developpement of Aperro (tool for orientation) ;

2010 : training sessions and developpement of simplified interfaces (without XML);

2012 : “culture 3d” project : Windows port, binaries distribution.

Why a summer school ?

Importance of photo acquisition :

Once you know the process, key stage is acquisition time :

Take “good photo” (contrast, noise, no blur)

Take enough photo

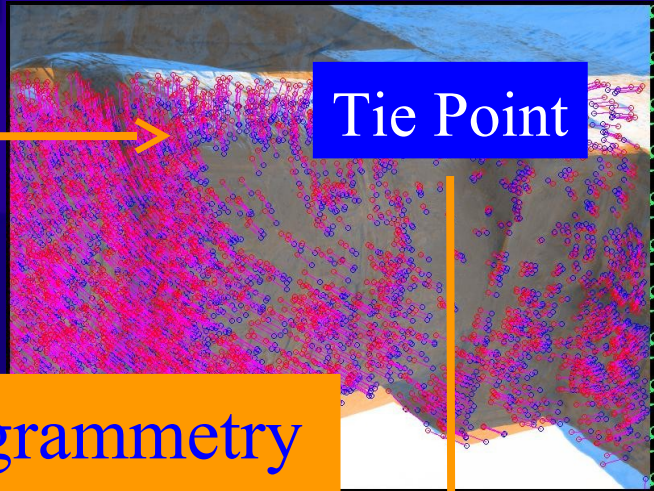
Take the good angles

Standard Pipeline for 3D photo modelization



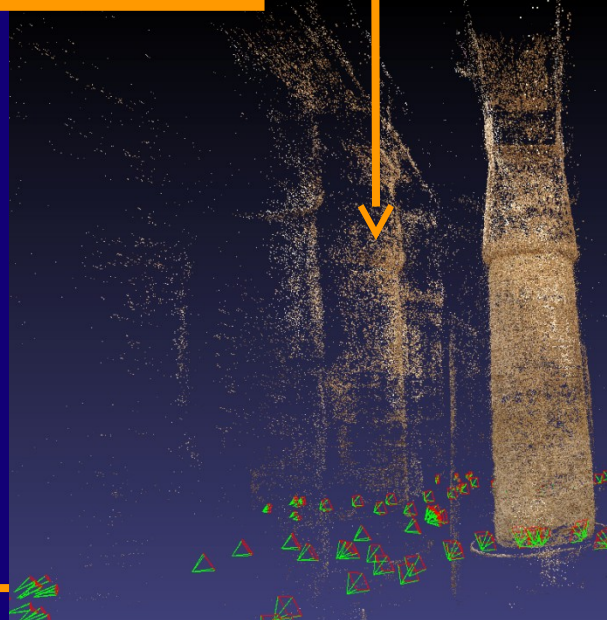
Images

Image processing



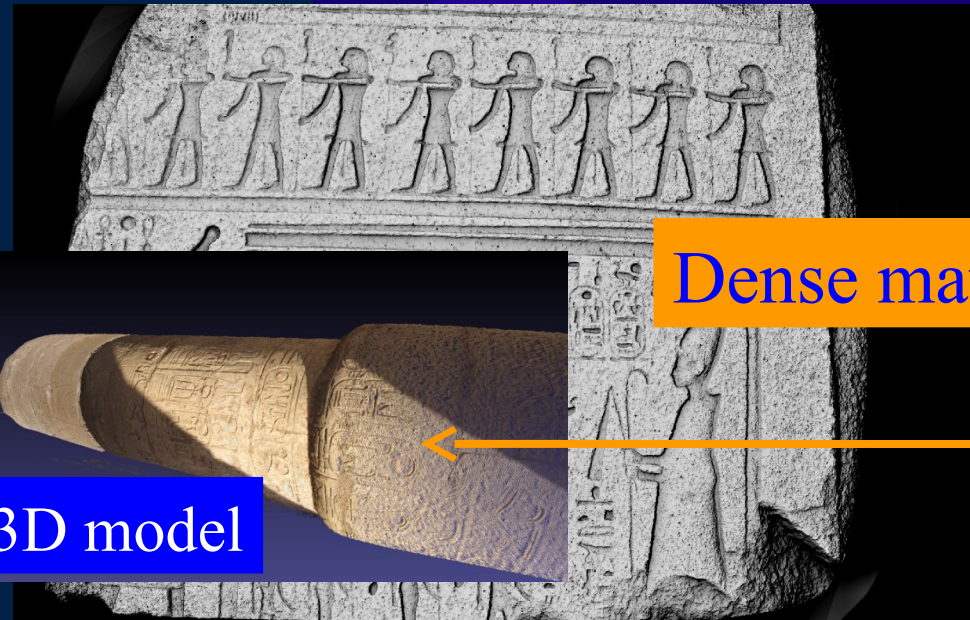
Tie Point

Photogrammetry
Computer Vision



Orientation, calibration

Dense matching



3D model

I



Proposed summer school :

- 3 to 4 days, week of 19 to 23 August 2013
- In Forcalquiers, south of France (pré Alpes)
- Topics :
 - Fundamental of photogrammetry
 - Learning the IGN's open source suite on simple case;
 - Test cases on forestry (aerial and satellite, UAV, terrestrial);
 - Table ronde and discussion for research and development

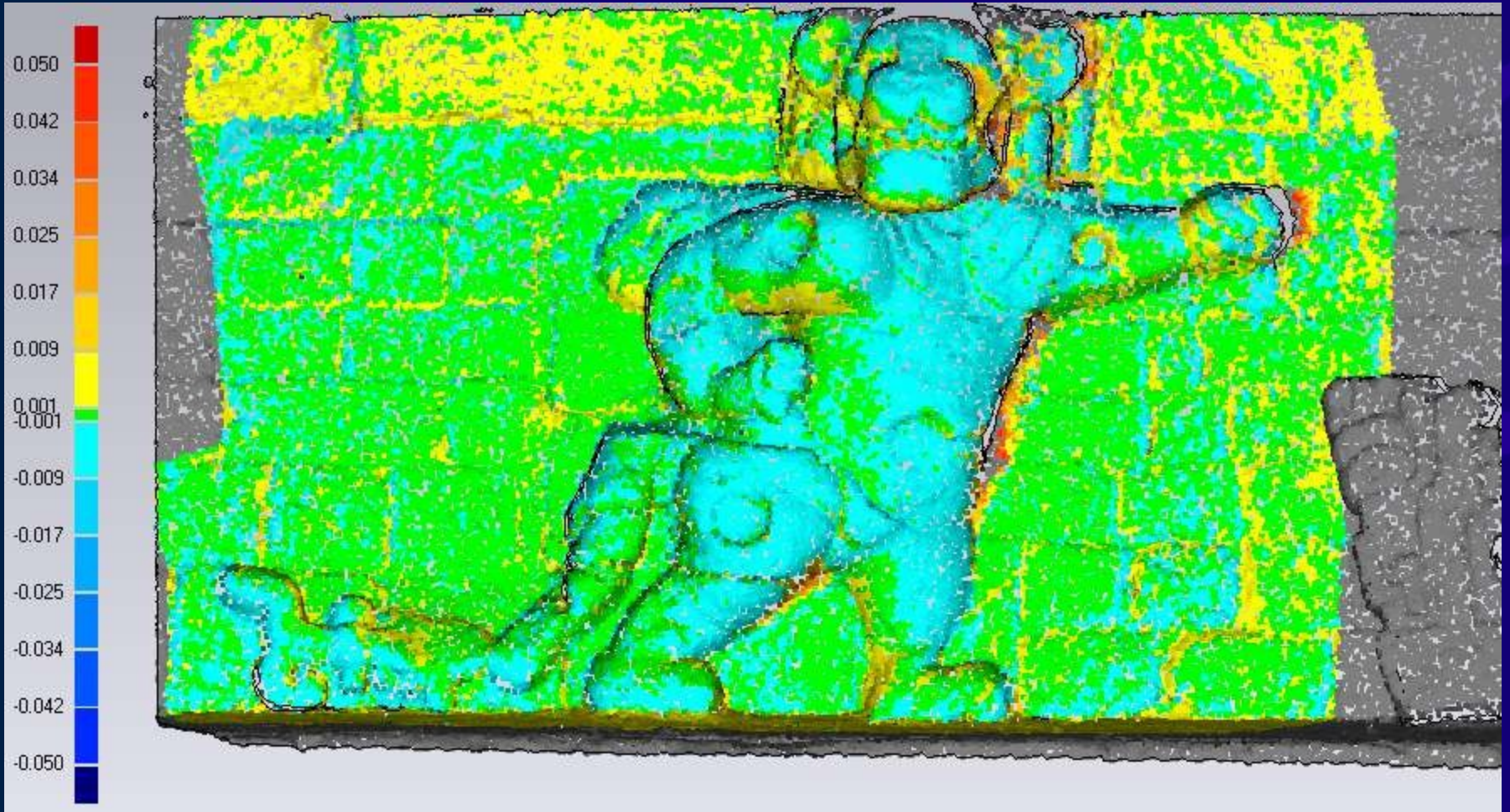
Thank you for your attention.

Slides available on :
<http://orbi.ulg.ac.be/handle/2268/144562>

Questions ?

Précision ?

“Autour du pixel “





N

O

e

s



N

O

e

s



N

O

e

s